S. Valarmathi Assignment -4

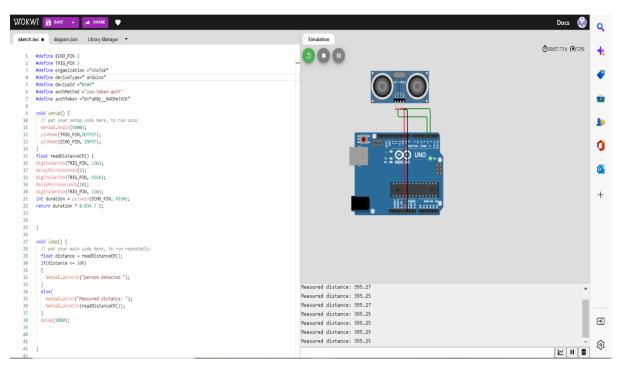
Question-1: Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to IBM cloud and display in device recent events.

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Solution:
#define ECHO_PIN 2
#define TRIG_PIN 3
#define organization ="46x7xk"
#define deviceType=" arduino"
#define deviceId ="0504"
#define authMethod ="use-token-auth"
#define authToken ="dv*uK8y X4O5m!V(K"
void setup() {
 // put your setup code here, to run once:
 Serial.begin(9600);
 pinMode(TRIG_PIN,OUTPUT);
 pinMode(ECHO_PIN, INPUT);
float readDistanceCM() {
digitalWrite(TRIG_PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
```

```
int duration = pulseIn(ECHO_PIN, HIGH);
return duration * 0.034 / 2;
}
void loop() {
// put your main code here, to run repeatedly:
 float distance = readDistanceCM();
 if(distance <= 100)
 {
  Serial.println("person detected ");
 }
 else{
  Serial.print("Measured distance: ");
  Serial.println(readDistanceCM());
 }
 delay(1000);
}
```

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       1 #define ECHO_PIN 2
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            #define TRIG_PIN 3
       3 #define organization ="46x7xk"
4 #define deviceType=" arduino"
5 #define deviceId ="0504"
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       6 #define authMethod ="use-token-auth"
7 #define authToken ="dv*uK8y_X405m!V(K"
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       9 void setup() {
           void setup() {
   // put your setup code here, to run once:
   Serial.begin(9680);
   pinMode(RXIG_PIM,CUTPUT);
   pinMode(ECHO_PIM, INPUT);
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      15 float readDistanceCM() {
      16 digitalWrite(TRIG_PIN, LOW);
17 delayMicroseconds(2);
      18 digitalWrite(TRIG_PIN, HIGH);
     19 delayMicroseconds(10);
20 digitalWrite(TRIG_PIN, LOW);
21 int duration = pulseIn(ECHO_PIN, HIGH);
22 return duration * 0.094 / 2;
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      24
      25 }
      27 void loop() {
             // put your main code here, to run repeatedly:
             float distance = readDistanceCM();
if(distance <= 100)</pre>
      30
31
32
                 Serial.println("person detected ");
              Serial.print("Measured distance: ");
Serial.println(readDistanceCM());
              delay(1000);
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     41
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      42 }
```

Output:



Wokwi Link: https://wokwi.com/projects/347484942224065107

IBM CLOUD

Device Recent Events

