## Assignment -4

## Distance Detection Using Ultrasonic Sensor

Assignment Date	13 November 2022
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Maximum Marks	2 Marks

## Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

WOKWI LINK: https://wokwi.com/projects/345964118720643668

**CODE:** 

```
#include <WiFi.h>//library for wifi
#include <PubSubClient.h>//library for MQtt
void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);
#define ORG "f59trs"//IBM ORGANITION ID
#define DEVICE TYPE "ultrasonicsensor"//Device type mentioned in
ibm watson IOT Platform
#define DEVICE ID "distancedetection"//Device ID mentioned in ibm
watson IOT Platform
#define TOKEN "AlGMGaaF01nawa1QA3"
//Token String data3; float dist;
//----- Customise the above values ------
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";//
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name
and type of event perform and format in which data to be send
char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd
REPRESENT command type AND COMMAND IS TEST OF FORMAT STRING char
authMethod[] = "use-token-auth";// authentication method char
token[] = TOKEN; char clientId[] = "d:" ORG ":" DEVICE_TYPE ":"
DEVICE_ID;//client id
WiFiClient wifiClient; // creating the instance for wificlient
```

```
PubSubClient client(server, 1883, callback ,wifiClient);
//calling the predefined client id by passing parameter like
server id, portand wificredential
int LED = 4;
int trig = 5;
int echo = 18;
void setup()
Serial.begin(115200);
pinMode(trig,OUTPUT);
pinMode(echo, INPUT);
pinMode(LED, OUTPUT);
delay(10); wificonnect();
mqttconnect();
} void loop()// Recursive
Function
{ digitalWrite(trig,LOW);
digitalWrite(trig,HIGH);
delayMicroseconds(10);
digitalWrite(trig,LOW); float
dur = pulseIn(echo, HIGH);
float dist = (dur * 0.0343)/2;
 Serial.print ("Distancein cm");
 Serial.println(dist);
 PublishData(dist);
delay(1000);
(!client.loop()) {
mqttconnect();
Cloud....*/
void PublishData(float dist) {
mqttconnect();//function call for connecting to ibm
          creating the String in in form JSon to update the
data to ibm cloud
 String object;
```

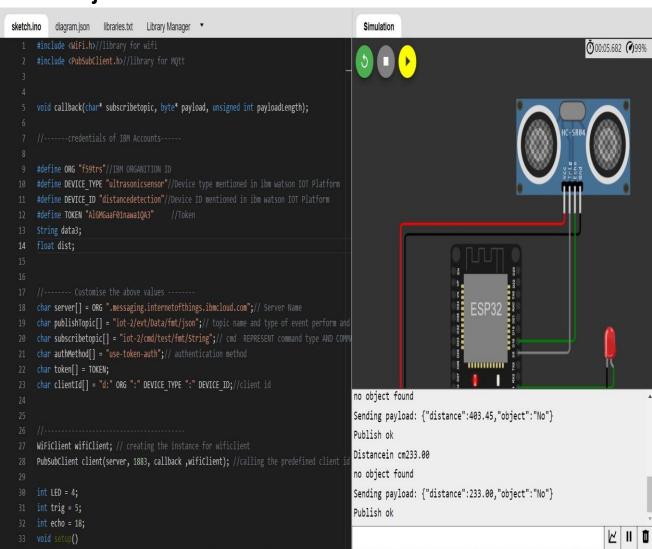
```
if (dist <100)</pre>
  {
    digitalWrite(LED, HIGH);
    Serial.println("object is near");
object = "Near";
else
    digitalWrite(LED, LOW);
    Serial.println("no object found");
object = "No";
  String payload =
"{\"distance\":";
                  payload +=
      payload += ","
dist;
"\"object\":\""; payload +=
object; payload += "\"}";
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish ok");// if it successfully upload data on
it will print publish failed
  } else {
    Serial.println("Publish failed");
mqttconnect() {
 if (!client.connected()) {
    Serial.print("Reconnecting client to ");
Serial.println(server);
    while (!!!client.connect(clientId, authMethod, token))
        Serial.print(".");
                               delay(500);
     initManagedDevice();
     Serial.println();
```

```
void wificonnect() //function defination for wificonnect {
  Serial.println();
  Serial.print("Connecting to ");
  WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi
credentials to establish the connection while (WiFi.status()
!= WL_CONNECTED) { delay(500);
    Serial.print(".");
 Serial.println("");
  Serial.println("WiFi connected");
 Serial.println("IP address: ");
  Serial.println(WiFi.localIP());
} void
initManagedDevice() {
 if (client.subscribe(subscribetopic)) {
Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
} void callback(char* subscribetopic, byte* payload, unsigned
int payloadLength)
 Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic);
 for (int i = 0; i < payloadLength; i++) {</pre>
//Serial.print((char)payload[i]);
                                    data3
+= (char)payload[i];
   if(data3=="Near")
// Serial.println(data3);
// digitalWrite(LED,HIGH);
// Serial.println(data3);
```

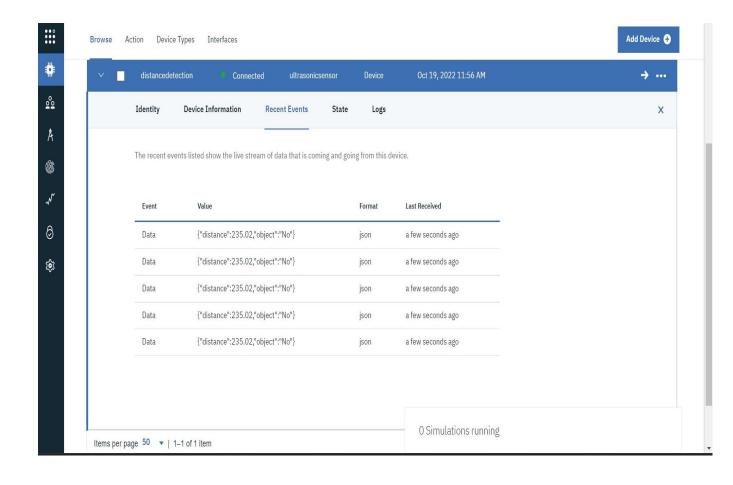
```
// digitalWrite(LED,LOW);
// }
data3="";
```

## **OUTPUT:**

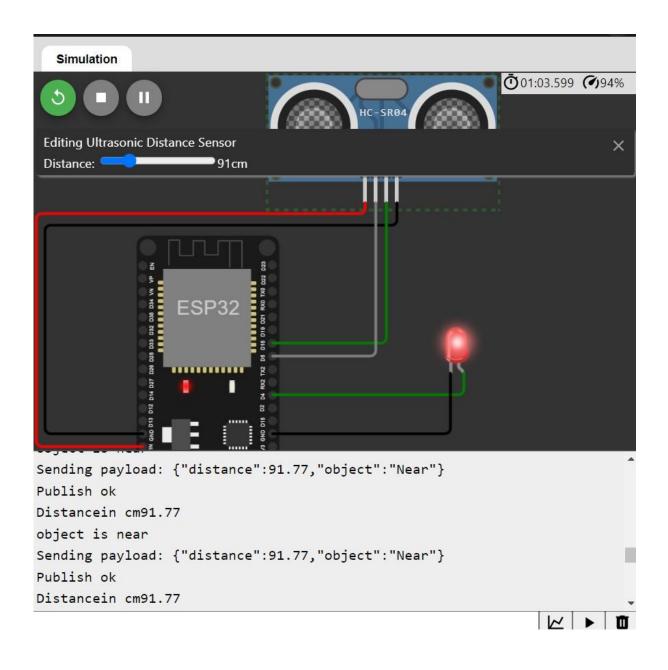
When object is not near to the ultrasonic sensor



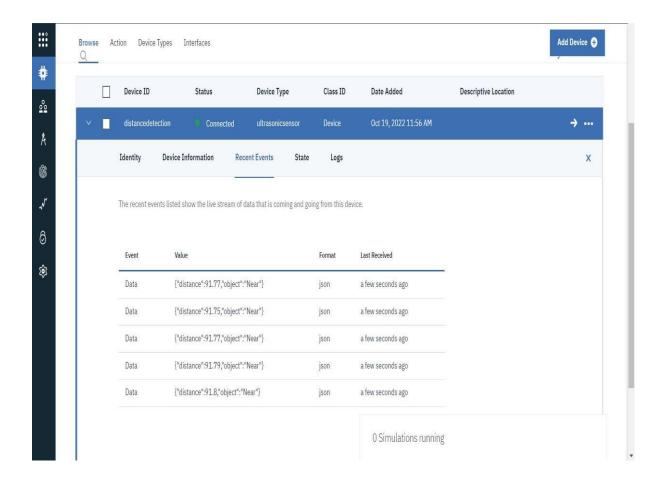
Data sent to the IBM cloud device when the object is far



When object is nearer to the ultrasonic sensor



Data sent to the IBM cloud device when the object is near



https://wokwi.com/projects/345964118720643668