#### ASSIGNMENT - 4

#### Ultrasonic sensor simulation in Wokwi

Date	25 October 2022
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Maximum Marks	2 marks

### **QUESTION:**

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events

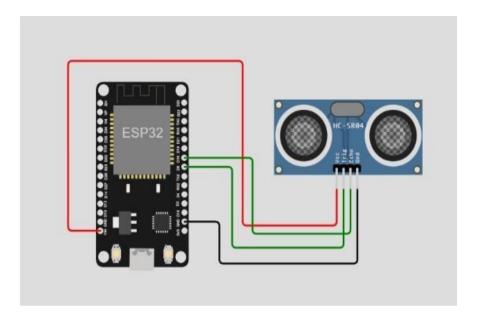
#### **CODE:**

```
#include <WiFi.h>
 #include < PubSubClient.h>
 void callback(char* subscribetopic, byte* payload, unsigned int
 payloadLength);
 //----credentials of IBM Accounts-----
#define ORG "5bfis0"//IBM ORGANITION ID
 #define DEVICE_TYPE "abcd"//Device type mentioned in ibm watson IOT
 Platform
 #define DEVICE_ID "1234"//Device ID mentioned in ibm watson IOT Platform
 #define TOKEN "12345678" //Token
 String data3;
 char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
 char publishTopic[] = "iot-2/evt/Data/fmt/json";
 char subscribetopic[] = "iot-2/cmd/test/fmt/String";
 char authMethod[] = "use-token-auth";
 char token[] = TOKEN;
 char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
 WiFiClient wifiClient;
 PubSubClient client(server, 1883, callback, wifiClient);
 const int trigPin = 5;
 const int echoPin = 18;
 #define SOUND_SPEED 0.034
 long duration;
 float distance;
 void setup() {
```

```
Serial.begin(115200);
pinMode(trigPin, OUTPUT);
pinMode(echoPin, INPUT);
wificonnect();
mqttconnect();
void loop()
digitalWrite(trigPin, LOW);
delayMicroseconds(2);
digitalWrite(trigPin, HIGH);
delayMicroseconds(10);
digitalWrite(trigPin, LOW);
duration = pulseIn(echoPin, HIGH);
distance = duration * SOUND SPEED/2;
Serial.print("Distance (cm): ");
Serial.println(distance);
if(distance<100)
Serial.println("ALERT!!");
delay(1000);
PublishData(distance);
delay(1000);
if (!client.loop()) {
mqttconnect();
}
delay(1000);
void PublishData(float dist) {
mqttconnect();
String payload = "{\"Distance\":";
payload += dist;
payload += ",\"ALERT!!\":""\"Distance less than 100cms\"";
payload += "}";
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish ok");
} else {
Serial.println("Publish failed");
void mqttconnect() {
if (!client.connected()) {
```

```
Serial.print("Reconnecting client to ");
Serial.println(server);
while (!!!client.connect(clientId, authMethod, token)) {
Serial.print(".");
delay(500);
initManagedDevice();
Serial.println();
void wificonnect()
Serial.println();
Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED) {
delay(500);
Serial.print(".");
Serial.println("");
Serial.println("WiFi connected");
Serial.println("IP address: ");
Serial.println(WiFi.localIP());
void initManagedDevice() {
if (client.subscribe(subscribetopic)) {
Serial.println((subscribetopic));
Serial.println("subscribe to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic);
for (int i = 0; i < payloadLength; i++) {
//Serial.print((char)payload[i]);
data3 += (char)payload[i];
Serial.println("data: "+ data3);
data3="";
```

### **CIRCUIT DIAGRAM:**



# Wokwi simulation link:

https://wokwi.com/projects/3471910302342190

## **WOKWI OUTPUT:**

```
Distance (cm): 399.92
Distance (cm): 399.96
Distance (cm): 399.94
Distance (cm): 399.98
Distance (cm): 399.94
Distance (cm): 399.94
Distance (cm): 399.92
Distance (cm): 399.94
```

### **IBM CLOUD OUTPUT:**

