Assignment 4

Student Name: Saravanan S

DATE	25-10-2022
TEAM ID	PNT2022TMID22305
PROJECT NAME	Signs with Smart Connectivity for Better Road Safety

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to IBM cloud and display in device recent events

```
#include <WiFi.h>
#include < PubSubClient.h >
WiFiClient wifiClient;
String data3;
#define ORG "c0mbt9"
#define DEVICE_TYPE "Node"
#define DEVICE ID "1234"
#define TOKEN "987654321"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; char
publishTopic[] = "iot-2/evt/shanmugam_assignment4/fmt/json";char
topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
const int trigpin=5;
const int
echopin=18;
String command;
String data="";
long
duration;float
dist; void
setup()
 Serial.begin(115200);
```

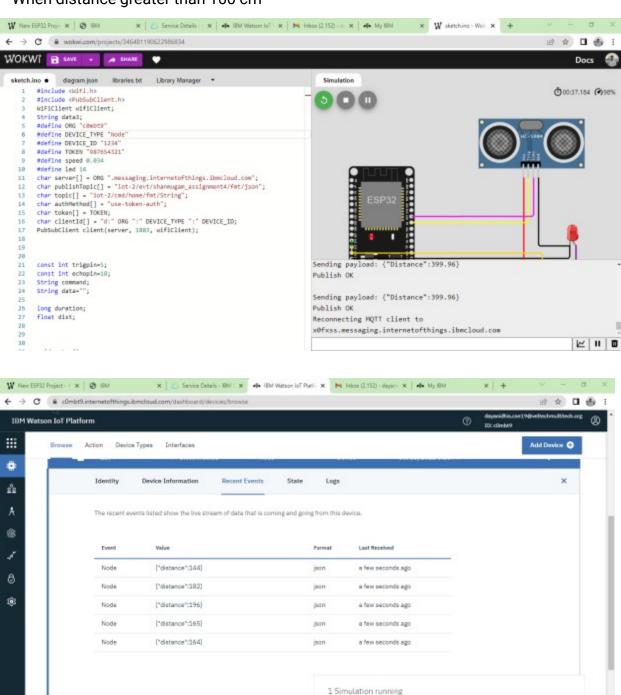
```
pinMode(led, OUTPUT);
 pinMode(trigpin, OUTPUT);
 pinMode(echopin, INPUT);
 wifiConnect();
 mqttConnect();
void loop() {
 bool isNearby = dist < 100;
 digitalWrite(led, isNearby);
 publishData();
 delay(500);
 if (!client.loop()) {
  mqttConnect();
 }
}
void wifiConnect() {
 Serial.print("Connecting to ");
 Serial.print("Wifi"); WiFi.begin("Wokwi-GUEST",
 "", 6);
 while (WiFi.status() != WL_CONNECTED) {
  delay(500);
  Serial.print(".");
 }
 Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}
void mqttConnect() {
 if (!client.connected()) {
  Serial.print("Reconnecting MQTT client to "); Serial.println(server);
  while (!client.connect(clientId, authMethod, token)) { Serial.print(".");
   delay(500);
  initManagedDevice();
  Serial.println();
 }
void initManagedDevice() {
 if (client.subscribe(topic)) {
```

```
/ Serial.println(client.subscribe(topic));
  Serial.println("IBM subscribe to cmd
  OK");
 } else {
  Serial.println("subscribe to cmd FAILED");
 }
}
void publishData()
 digitalWrite(trigpin,LOW);
 digitalWrite(trigpin,HIGH);
 delayMicroseconds(10);
 digitalWrite(trigpin,LOW);
 duration=pulseIn(echopin,HIGH);
 dist=duration*speed/2;
 if(dist<100){
  String payload = "{\"Alert Distance\":";
  payload += dist;
  payload += "}";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c_str())) {
   Serial.println("Publish OK");
  }
 }
  if(dist>100){
  String payload = "{\"Distance\":";
  payload += dist;
  payload += "}";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if(client.publish(publishTopic, (char*) payload.c_str())) {
   Serial.println("Publish OK");
  }else {
   Serial.println("Publish FAILED");
```

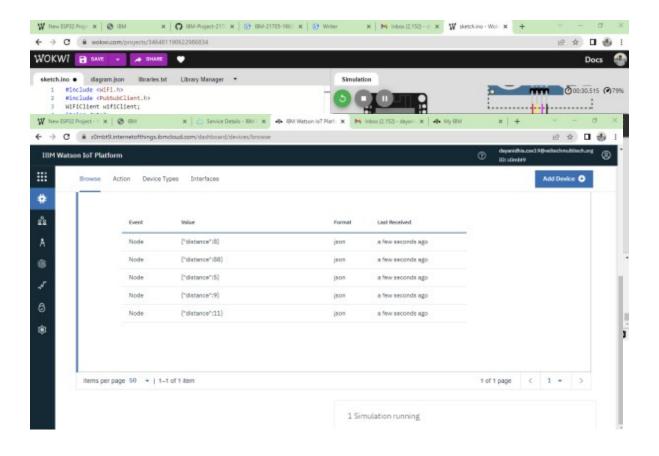
```
}
}
}
```

OUTPUT:

i) When distance greater than 100 cm



ii) When distance is less than 100



WOKWI LINK -

https://wokwi.com/projects/346481190622986834