IOT Assignment 1

Topic: Smart Home in Thinker CAD using 2+ sensors, Led and Buzzer in Single code.

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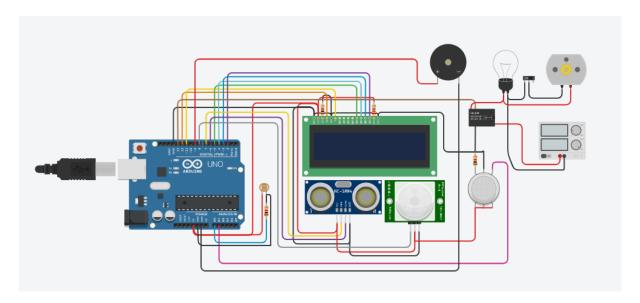


Fig: Smart Home Simulation Design

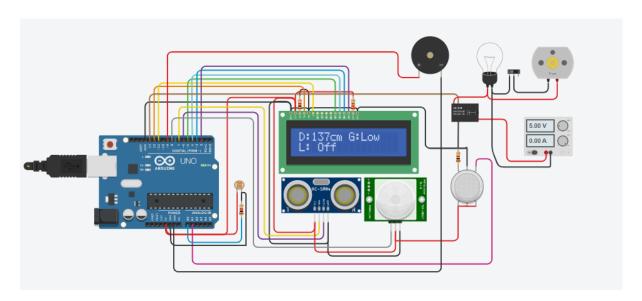


Fig: Smart Home Simulation Design Output

Code:

```
#include <LiquidCrystal.h>
LiquidCrystal lcd(12, 11, 5, 4, 3, 2);
int distanceThreshold = 0;
int cm = 0;
int inches = 0;
int buzzer=9;
int releNO = 13;
int inputPir = 8;
int val = 0;
int resuldoSensorLDR;
int sensorLDR = A0;
int const PINO_SGAS = A1;
long readUltrasonicDistance(int triggerPin, int echoPin)
{
 pinMode(triggerPin, OUTPUT);
 digitalWrite(triggerPin, LOW);
 delayMicroseconds(2);
 digitalWrite(triggerPin, HIGH);
 delayMicroseconds(10);
 digitalWrite(triggerPin, LOW);
 pinMode(echoPin, INPUT);
 return pulseIn(echoPin, HIGH);
}
void setup() {
 lcd.begin(16, 2);
 pinMode(releNO, OUTPUT);
 pinMode(inputPir, INPUT);
 pinMode(sensorLDR, INPUT);
 Serial.begin(9600);
```

```
}
void loop() {
 distanceThreshold = 350;
 cm = 0.01723 * readUltrasonicDistance(7, 6);
 inches = (cm / 2.54);
 lcd.setCursor(0,0);
 lcd.print("D:");
 lcd.print(cm);
 lcd.print("cm");
 delay(10);
 pinMode(buzzer, OUTPUT);
 if(buzzer >= 15 && buzzer <= 30)
 digitalWrite(buzzer, HIGH);
 delay(2000);
 }
 else
 digitalWrite(buzzer, LOW);
 delay(2000);
  val = digitalRead(inputPir);
 resuldoSensorLDR = analogRead(sensorLDR);
 if(resuldoSensorLDR<600)</pre>
  if(val == HIGH)
   digitalWrite(releNO, HIGH);
   lcd.setCursor(0,1);
```

```
lcd.print("L: On ");
   delay(5000);
 }
  else{
   digitalWrite(releNO, LOW);lcd.setCursor(0,1);
 lcd.print("L: Off");
   delay(300);
 }
}
 else{ digitalWrite (releNO, LOW);
 Serial.println(resuldoSensorLDR);
 delay(500);
 }
 int color = analogRead(PINO_SGAS);
 lcd.setCursor(8,0);
 //lcd.print("");
 if(color <= 85){
  lcd.print("G:Low ");
 } else if(color <= 120){
  lcd.print("G:Med ");
 } else if(color <= 200){
  lcd.print("G:High");
 } else if(color <= 300){
  lcd.print("G:Ext ");
 }
 delay(250);
}
```