# Assignment -4

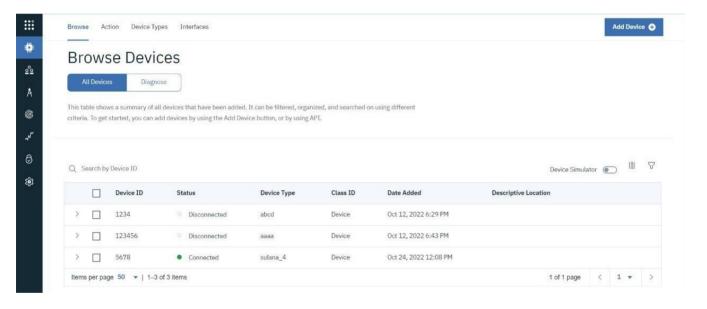
Assignment Date	22 October 2022
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Write code and connection in Wowki for ultrasonic sensor.

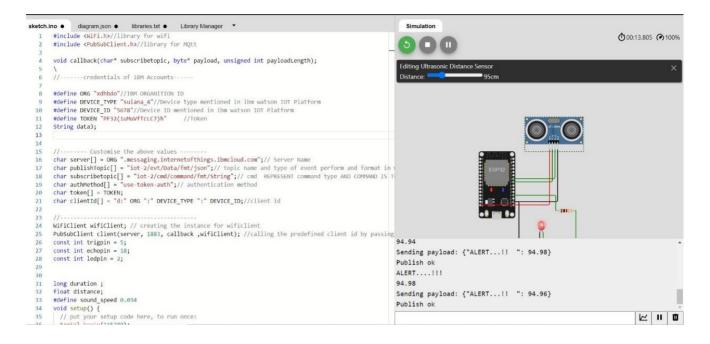
Whenever distance is less than 100 cm send "Alert" to IBM cloud and display in devicerecent events

Wowki link: https://wokwi.com/projects/346389445244617300

Step 1: Add new device in IBM cloud

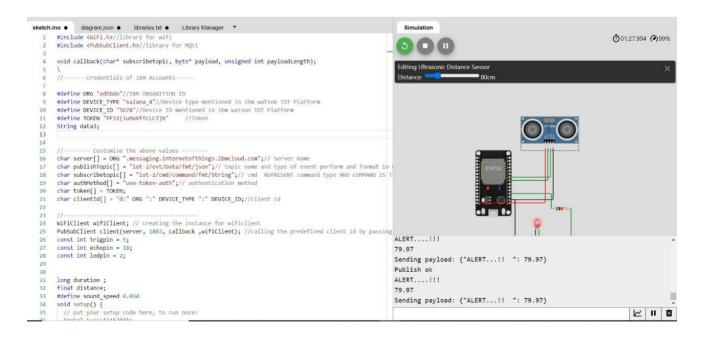


## Step 2: Complete the Circuit and run the program



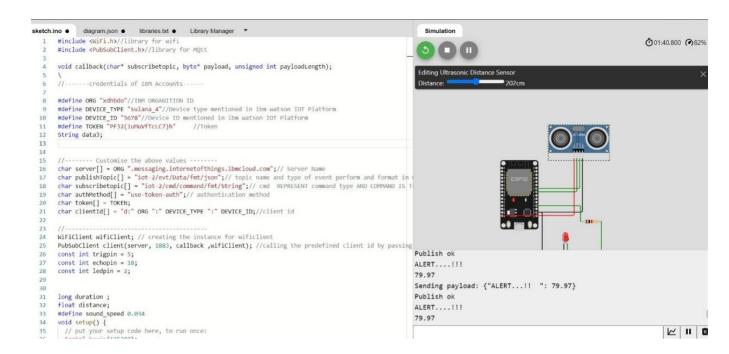
### Output in WOWKI

a) when the distance is below 100 cms



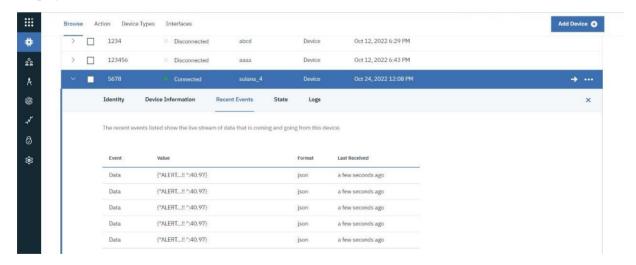


b) when the distance is above 100 cms, (no alert message is displayed here for 202 cm)



### Output in IBM CLOUD (Watson Platform)

Displayed in device recent events



### Program Code:



```
#include <WiFi.h>//library for wifi
#include <PubSubClient.h>//library for MQtt
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);
//----credentials of IBM Accounts-----
#define ORG "xdhbdo"//IBM ORGANITION ID
#define DEVICE TYPE "sulana 4"//Device type mentioned in ibm watson IOT Platform#define
DEVICE ID "5678"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "PF32(1uMuVfTcLC7)h"
String data3;
//----- Customise the above values ------
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event perform andformat in
which data to be send
char subscribetopic[] = "iot-2/cmd/command/fmt/String";// cmd REPRESENT commandtype AND
COMMAND IS TEST OF FORMAT STRING
char authMethod[] = "use-token-auth";// authentication methodchar token[]
= TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id
//<sub>______</sub>
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback, wifiClient); //calling the predefined client id bypassing
parameter like server id, portand wificredential
const int trigpin = 5;
const int echopin = 18;
const int ledpin = 2;
long duration;
float distance;
#define sound_speed 0.034
void setup() {
// put your setup code here, to run once:
 Serial.begin(115200);
 pinMode(trigpin, OUTPUT);
 pinMode(echopin, OUTPUT);
 pinMode(ledpin, OUTPUT);
 wificonnect(); mqttconnect();
}
void loop() {
 digitalWrite(trigpin, LOW);
 digitalWrite(trigpin, HIGH);
 delayMicroseconds(10);
 digitalWrite(trigpin, LOW);
 duration= pulseIn(echopin,HIGH);
```



```
distance = duration * sound_speed /2;
 if(distance<=100){
 PublishData(distance);
 delay(1000);
 if (!client.loop()) {
  mqttconnect();
  digitalWrite(ledpin, HIGH);
  Serial.println("ALERT
   .....!!!")
  Serial.println(distance);
 else
  digitalWrite(ledpin, LOW);
 // put your main code here, to run repeatedly:
 delay(10); // this speeds up the simulation
}
/*....retrieving to Cloud....*/
void PublishData(float distance) { mqttconnect();//function call
 for connecting to ibm
  // creating the String in in form JSon to update the data to ibm cloudString payload
 = "{\"ALERT...!! \": ";
 payload += distance;
 payload += "}";
 Serial.print("Sending payload: ");
 Serial.println(payload);
 if (client.publish(publishTopic, (char*) payload.c_str())) {
  Serial.println("Publish ok");// if it sucessfully upload data on the cloud then it will printpublish ok in
Serial monitor or else it will print publish failed
 } else {
  Serial.println("Publish failed");
 }
void mqttconnect() {
 if (!client.connected()) {
  Serial.print("Reconnecting client to ");
  Serial.println(server);
  while (!!!client.connect(clientId, authMethod, token)) {Serial.print(".");
   delay(500);
  initManagedDevice();
   Serial.println();
 }
}
```



```
void wificonnect() //function defination for wificonnect
 Serial.println();
 Serial.print("Connecting to ");
 WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection while
 (WiFi.status() != WL_CONNECTED) {
  delay(500);
  Serial.print(".");
 Serial.println(""); Serial.println("WiFi
 connected");Serial.println("IP
 address: ");
 Serial.println(WiFi.localIP());
void initManagedDevice() {
 if (client.subscribe(subscribetopic)) {
  Serial.println((subscribetopic));
  Serial.println("subscribe to cmd OK");
 } else {
  Serial.println("subscribe to cmd FAILED");
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
 Serial.print("callback invoked for topic: ");
 Serial.println(subscribetopic);
 for (int i = 0; i < payloadLength; i++) {
  //Serial.print((char)payload[i]); data3
  += (char)payload[i];
 Serial.println("data: "+ data3);
 if(data3=="lighton")
   Serial.println(data3);
 else
   Serial.println(data3);
data3="";
```