Assignment -4

Assignment Date	21october 2022
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Maximum Marks	2marks

Question-1:

Write code and connection in wokwi for the ultrasonic sensor. Whenever the distance is less than 100cms send "alert" to the IBM cloud and display recent events.

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Solution:
#include <WiFi.h>
#include < PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "2yey9a"
#define DEVICE_TYPE "12345"
#define DEVICE_ID "958523"
#define TOKEN "Rkyi42H-+Yduer90Uh"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin=2;
const int echopin=4;
String command;
String data="";
long duration;
float dist:
void setup()
 Serial.begin(115200);
 pinMode(led, OUTPUT);
 pinMode(trigpin, OUTPUT);
 pinMode(echopin, INPUT);
 wifiConnect();
 mqttConnect();
```

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}
void loop() {
 bool is Nearby = dist < 100;
 digitalWrite(led, isNearby);
 publishData();
 delay(500);
 if (!client.loop()) {
  mqttConnect();
}
void wifiConnect() {
 Serial.print("Connecting to "); Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
 while (WiFi.status() != WL_CONNECTED) {
  delay(500);
  Serial.print(".");
 Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
void mqttConnect() {
 if (!client.connected()) {
  Serial.print("Reconnecting MQTT client to "); Serial.println(server);
  while (!client.connect(clientId, authMethod, token)) {
   Serial.print(".");
   delay(500);
  initManagedDevice();
  Serial.println();
}
void initManagedDevice() {
 if (client.subscribe(topic)) {
  // Serial.println(client.subscribe(topic));
  Serial.println("IBM subscribe to cmd OK");
 } else {
  Serial.println("subscribe to cmd FAILED");
void publishData()
 digitalWrite(trigpin,LOW);
 digitalWrite(trigpin,HIGH);
 delayMicroseconds(10);
 digitalWrite(trigpin,LOW);
 duration=pulseIn(echopin,HIGH);
 dist=duration*speed/2;
 if(dist<100){
  String payload = "{\"Normal Distance\":";
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payload += dist;
 payload += "}";
 Serial.print("\n");
 Serial.print("Sending payload: ");
 Serial.println(payload);
 if (client.publish(publishTopic, (char*) payload.c_str())) {
  Serial.println("Publish OK");
 }
}
 if(dist>101 && dist<111){
 String payload = "{\"Alert distance\":";
 payload += dist;
 payload += "}";
 Serial.print("\n");
 Serial.print("Sending payload: ");
 Serial.println(payload);
 if(client.publish(publishTopic, (char*) payload.c_str())) {
  Serial.println("Warning crosses 110cm -- it automatically of the loop");
  digitalWrite(led,HIGH);
 }else {
  Serial.println("Publish FAILED");
}
void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength){
Serial.print("callback invoked for topic:");
Serial.println(subscribeTopic);
for(int i=0; i<payloadLength; i++){</pre>
 dist += (char)payload[i];
Serial.println("data:"+ data3);
if(data3=="lighton"){
 Serial.println(data3);
 digitalWrite(led,HIGH);
data3="";
```



