



```

2  #define echoPin 2
3  #define trigPin 3
4  long duration;
5  int distance;
6
7  void setup() {
8      pinMode(trigPin, OUTPUT);
9      pinMode(echoPin, INPUT);
10     Serial.begin(9600);
11     Serial.println("Ultrasonic Sensor HC-SR04 Test");
12     Serial.println("with Arduino UNO R3");
13 }
14 void loop() {
15     digitalWrite(trigPin, LOW);
16     digitalWrite(trigPin, HIGH);  delayMicroseconds(2);
17     delayMicroseconds(10);
18     digitalWrite(trigPin, LOW);
19     duration = pulseIn(echoPin, HIGH);
20     distance = duration * 0.034 / 2;
21     Serial.print("Distance: ");
22     Serial.print(distance);
23     Serial.println(" cm");
24 }

```



Serial Monitor

```

Distance: 110 cm
Distance: 110 cm
Distance: 110 cm
Distance: 110 cm
Distance: 110 cm
Distance: 110 cm

```