Assignment 4
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TEAM ID	PNT2022TMID22305
PROJECT NAME	Signs with Smart Connectivity for Better Road Safety

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is lessthan 100 cms send "alert" to IBM cloud and display in device recent events

```
#include   <WiFi.h> #include
<PubSubClient.h>WiFiClient
wifiClient;
String data3;
#define ORG "c0mbt9" #define
DEVICE_TYPE "Node"#define
DEVICE_ID "1234"
#define TOKEN "987654321"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; char
publishTopic[] = "iot-2/evt/shanmugam_assignment4/fmt/json";char topic[] =
"iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";char
token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long duration;
float dist; void
setup()
{
  Serial.begin(115200);
```

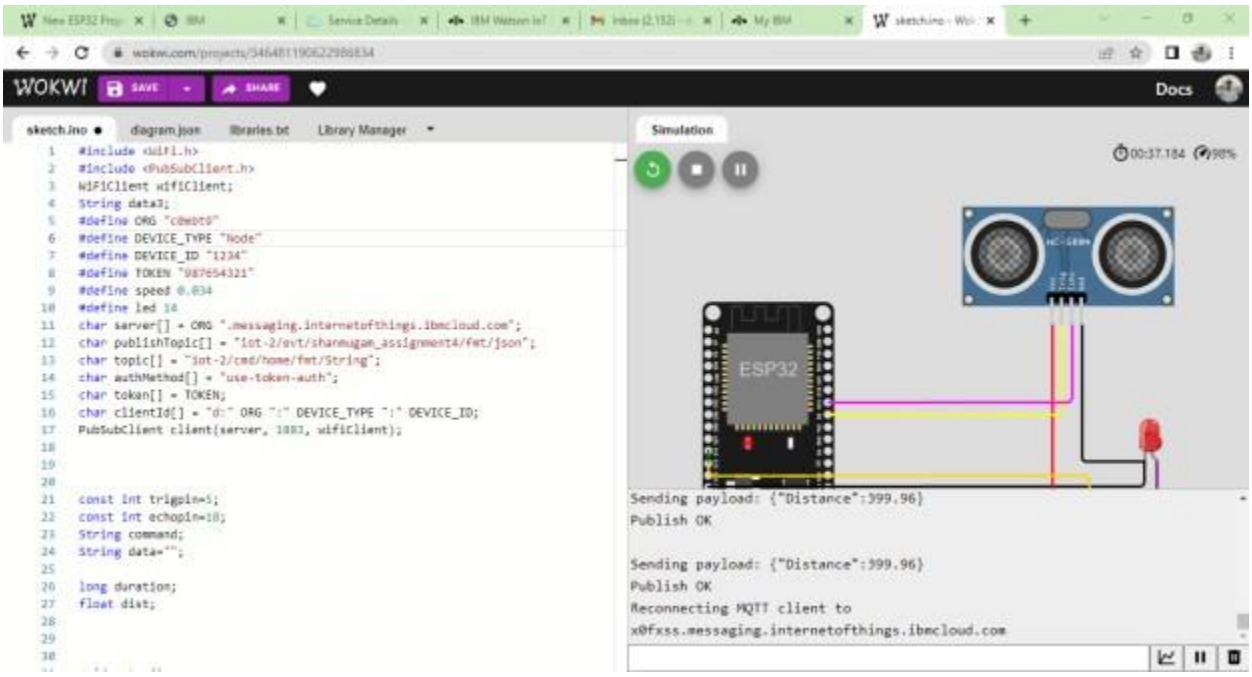
```
  pinMode(led, OUTPUT);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect(); mqttConnect();
}
void loop() {
  bool isNearby = dist < 100;
  digitalWrite(led,    isNearby);
  publishData();
  delay(500);
  if (!client.loop()) {
    mqttConnect();
  }
}
void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED)
    {delay(500);
    Serial.print(".");
  }
  Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}
void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);while
    (!client.connect(clientId, authMethod, token)) { Serial.print(".");
      delay(500);
    }
    initManagedDevice();
    Serial.println();
  }
}
void initManagedDevice() { if
  (client.subscribe(topic)) {
```

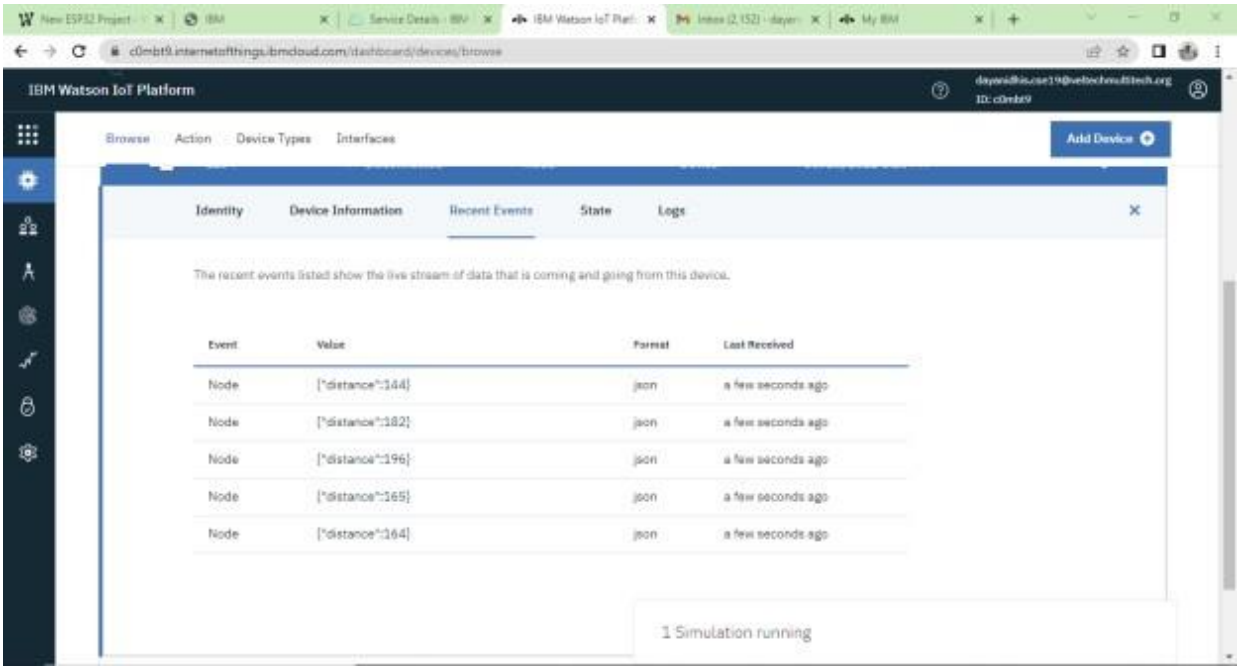
```
   / Serial.println(client.subscribe(topic));
    Serial.println("IBM subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}
void publishData()
{
  digitalWrite(trigpin,LOW);
  digitalWrite(trigpin,HIGH);
  delayMicroseconds(10);
  digitalWrite(trigpin,LOW);
  duration=pulseIn(echopin,HIGH);
  dist=duration*speed/2; if(dist<100){
    String payload = "{\"Alert Distance\":";
    payload += dist;
    payload += "}";
    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str())) {
      Serial.println("Publish OK");
    }

  }
    if(dist>100){
    String payload = "{\"Distance\":";payload
    += dist;
    payload += "}";
    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
     if(client.publish(publishTopic, (char*) payload.c_str())) {
      Serial.println("Publish OK");
    }else {
      Serial.println("Publish  FAILED");
```

```
  }

 }
}
```

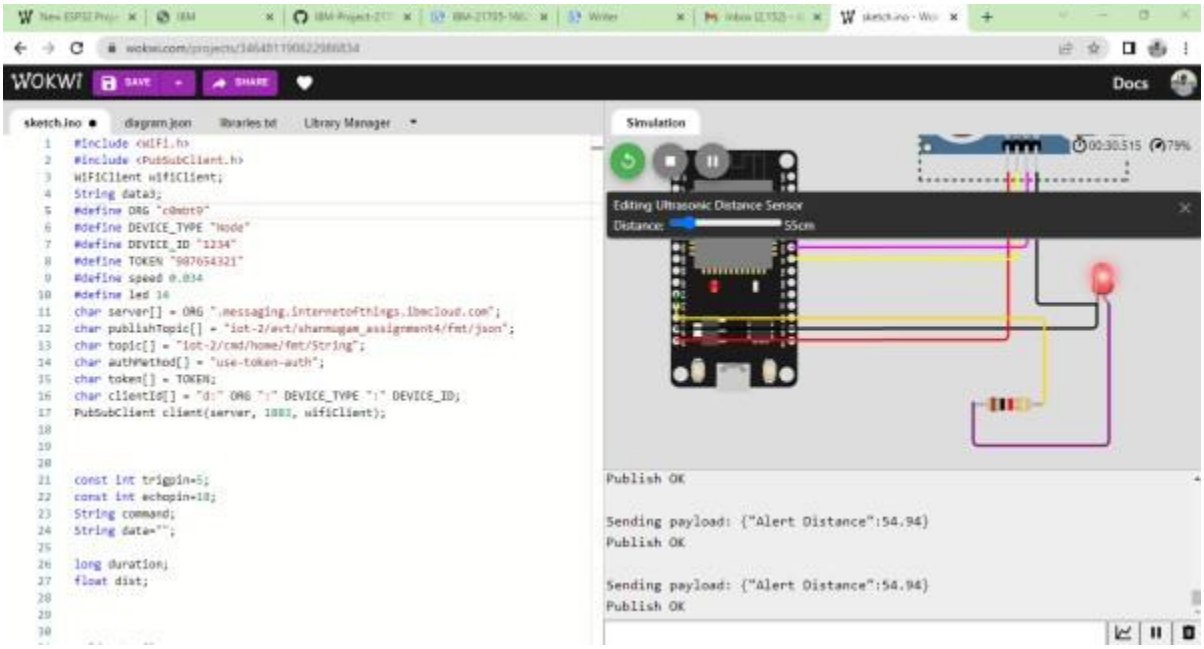
OUTPUT:

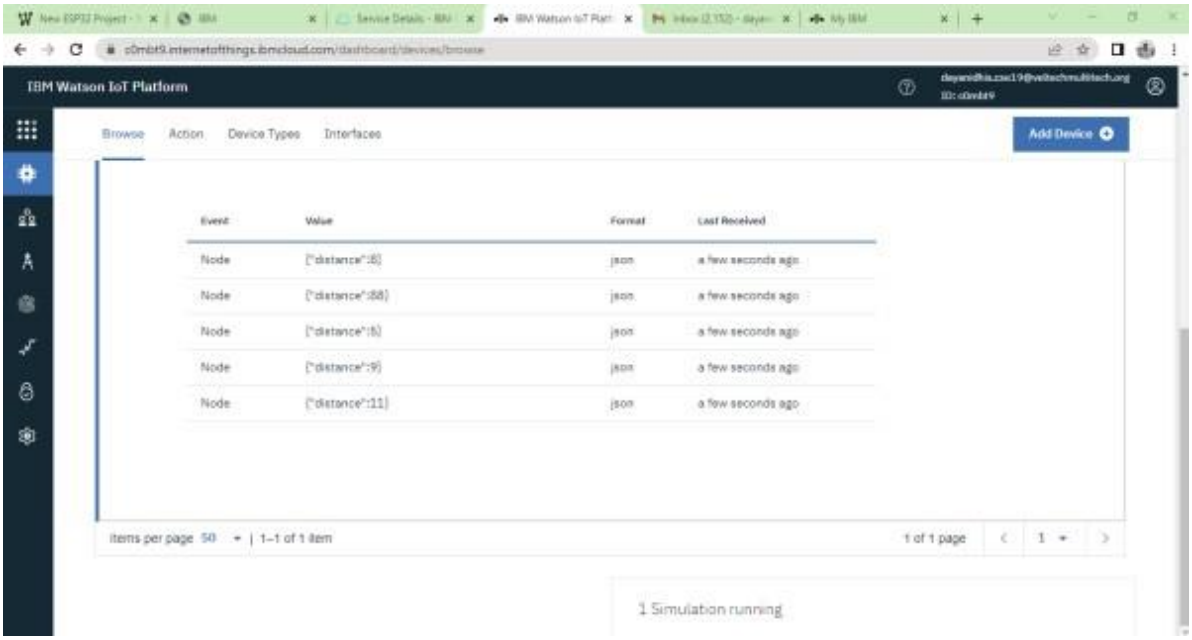
i) When distance greater than 100 cm





ii) When distance is less than 100





WOKWI LINK -

https:/ wokwi.com/projects/346481190622986834