

```
// C++ code
void setup()
 //LED_BUILTIN =PIN 13
 pinMode(LED_BUILTIN, OUTPUT);
 pinMode(2,INPUT);
 pinMode(4,OUTPUT); Serial.begin(9600);
 Serial.println("Start");
void loop()
 int TEMP =analogRead(A0);
 Serial.println(TEMP);
 int SENSORSTATE =digitalRead(2);
 Serial.println(SENSORSTATE);
 if(SENSORSTATE==1){
 digitalWrite(LED_BUILTIN, HIGH);
  digitalWrite(4,HIGH);
 Serial.println("DETECTED");
```

```
else{
 digitalWrite(LED_BUILTIN, LOW);
  digitalWrite(4,LOW);
  Serial.println("NOT DETECTED");
 if(TEMP>200){
  digitalWrite(4,HIGH);
  Serial.println(TEMP);
 else{
  digitalWrite(4,LOW);
  Serial.println(TEMP);
 delay(10);
```

MOTION SENSOR DECTECTION

All changes saved

























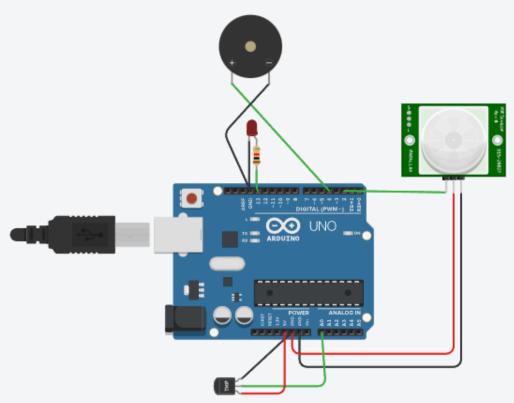












```
1 (Arduino Uno R3) -
Text
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   void setup()
     //LED BUILTIN =PIN 13
     pinMode(LED_BUILTIN, OUTPUT);
     pinMode(2,INPUT);
     pinMode(4,OUTPUT); Serial.begin(9600);
      Serial.println("Start");
10
11
    void loop()
13
14
15
     int TEMP =analogRead(A0);
16
      Serial.println(TEMP);
17
     int SENSORSTATE =digitalRead(2);
      Serial.println(SENSORSTATE);
18
19
     if(SENSORSTATE==1) {
     digitalWrite(LED_BUILTIN, HIGH);
20
21
       digitalWrite(4, HIGH);
22
       Serial.println("DETECTED");
23
  Serial Monitor
```

MOTION SENSOR DECTECTION

All changes saved



Start Simulation





Send To















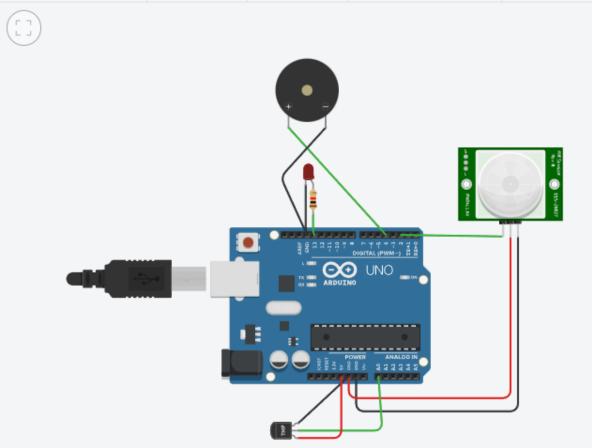
Text











```
19
     if(SENSORSTATE==1){
20
     digitalWrite(LED_BUILTIN, HIGH);
21
       digitalWrite(4,HIGH);
22
      Serial.println("DETECTED");
23
24
25
      else{
     digitalWrite(LED_BUILTIN, LOW);
26
27
       digitalWrite(4,LOW);
28
         Serial.println("NOT DETECTED");
29
30
     if(TEMP>200){
       digitalWrite(4,HIGH);
31
32
       Serial.println(TEMP);
33
34
35
     else{
36
       digitalWrite(4,LOW);
37
       Serial.println(TEMP);
38
39
40
41
     delay(10);
42
```