

ARDUINO BOARD

```
#include <WiFi.h>

#include <WiFiClient.h>

#include <PubSubClient.h>

#include <ArduinoJson.h>

#include <TinyGPS++.h>

#define RXD2 16

#define TXD2 17

HardwareSerial neogps(1);


TinyGPSPplus gps;

char arr[100];


const char* ssid = "HOME WIFI";

const char* password = "EzMadhiBhaRad12.";


#define ID "17cmwk"

#define DEVICE_TYPE "Tracker"

#define DEVICE_ID "gps1"

#define TOKEN "childtracker1"


char server[] = ID ".messaging.internetofthings.ibmcloud.com";

char publish_Topic1[] = "iot-2/evt/Data1/fmt/json";

char publish_Topic2[] = "iot-2/evt/Data2/fmt/json";

char authMethod[] = "use-token-auth";

char token[] = TOKEN;

char clientId[] = "d:" ID ":" DEVICE_TYPE ":" DEVICE_ID;


WiFiClient wifiClient;
```

```
PubSubClient client(server, 1883, NULL, wifiClient);
```

```
void setup() {  
    Serial.begin(115200);  
    Serial.println();  
    wifi_init();  
}
```

```
long previous_message = 0;
```

```
void loop() {  
    client.loop();  
    String payload = getLocationPayload();  
    if(payload==""){  
        return;  
    }  

```

```
    Serial.print("Sending payload: ");  
    Serial.println(payload);  
    if (client.publish(publish_Topic1, arr)) {  
        Serial.println("Published successfully");  
    } else {  
        Serial.println("Failed");  
    }  
    delay(2000);  
}
```

```
void wifi_init(){  
    WiFi.begin(ssid, password);  
    neogps.begin(9600,SERIAL_8N1,RXD2,TXD2);  
    while (WiFi.status() != WL_CONNECTED) {
```

```

    delay(500);

    Serial.print(".");
}

Serial.println("");

Serial.println(WiFi.localIP());

if (!client.connected()) {
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
        Serial.print(".");
        delay(500);
    }
    Serial.println("Connected TO IBM IoT cloud!");
}
}

String getLocationPayload(){
    boolean newData = false;
    for(unsigned long start = millis();millis()-start<1000;){
        while(neogps.available()){
            if(gps.encode(neogps.read())){
                newData = true;
            }
        }
    }

    String payload;
    if(newData == true){
        newData = false;
        payload = locationPayloadGenerator();
    }
}

```

```

    }
    else{
        Serial.println("No data");
        payload = "{}";
    }
    return payload;
}

String locationPayloadGenerator(){
    String payload = "{}";
    if(gps.location.isValid()){
        float lat = gps.location.lat();
        float lon = gps.location.lng();
        payload = "{\"latitude\" : "+String(lat)+"\", \"longitude\" : "+String(lon)+"}";
        create_json(lat,lon);
    }
    return payload;
}

void create_json(float lat,float lon){
    StaticJsonDocument<100> doc;
    JsonObject root = doc.to<JsonObject>();
    root["lat"] = lat;
    root["lon"] = lon;
    serializeJsonPretty(doc,arr);
}

```