## **ASSIGNMENT4**

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Write code and connections in wokwi for ultrasonic sensor. Whenever the distance is less than 100 cms send "alert" to IBM cloud and display indevice recent events.

```
code:
#include<WiFi.h>#include
<PubSubClient.h>WiFiClientwi
fiClient;Stringdata3;#defineOR
G"x0fxss"
#defineDEVICE_TYPE"Noder"#de
fineDEVICE_ID"1234"
#defineTOKEN"987654321"
#definespeed0.034
#defineled14
charserver[]=ORG".messaging.internetofthings.ibmcloud.com";charpublishTopic[]="
iot-2/evt/shanmugam_assignment4/fmt/json";chartopic[]="iot-
2/cmd/home/fmt/String";
charauthMethod[]="use-token-
auth";chartoken[]=TOKEN;
charclientId[]="d:"ORG":"DEVICE_TYPE":"DEVICE_ID;
PubSubClientclient(server,1883,wifiClient);
```

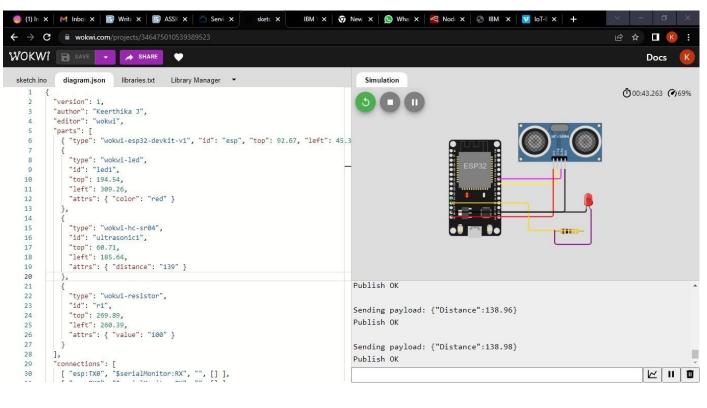
constinttrigpin=5;cons tintechopin=18;Stringc ommand;

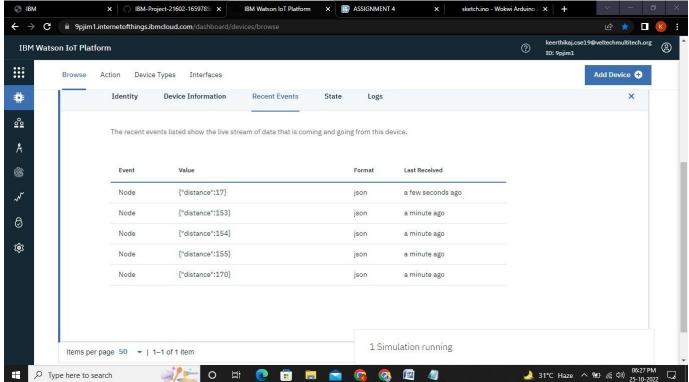
```
Stringdata="";
longduration;fl
oatdist;
voidsetup()
{
  Serial.begin(115200);pinMode(led,
  OUTPUT);pinMode(trigpin,OUTPUT);
  pinMode(echopin,INPUT);wifiConne
  ct();mqttConnect();
}
voidloop(){
  boolisNearby=dist<100;digitalWrite
  (led,isNearby);
  publishData();delay(500);
  if(!client.loop()){mqttConnect();
  }
}
voidwifiConnect(){
  Serial.print("Connectingto");Serial.print("Wifi");WiFi.b
  egin("Wokwi-GUEST","",6);
  while(WiFi.status()!=WL_CONNECTED){del
     ay(500);
    Serial.print(".");
  }
```

```
Serial.print("WiFiconnected,IPaddress:");Serial.println(WiFi.localIP());
}
voidmqttConnect(){
  if(!client.connected()) {
     Serial.print("ReconnectingMQTTclientto");Serial.println(server);while(!client.c
     onnect(clientId,authMethod,token)){
       Serial.print(".");delay(500);
     }
     initManagedDevice();
     Serial.println();
  }
}
voidinitManagedDevice(){
  if(client.subscribe(topic)){
     //Serial.println(client.subscribe(topic));Serial.println("
     IBMsubscribetocmdOK");
  }else{
     Serial.println("subscribetocmdFAILED");
  }
}
voidpublishData()
{
  digitalWrite(trigpin,LOW);digitalWrite(tri
  gpin,HIGH);delayMicroseconds(10);digit
  alWrite(trigpin,LOW);duration=pulseIn(e
  chopin,HIGH);dist=duration*speed/2;if(di
  st<100){
     Stringpayload="{\"AlertDistance\":";payload+=di
     st;
     payload+="}";
```

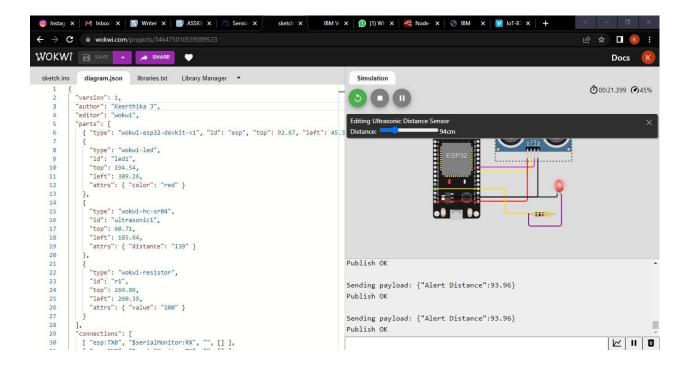
```
Serial.print("\n");Serial.print("Sen
  dingpayload:");Serial.println(payl
  oad);
  if(client.publish(publishTopic,(char*)payload.c_str())){Serial.println("PublishOK");
  }
}
  if(dist>100){
  Stringpayload="{\"Distance\":";payload+
  =dist;
  payload+="}";
  Serial.print("\n");Serial.print("Sen
  dingpayload:");Serial.println(payl
  oad);
   if(client.publish(publishTopic,(char*)payload.c_str())){Serial.println("PublishOK");
  }else{
     Serial.println("PublishFAILED");
  }
}
}
```

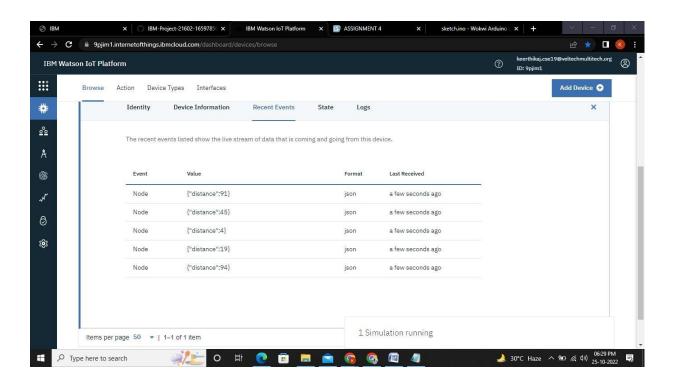
## OUTPUT:-i)Whendistancegreaterthan 100cm





## ii)Whendistancelessthan100cms.





## WOKWILINK

https://wokwi.com/projects/346491488923812434