

## Assignment 4

### Wokwi Assignment

Assignment Date	29 October 2022
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Maximum Marks	2 Marks

Assignment Question:

Write code and connections in wokwi for ultrasonic sensor.

Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

Wokowi Link: <https://wokwi.com/projects/346504267904844371>

Program code:

```
#include <WiFi.h> //library for wifi
```

```
#include <PubSubClient.h> //library for MQTT
```

```
#define ECHO_GPIO 12
```

```
#define TRIGGER_GPIO 13
```

```
#define MAX_DISTANCE_CM 100 // Maximum of 5 meters
```

```
#include "Ultrasonic.h"
```

```
Ultrasonic ultrasonic(13, 12);
```

```
int distance;
```

```
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);
```

```
//-----credentials of IBM Accounts-----
```

```

#define ORG "8w06mr"//IBM ORGANITION ID

#define DEVICE_TYPE "ESP32"//Device type mentioned in ibm watson IOT Platform

#define DEVICE_ID "ESP"//Device ID mentioned in ibm watson IOT Platform

#define TOKEN "123456789" //Token

String data3;

float h, t;


//----- Customise the above values -----

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name

char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event perform and format in
which data to be send

char subscribetopic[] = "iot-2/cmd/command/fmt/String";// cmd REPRESENT command type AND
COMMAND IS TEST OF FORMAT STRING

char authMethod[] = "use-token-auth";// authentication method

char token[] = TOKEN;

char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id


//-----

WiFiClient wifiClient; // creating the instance for wificlient

PubSubClient client(server, 1883, callback, wifiClient); //calling the predefined client id by passing
parameter like server id,portand wificredential


void setup()// configureing the ESP32
{
  Serial.begin(115200);

  delay(10);

  Serial.println();

  wificonnect();

  mqttconnect();

```

```
}
```

```
void loop()// Recursive Function
```

```
{
```

```
distance = ultrasonic.read(CM);
```

```
if (distance < 100) {
```

```
    Serial.print("Distance in CM: ");
```

```
    Serial.println(distance);
```

```
    PublishData(distance);
```

```
    delay(1000);
```

```
    if (!client.loop()) {
```

```
        mqttconnect();
```

```
    }
```

```
}
```

```
delay(1000);
```

```
}
```

```
/*.....retrieving to Cloud.....*/
```

```
void PublishData(float temp) {
```

```
    mqttconnect();//function call for connecting to ibm
```

```
    /*
```

```
        creating the String in in form JSon to update the data to ibm cloud
```

```
    */
```

```
    String payload = "{\"Alert Distance\":\"";
```

```
payload += temp;
```

```
payload += "}";
```

```
Serial.print("Sending payload: ");
```

```
Serial.println(payload);
```

```
if (client.publish(publishTopic, (char*) payload.c_str())) {
```

```
    Serial.println("Publish ok");// if it successfully upload data on the cloud then it will print publish ok
```

```
in Serial monitor or else it will print publish failed
```

```
    } else {
```

```
        Serial.println("Publish failed");
```

```
    }
```

```
}
```

```
void mqttconnect() {
```

```
    if (!client.connected()) {
```

```
        Serial.print("Reconnecting client to ");
```

```
        Serial.println(server);
```

```
        while (!client.connect(clientId, authMethod, token)) {
```

```
            Serial.print(".");
```

```
            delay(500);
```

```
        }
```

```
        initManagedDevice();
```

```
        Serial.println();
```

```
    }
```

```
}
```

```
void wificonnect() //function definition for wificonnect
```

```

{
    Serial.println();

    Serial.print("Connecting to ");

    WiFi.begin("Wokwi-GUEST", "", 6); //passing the wifi credentials to establish the connection
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }

    Serial.println("");
    Serial.println("WiFi connected");
    Serial.println("IP address: ");
    Serial.println(WiFi.localIP());
}

void initManagedDevice() {
    if (client.subscribe(subscribetopic)) {
        Serial.println((subscribetopic));
        Serial.println("subscribe to cmd OK");
    } else {
        Serial.println("subscribe to cmd FAILED");
    }
}

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{
    Serial.print("callback invoked for topic: ");
    Serial.println(subscribetopic);
    for (int i = 0; i < payloadLength; i++) {

```

```

//Serial.print((char)payload[i]);

data3 += (char)payload[i];
}

Serial.println("data: " + data3);

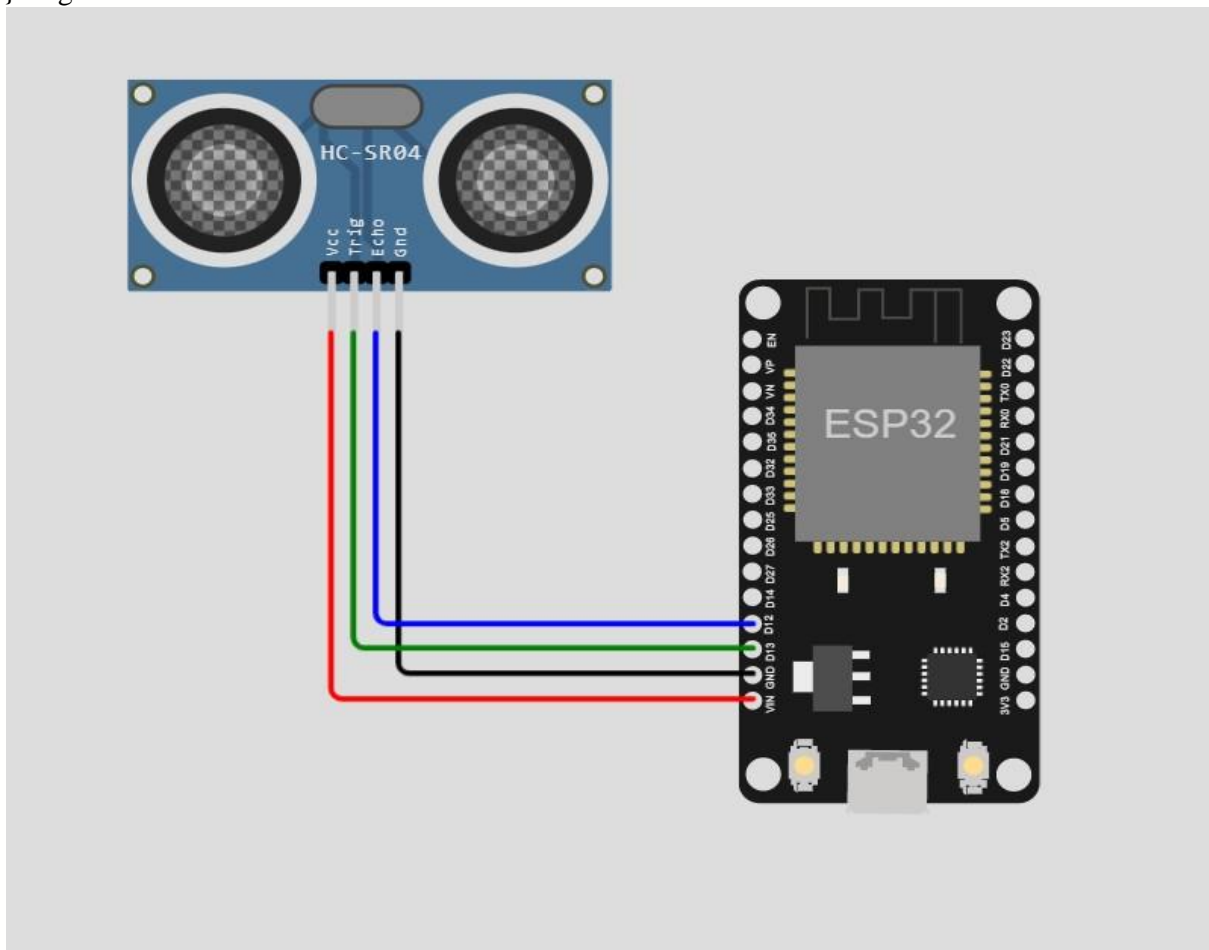
if (data3 == "lighton")
{
    Serial.println(data3);
}

else

{
    Serial.println(data3);
}

data3 = "";
}
}
Diagram:

```



When the distance is less than 100cm the alert is sent to the IBM cloud

IBM Watson IoT Platform

Back

Device Drilldown - ESP

Connection Information

Recent Events

State

Device Information

Metadata

Diagnostics

Connection Logs

Device Actions

Event	Value	Format	Last Received
Data	{"Alert Distance":91}	json	a few seconds ago
Data	{"Alert Distance":91}	json	a few seconds ago
Data	{"Alert Distance":91}	json	a few seconds ago
Data	{"Alert Distance":91}	json	a few seconds ago
Data	{"Alert Distance":91}	json	a few seconds ago

State

This table shows a list of data points that are reported by this device.

Showing Raw Data | No Interfaces Available

Property	Value	Type
0 Simulations running		

Simulation

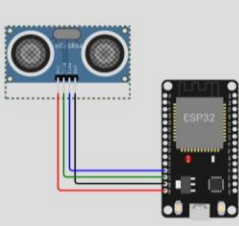
Code

00:59.317

71%

Editing Ultrasonic Distance Sensor

Distance: 87cm



Sending payload: {"Alert Distance":91.00}

Publish ok

Distance in CM: 91

Sending payload: {"Alert Distance":91.00}

When the distance is more than 100cm the alert is not sent to the IBM cloud

IBM Watson IoT Platform

Device Drilldown - ESP

Connection Information

Recent Events

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
-------	-------	--------	---------------

Waiting for device events...

0 Simulations running

WOKWI

Simulation

Code

01:42.500 98%

Editing Ultrasonic Distance Sensor

Distance: 276cm

Sending payload: {"Alert Distance": "91.00"}  
Publish ok  
Distance in CM: 91  
Sending payload: {"Alert Distance": "91.00"}