

## ASSIGNMENT-4

### Connecting wokwi and IBM Cloud Service

Assignment Date	24 October 2022
Student Name	Mr. Dineshpandi G
Student Roll Number	923819106015
Maximum Marks	2 Marks

#### Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100cms send "alert" to IBM cloud and display in device recent events.

#### CODE:

```
1  #include <WiFi.h> //library for wifi
2  #include <PubSubClient.h> //library for MQTT
3
4
5  void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);
6
7  //-----credentials of IBM Accounts-----
8
9  #define ORG "4hn0jp" //IBM ORGANITION ID
10 #define DEVICE_TYPE "ULTRASON" //Device type mentioned in ibm watson IOT Platform
11 #define DEVICE_ID "DISTANCEDETECT" //Device ID mentioned in ibm watson IOT Platform
12 #define TOKEN "wuo5s7PR)ZSegVk&Rx" //Token
13 String data3;
14 float dist;
15
16
17 //----- Customise the above values -----
18 char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; // Server Name
19 char publishTopic[] = "iot-2/evt/Data/fmt/json"; // topic name and type of event perform and format in which data to be send
20 char subscribetopic[] = "iot-2/cmd/test/fmt/String"; // cmd REPRESENT command type AND COMMAND IS TEST OF FORMAT STRING
21 char authMethod[] = "use-token-auth"; // authentication method
22 char token[] = TOKEN;
23 char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID; //client id
24
25
26 //-----
27 WiFiClient wificlient; // creating the instance for wificlient
28 PubSubClient client(server, 1883, callback, wificlient); //calling the predefined client id by passing parameter like server id, port and wificredential
29
30 int LED = 4;
31 int trig = 5;
32 int echo = 18;
33 void setup()
34 {
35   Serial.begin(115200);
```

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```
36 pinMode(trig,OUTPUT);
37 pinMode(echo,INPUT);
38 pinMode(LED, OUTPUT);
39 delay(10);
40 wificonnect();
41 mqttconnect();
42 }
43 void loop()// Recursive Function
44 {
45
46     digitalWrite(trig,LOW);
47     digitalWrite(trig,HIGH);
48     delayMicroseconds(10);
49     digitalWrite(trig,LOW);
50     float dur = pulseIn(echo,HIGH);
51     float dist = (dur * 0.0343)/2;
52     Serial.print ("Distancein cm");
53     Serial.println(dist);
54
55
56     PublishData(dist);
57     delay(1000);
58     if (!client.loop()) {
59         mqttconnect();
60     }
61 }
62
63
64
65 /*.....retrieving to Cloud.....*/
66
67 void PublishData(float dist) {
68     mqttconnect();//function call for connecting to ibm
69     /*
70     | creating the String in in form JSon to update the data to ibm cloud
```

```

69  |
70  | | creating the String in in form JSON to update the data to ibm cloud
71  */
72  String object;
73  if (dist <100)
74  {
75      digitalWrite(LED,HIGH);
76      Serial.println("object is near");
77      object = "Near";
78  }
79  else
80  {
81      digitalWrite(LED,LOW);
82      Serial.println("no object found");
83      object = "No";
84  }
85
86  String payload = "{\"distance\":\"";
87  payload += dist;
88  payload += "," " \"object\":\"";
89  payload += object;
90  payload += "\"}";
91
92
93  Serial.print("Sending payload: ");
94  Serial.println(payload);
95
96
97
98

```

```

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98
99  if (client.publish(publishTopic, (char*) payload.c_str())) {
100      Serial.println("Publish ok");// if it sucessfully upload data on the cloud then it will print publish ok in Serial monitor or else it will print publish failed
101  } else {
102      Serial.println("Publish failed");
103  }
104
105  }
106  void mqttconnect() {
107      if (!client.connected()) {
108          Serial.print("Reconnecting client to ");
109          Serial.println(server);
110          while (!client.connect(clientId, authMethod, token)) {
111              Serial.print(".");
112              delay(500);
113          }
114
115          initManagedDevice();
116          Serial.println();
117      }
118  }
119  void wificonnect() //function defination for wificonnect
120  {
121      Serial.println();
122      Serial.print("Connecting to ");
123
124      Wifi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
125      while (Wifi.status() != WL_CONNECTED) {
126          delay(500);
127          Serial.print(".");
128      }
129      Serial.println("");
130      Serial.println("Wifi connected");
131      Serial.println("IP address: ");
132      Serial.println(Wifi.localIP());

```

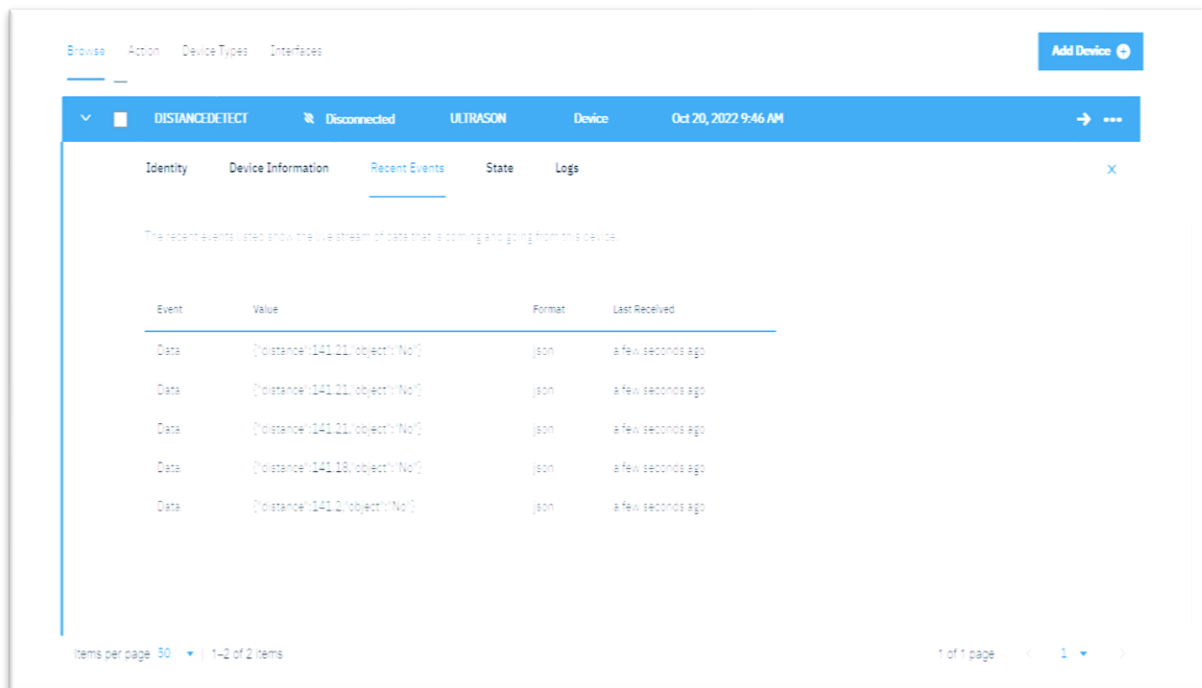
esp32-blink.ino • diagram.json • libraries.txt • Library Manager ▼

```
123
124   WiFi.begin("Wokwi-GUEST", "", 6); //passing the wifi credentials to establish the connection
125   while (WiFi.status() != WL_CONNECTED) {
126       delay(500);
127       Serial.print(".");
128   }
129   Serial.println("");
130   Serial.println("WiFi connected");
131   Serial.println("IP address: ");
132   Serial.println(WiFi.localIP());
133 }
134
135 void initManagedDevice() {
136     if (client.subscribe(subscribetopic)) {
137         Serial.println((subscribetopic));
138         Serial.println("subscribe to cmd OK");
139     } else {
140         Serial.println("subscribe to cmd FAILED");
141     }
142 }
143
144 void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
145 {
146
147     Serial.print("callback invoked for topic: ");
148     Serial.println(subscribetopic);
149     for (int i = 0; i < payloadLength; i++) {
150         //Serial.print((char)payload[i]);
151         data3 += (char)payload[i];
152     }
153
154     // Serial.println("data: " + data3);
155     // if(data3=="Near")
156     // {
157     // Serial.println(data3);
158     // if (data3=="Near") {
159     //     Serial.println("Near");
160     // }
```

```
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142 }
143
144 void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
145 {
146
147     Serial.print("callback invoked for topic: ");
148     Serial.println(subscribetopic);
149     for (int i = 0; i < payloadLength; i++) {
150         //Serial.print((char)payload[i]);
151         data3 += (char)payload[i];
152     }
153
154     // Serial.println("data: "+ data3);
155     // if(data3=="Near")
156     // {
157     // Serial.println(data3);
158     // digitalWrite(LED,HIGH);
159
160     // }
161
162     // else
163     // {
164     // Serial.println(data3);
165     // digitalWrite(LED,LOW);
166
167     // }
168     data3="";
169
170
171 }
```

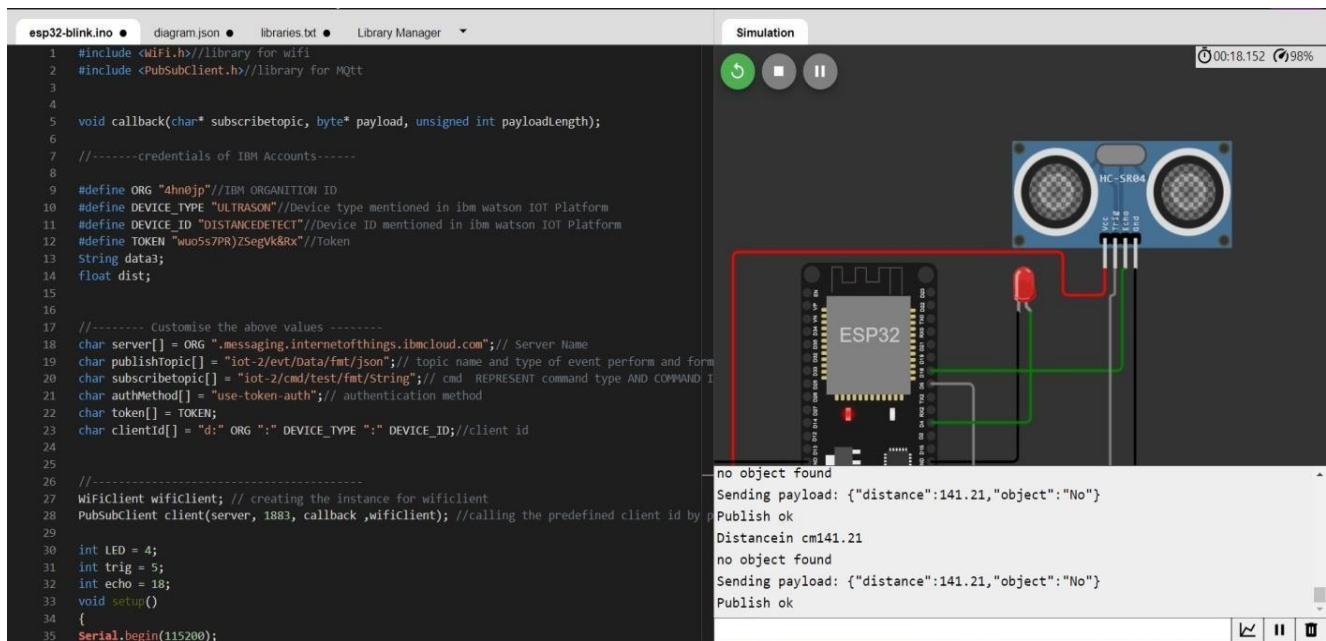
## OUTPUT:



The screenshot shows the IBM Watson IoT Platform interface. The top navigation bar includes 'Browse', 'Action', 'Device Types', and 'Interfaces'. A blue 'Add Device' button is in the top right. Below the navigation bar, a header bar displays 'DISTANCEDETECT', 'Disconnected', 'ULTRASON', 'Device', and the timestamp 'Oct 20, 2022 9:46 AM'. The main content area has tabs for 'Identity', 'Device Information', 'Recent Events', 'State', and 'Logs'. The 'Recent Events' tab is active, showing a table of events. The table has columns for 'Event', 'Value', 'Format', and 'Last Received'. There are five rows of data, all with a value of '["distance":141.21,"object":"No"]' and a format of 'json'. The 'Last Received' column shows 'a few seconds ago' for each row. At the bottom, there is a pagination bar showing 'Items per page: 50' and '1-2 of 2 items'.

Event	Value	Format	Last Received
Data	["distance":141.21,"object":"No"]	json	a few seconds ago
Data	["distance":141.21,"object":"No"]	json	a few seconds ago
Data	["distance":141.21,"object":"No"]	json	a few seconds ago
Data	["distance":141.18,"object":"No"]	json	a few seconds ago
Data	["distance":141.2,"object":"No"]	json	a few seconds ago

Data send to the IBM cloud device when the objects far



The screenshot shows the Arduino IDE with a code editor on the left and a simulation window on the right. The code editor displays the following code:

```
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27 WiFiClient wificlient; // creating the instance for wificlient
28 PubSubClient client(server, 1883, callback, wificlient); //calling the predefined client id by p
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30 int LED = 4;
31 int trig = 5;
32 int echo = 18;
33 void setup()
34 {
35   Serial.begin(115200);
```

The simulation window on the right shows a 3D model of the ESP32 board connected to an HC-SR04 ultrasonic sensor. The sensor is connected to the ESP32 via a breadboard. The simulation window also displays the following text:

```
no object found
Sending payload: {"distance":141.21,"object":"No"}
Publish ok
Distancein cm141.21
no object found
Sending payload: {"distance":141.21,"object":"No"}
Publish ok
```

## Data sent to the IBM Cloud Device when the object is near

Browser Action Device Types Interfaces Add Device

DistanceDETECT Disconnected ULTRASON Device Oct 20, 2022 9:46 AM

Identity Device Information Recent Events State Logs

The recent events listed show the last streams of data that's coming and going from this device.

Event	Value	Format	Last Received
Data	["distance":79.66,"object":"Near"]	json	a few seconds ago
Data	["distance":79.64,"object":"Near"]	json	a few seconds ago
Data	["distance":79.66,"object":"Near"]	json	a few seconds ago
Data	["distance":79.64,"object":"Near"]	json	a few seconds ago
Data	["distance":79.66,"object":"Near"]	json	a few seconds ago

Items per page: 50 1-2 of 2 items 1 of 1 page 1

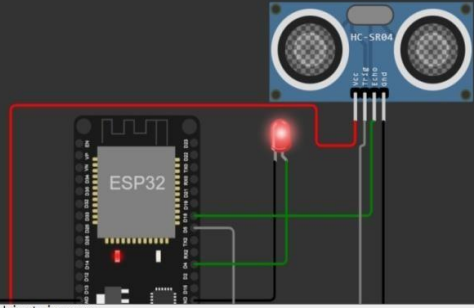
## When objects near to the ultrasonic sensor

wokwi.com/projects/305566932847821378

esp32-arduino.ino by urish

Simulation

00:12.028 100%



```
object is near
Sending payload: {"distance":97.82,"object":"Near"}
Publish ok
Distancein cm97.82
object is near
Sending payload: {"distance":97.82,"object":"Near"}
Publish ok
```