## **ASSIGNMENT-4**

### Connecting wokwi and IBM Cloud Service

Assignment Date	24 October 2022
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Maximum Marks	2 Marks

# **Question1:**

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100cms send "alert" to IBM cloud and display in device recent events.

#### CODE:

```
### stinclude of process of the proc
```

```
esp32-blink.ino
                 diagram.json •
                                   libraries.txt ●
                                                 Library Manager *
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
           mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

```
creating the String in in form JSon to update the data to ibm cloud

''

String object;

if (dist <100)

{
    digitalWrite(LED,HIGH);
    Serial.println("object is near");
    object = "Near";

}

else

digitalWrite(LED,LOW);

Serial.println("no object found");
    object = "No";

String payload = "(\"distance\":";
    payload += dist;
    payload += object;
    payload += "\"\";

payload += "\"\";

Serial.print("Sending payload: ");

Serial.println(payload);
```

```
### displaying the serial println(publishtopic, (char*) payload.c_str()) {

### serial println(publishtopic, (char*) payload.c_str()) {

### serial println(publish ok);/ if it successfully upload data on the cloud then it will print publish ok in Serial monitor or else it will print publish failed

### serial println("Publish failed");

### serial println("Serial println(");

### serial println();

### serial println();

### serial println();

### serial println(");

### serial
```

```
esp32-blink.ino •
                   diagram.json •
                                    libraries.txt ●
                                                  Library Manager
         WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
         while (WiFi.status() != WL_CONNECTED) {
           delay(500);
           Serial.print(".");
         Serial.println("");
         Serial.println("WiFi connected");
         Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
       void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
           Serial.println((subscribetopic));
           Serial.println("subscribe to cmd OK");
           Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
         Serial.print("callback invoked for topic: ");
         Serial.println(subscribetopic);
 148
         for (int i = 0; i < payloadLength; i++) {</pre>
           data3 += (char)payload[i];
```

```
esp32-blink.ino  diagramjson  libraries.bt  Library Manager  

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)

lad
    void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)

serial.print("callback invoked for topic: ");

serial.println(subscribetopic);

for (int i = 0; i < payloadLength; i++) {
    //serial.println((char)payload[i]);
    data3 += (char)payload[i];
    // serial.println("data: "+ data3);
    // fif(data3=="Near")
    // serial.println(data3);
    // digitalwrite(LED,HIGH);

lad
    // serial.println(data3);
    // digitalwrite(LED,LOW);

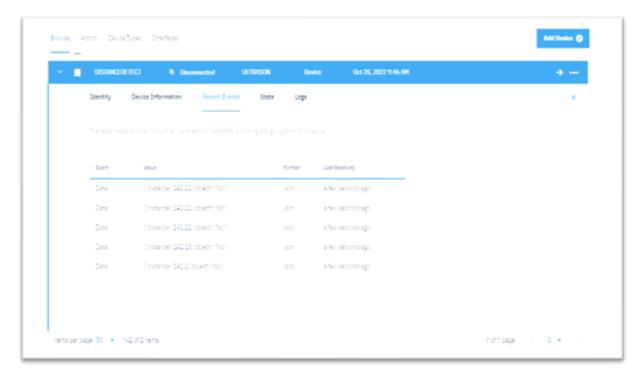
data3="";

data3="";

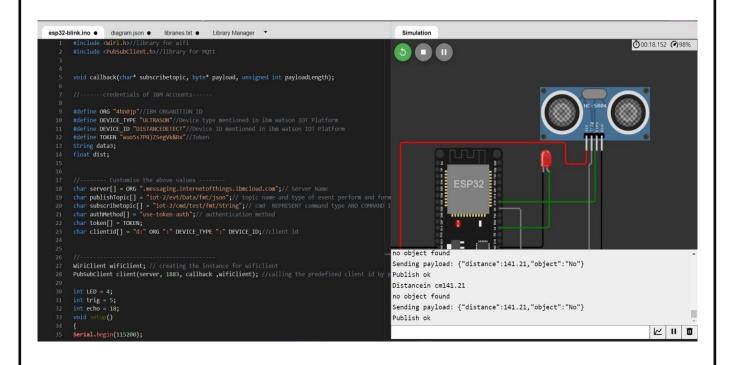
lad
    // serial.println(data3);
    // digitalwrite(LED,LOW);

lad
    // serial.println(data3);
    // serial.println(d
```

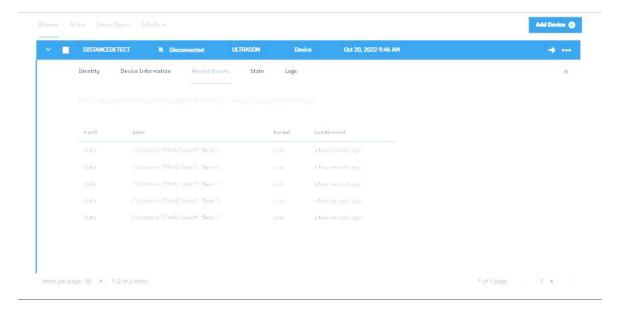
## **OUTPUT**:



Data send to the IBM cloud device when the objects far



# Data sent to the IBM Cloud Device when the object is near



### When objects near to the ultrasonic sensor

