

SMART WASTE MANAGEMENT SYSTEM FOR METROPOLITAN CITIES

Category: INTERNET OF THINGS

A PROJECT REPORT

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FROM

UNIVERSITY COLLEGE OF ENGINEERING KANCHEEPURAM

In fulfillment of project in IBM-NALAYATHIRAN 2022

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1.

INTRODUCTION**1.1 Project Overview:****Smart waste management System**

Smart waste management solutions use sensors placed in waste receptacles to measure fill levels and to notify city collection services when bins are ready to be emptied. Over time, historical data collected by sensors can be used to identify fill patterns, optimize driver routes and schedules, and reduce operational costs. The cost of these sensors is steadily decreasing, making IoT waste bins more feasible to implement and more attractive to city leaders.

1.2 Purpose:

Smart bins are the newest type of waste management technology that helps cities reduce waste effectively. A smart waste management system allows sanitation workers and employees to obtain real-time data, which helps prevent the bins from overflowing, contributing to healthier and smarter cities.

- Efficient waste collection in a short span of time with less labor,
- To minimize the harmful effects of waste on the environment,
- A cleaner and more organized city plan,
- Reducing the irregularly placed and excessive number of containers to help to improve the environmental image, and reduce noise pollution, and traffic density during collection by collecting waste at longer intervals.
- In the present scenario, we see the garbage bins being overloaded and all the garbage spilling out resulting in pollution. The detection, monitoring, and management of waste are one of the primary problems of the present era.
- People throw garbage in the dustbin which is already overflowed. Sometimes due to unclean garbage bins, bad smell arises also toxic and unhygienic gases are produced which is a way to

support Air pollution and other harmful diseases which are easily spreadable. It is the very bad look of the city.

2.

LITERATURE SURVEY

2.1 Existing Problem:

In the present scenario, we see the garbage bins being overloaded and all the garbage spills out resulting in pollution. The detection, monitoring, and management of waste are one of the primary problems of the present era.

A big challenge in urban cities is solid waste management. The garbage collecting authority in traditional waste management systems doesn't know about the level of garbage in dustbins the dust bins get full of garbage, then it gets overflowed as well as spilled out from the dustbin leading to unhygienic conditions in cities.

People throw garbage on that dustbin which is already overflowed. Sometimes due to unclean garbage bins, bad smell arises also toxic & unhygienic gases are produced which is a way to support Air pollution and other harmful diseases which are easily spreadable. It is very a bad look at the city. The use of a traditional system results in an efficient and time and money-spending System.

Hence, we design a system based on an IoT application for collecting garbage from particular areas whose garbage bins are overflowing with prior concerns. This method is advanced in which garbage management is automated. This project Garbage Monitoring system using IoT is a very innovative system that will help to keep the cities clean.

2.2 References:

1. K.S. Adu-Manu, C. Tapparello, W. Heinzelman, F.A. Katsriku, J.-D. Abdulai

A Smart IoT System for Waste Management: Without well management, the waste containers may be overflowed or give off unpleasant smell, which affect the public health. (2018).

2.

IoT based Waste collection Management System for Smart cities: In the recent decades, Urbanization has been a pivotal issue tremendously. In the meantime, there is an expansion in waste creation.(2019)

3.

IoT based Smart waste Management System: “Indian prospective”: In present scenario corporations in India doesn’t get real time information about the dustbins.(2019)

4.

Waste Management Improvement in cities using IoT: Implementing waste management the major challenge is the management of waste in cost optimal. And the containers everyday which is a complicates. (2020)

2.3 Problem Statement Definition:

Design a system based on IoT application for collecting garbage from particular area whose garbage bins are overflowing with prior concern. This method is advanced in which garbage management is automated. This project Garbage Monitoring system using IOT is a very innovative system which will help to keep the cities clean.

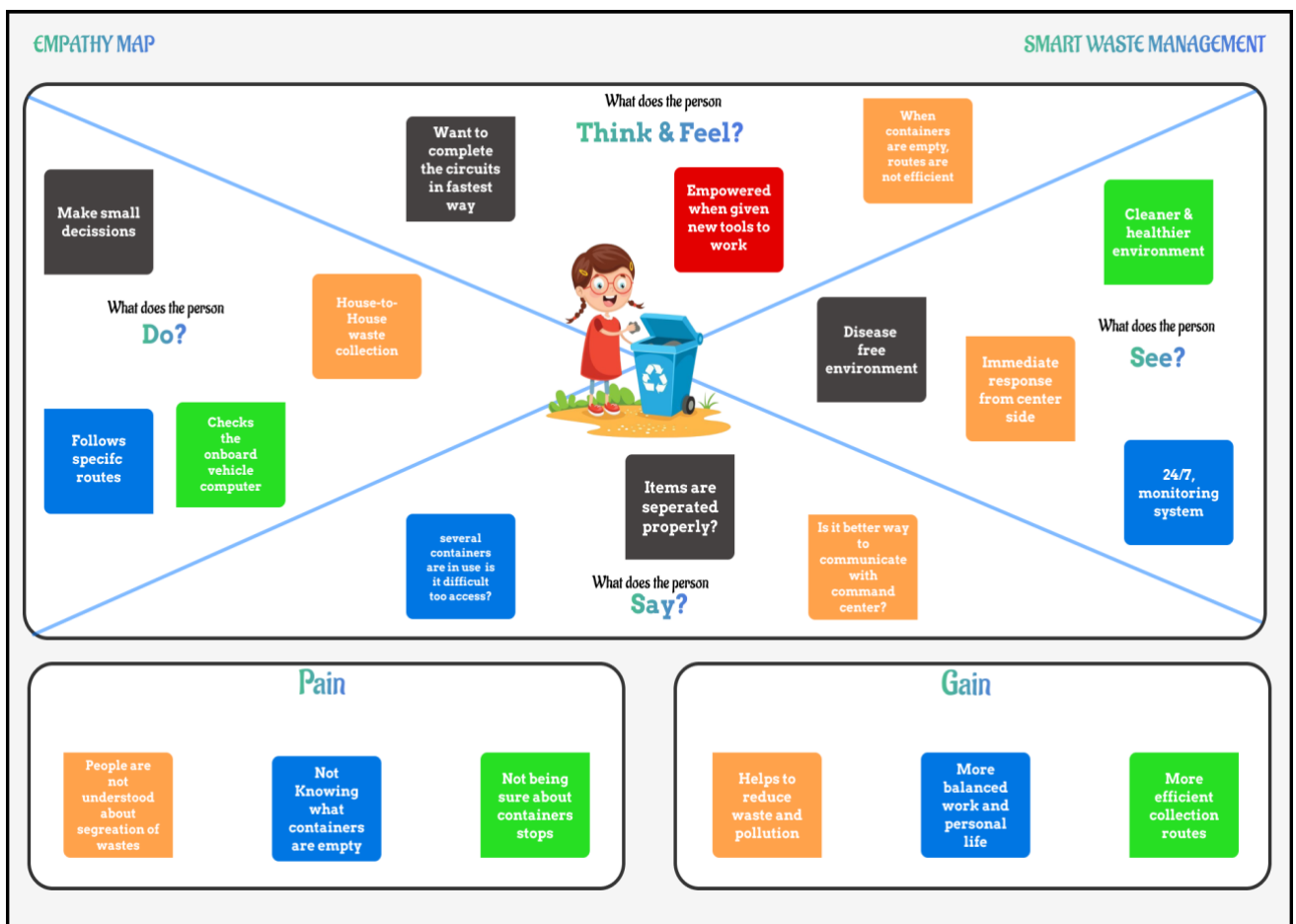
A growing population and economy, which means increased volumes of waste generated. This puts pressure on waste management facilities, which are already in short supply.

A policy and regulatory environment that does not actively promote the waste management hierarchy. This has limited the economic potential of the waste management sector, which has an estimated turnover of approximately R10 billion per annum¹¹. Both waste collection and the recycling industry make meaningful contributions to job creation and GDP, and they can expand further.

IDEATION & PROPOSED SOLUTION

3.1 Empathy Map Canvas:

An empathy map is a simple, easy-to-digest visual that captures knowledge about a user's behaviours and attitudes. It is a useful tool to help teams better understand their users. Creating an effective solution requires understanding the true problem and the person who is experiencing it. The exercise of creating the map helps participants consider things from the user's perspective along with his or her goals and challenges.




Reference: [ClickHere.](#)

3.2 Ideation & Brainstorming:

Ideation and Brainstorming Ideation is often closely related to the practice of brainstorming, a **specific technique that is utilized to generate new ideas**. A principal difference between ideation and brainstorming is that ideation is commonly more thought of as being an individual pursuit, while brainstorming is almost always a group activity.




Reference: [ClickHere](#)

Template



Brainstorm & idea prioritization

Use this template in your own brainstorming sessions so your team can unleash their imagination and start shaping concepts even if you're not sitting in the same room.


 10 minutes to prepare
 1 hour to collaborate
 2-8 people recommended

[Share template feedback](#)

→

Before you collaborate

A little bit of preparation goes a long way with this session. Here's what you need to do to get going.

 10 minutes

A

Team gathering

Define who should participate in the session and send an invite. Share relevant information or pre-work ahead.

B

Set the goal

Think about the problem you'll be focusing on solving in the brainstorming session.

C

Learn how to use the facilitation tools


Use the Facilitation Superpowers to run a happy and productive session.

[Open article](#) →

1


Define your problem statement

What problem are you trying to solve? Frame your problem as a How Might We statement. This will be the focus of your brainstorm.

 5 minutes







PROBLEM


Smart Waste Management System For Metropolitan Cities



Key rules of brainstorming

To run a smooth and productive session

-  Stay in topic.
-  Encourage wild ideas.
-  Defer judgment.
-  Listen to others.
-  Go for volume.
-  If possible, be visual.



Need some inspiration?

See a finished version of this template to kickstart your work.

[Open example](#) →

2

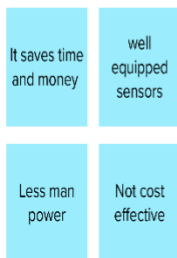
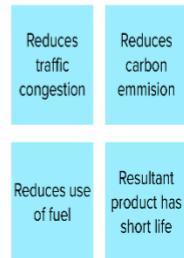
Brainstorm

Write down any ideas that come to mind that address your problem statement.

🕒 10 minutes

TIP

You can select a sticky note and, with the pencil icon, switch to sketch. Icon to start drawing!

Santhoshshivan K**ShanmugaKamalesh M****Raghul R****Mystica C**

3

Group ideas

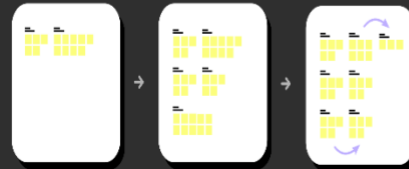
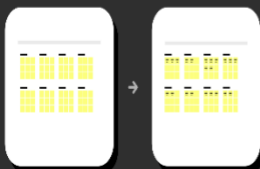
Take turns sharing your ideas while clustering similar or related notes as you go. In the last 10 minutes, give each cluster a sentence-like label. If a cluster is bigger than six sticky notes, try and see if you and break it up into smaller sub-groups.

🕒 20 minutes

Making the task simple

Collection and utilization of data

Reduce wastage of energy

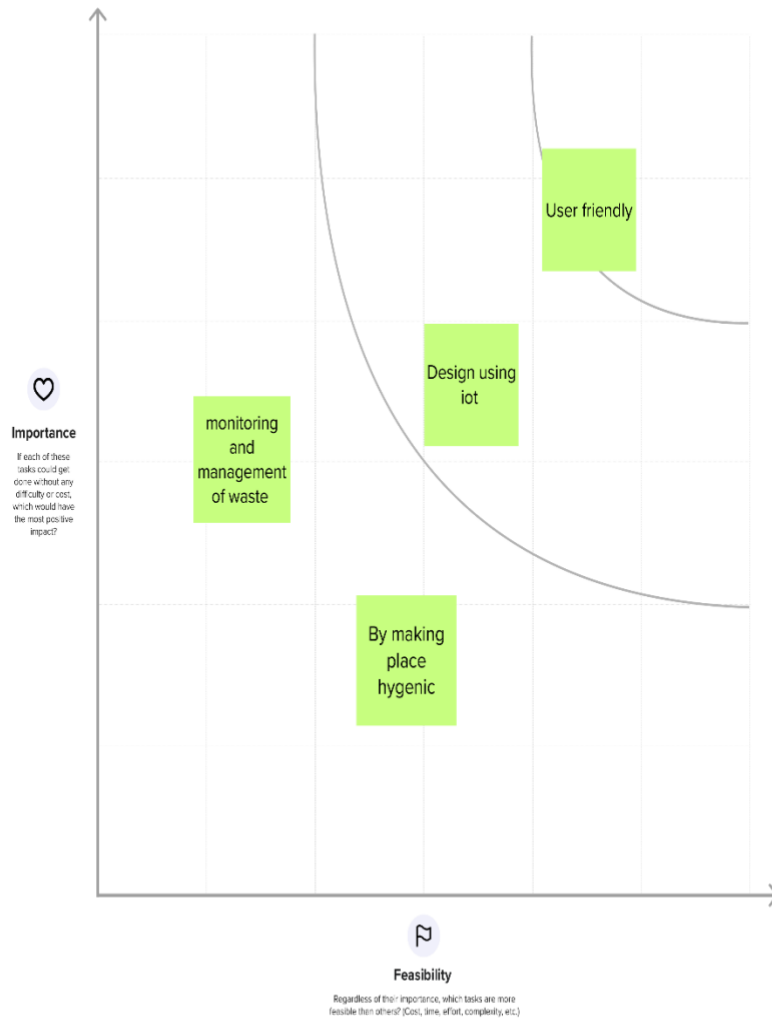


4

Prioritize

Your team should all be on the same page about what's important moving forward. Place your ideas on this grid to determine which ideas are important and which are feasible.

20 minutes



→

After you collaborate

You can export the mural as an image or pdf to share with members of your company who might find it helpful.

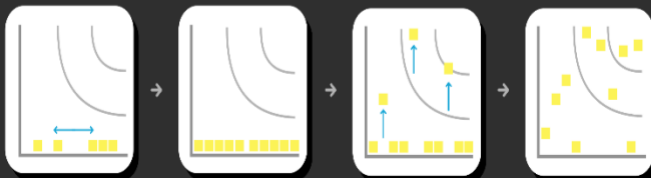
Quick add-ons

- A Share the mural**
Share a view link to the mural with stakeholders to keep them in the loop about the outcomes of the session.
- B Export the mural**
Export a copy of the mural as a PNG or PDF to attach to emails, include in slides, or save in your drive.

Keep moving forward

- Strategy blueprint**
Define the components of a new idea or strategy.
[Open the template →](#)
- Customer experience journey map**
Understand customer needs, motivations, and obstacles for an experience.
[Open the template →](#)
- Strengths, weaknesses, opportunities & threats**
Identify strengths, weaknesses, opportunities, and threats (SWOT) to develop a plan.
[Open the template →](#)

[Share template feedback](#)



3.3 Proposed Solution:

S.No.	Parameter	Description
1.	Problem Statement (Problem to be solved)	How can the trash bins in metropolitan cities can be easily notified and cleaned in an efficient manner?
2.	Idea / Solution description	The fill level and weight of garbage in Smart bins are observed using a web page and the information is collected using sensors. If the garbage in the smart bin gets filled then the sensors in the smart bins sends an information alert to GPS location of those smart bins to the respective person.
3.	Novelty / Uniqueness	<ul style="list-style-type: none"> ❖ Smart waste bins classifies recyclables into separate compartments. ❖ This can lower waste management costs as much 80% and drastically improve employee efficiency.
4.	Social Impact / Customer Satisfaction	<ul style="list-style-type: none"> ✓ It reduces CO₂ emission since the usage of fuel is reduced. ✓ Prevents contamination due to overflowing of garbage. ✓ Maintain clean environment.

<p>2. JOBS-TO-BE-DONE / PROBLEMS J&P</p> <p>Which jobs-to-be-done (or problems) do you address for your customers? There could be more than one; explore different sides.</p> <ul style="list-style-type: none"> ➤ To reduce the contamination of disease. ➤ To control the overflow of garbage. 	<p>9. PROBLEM ROOT CAUSE RC</p> <p>What is the real reason that this problem exists? What is the back story behind the need to do this job? I.e. customers have to do it because of the change in regulations.</p> <ul style="list-style-type: none"> ➤ Due to over flow of waste in garbage bins and lack of proper waste collection makes the environment unclean. This may cause various diseases. 	<p>7. BEHAVIOUR BE</p> <p>What does your customer do to address the problem and get the job done? i.e. directly related: find the right solar panel installer, calculate usage and benefits; indirectly associated: customers spend free time on volunteering work (i.e. Greenpeace)</p> <ul style="list-style-type: none"> ➤ In order to control the overflow of garbage a sensor is to be inserted and thus makes the environment clean.
--	--	---

<p>3. TRIGGERS TR</p> <p>! ? i.e. seeing their neighbour installing solar panels, reading about a more efficient solution in the news.</p> <ul style="list-style-type: none"> ➤ By seeing the neighboring countries, it makes us to do this things. 	<p>10. YOUR SOLUTION SL</p> <p>If you are working on an existing business, write down your current solution first, fill in the canvas, and check how much it fits really. If you are working on a new business proposition, then keep it blank until you fill in the canvas and come up with a solution that fits within customer limitations, solves a problem and matches customer behaviour.</p> <ul style="list-style-type: none"> ➤ In the present scenario, we see the garbage spills out resulting in pollution. ➤ Here we use IOT based application in which the garbage management is automated. ➤ Sensors are used to give alert messages and then web portal shows the location of garbage for easier access. 	<p>8. CHANNELS of BEHAVIOUR CH</p> <p>8.1 ONLINE What kind of actions do customers take online? Extract online channels from #7</p> <ul style="list-style-type: none"> ➤ By collecting the data we can easily identify the garbage location i.e., where the garbage has to be collected.
<p>4. EMOTIONS: BEFORE / AFTER EM</p> <p>How do customers feel when they face a problem or a job and afterwards? I.e. lost, insecure > confident, in control - use it in your communication strategy & design.</p> <ul style="list-style-type: none"> ➤ Before solving the problem people feels more difficulties such as unclean environment, bad odor due to waste. ➤ After solving the problem they feel very comfortable than the previous system of the waste management. 		<p>8.2 OFFLINE What kind of actions do customers take offline? Extract offline channels from #7 and use them for customer development.</p> <ul style="list-style-type: none"> ➤ The separated garbage are collected. Then it is recycled into some other useful byproducts.

Reference: [ClickHere](#).

4 REQUIREMENT ANALYSIS

4.1 Functional Requirements:

Following are the functional requirements of the proposed solution.

FR No.	Functional Requirement (Epic)	Sub Requirement (Story / Sub-Task)
FR-1	User Registration	The municipality have to register by creating id and password through webpage by using G-mail.
FR-2	User Confirmation	User can login through their ID and Password and the status can be monitored.
FR-3	Smart Waste bins	If waste in the bins reaches 80%, then sensors in the bin gives an alert to the user and the user can monitor periodically so that we can collect some data.
FR-4	GPS	GPS is used to trace the actual location of the filled smart bin and helps to collect the filled smart bins from the particular location.
FR-5	Cloud	The data which are collected is stored under the IBM cloud.

4.2 Non-functional Requirements:

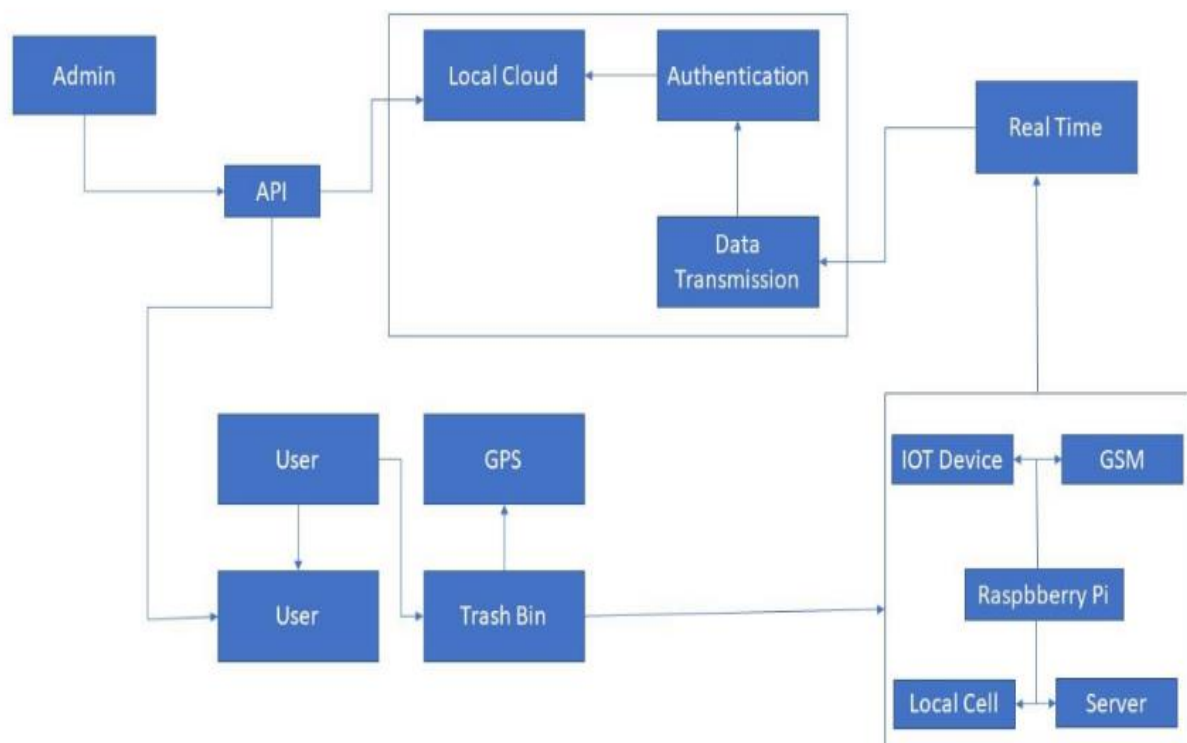
Following are the non-functional requirements of the proposed solution.

FR No.	Non-Functional Requirement	Description
NFR-1	Usability	The portal can be easily accessible and monitored. This is an user-friendly process.
NFR-2	Security	Data are more secured and only the user can login to the webpage. No other person can access the data except the user.
NFR-3	Reliability	Smart waste management provides better working conditions for drivers and waste collectors. They spend their time more efficiently by this technique.
NFR-4	Performance	User are provided with decision-making and optimization of waste collection routes and vehicle loads resulting in at least 30% of route reduction.
NFR-5	Availability	The system is user-friendly. Failure percentage is much less and 24*7 support is available.
NFR-6	Scalability	Finally the filled smart bins can be easily managed from small towns to large metropolitan cities.

5 PROJECT DESIGN

5.1 Data Flow Diagrams:

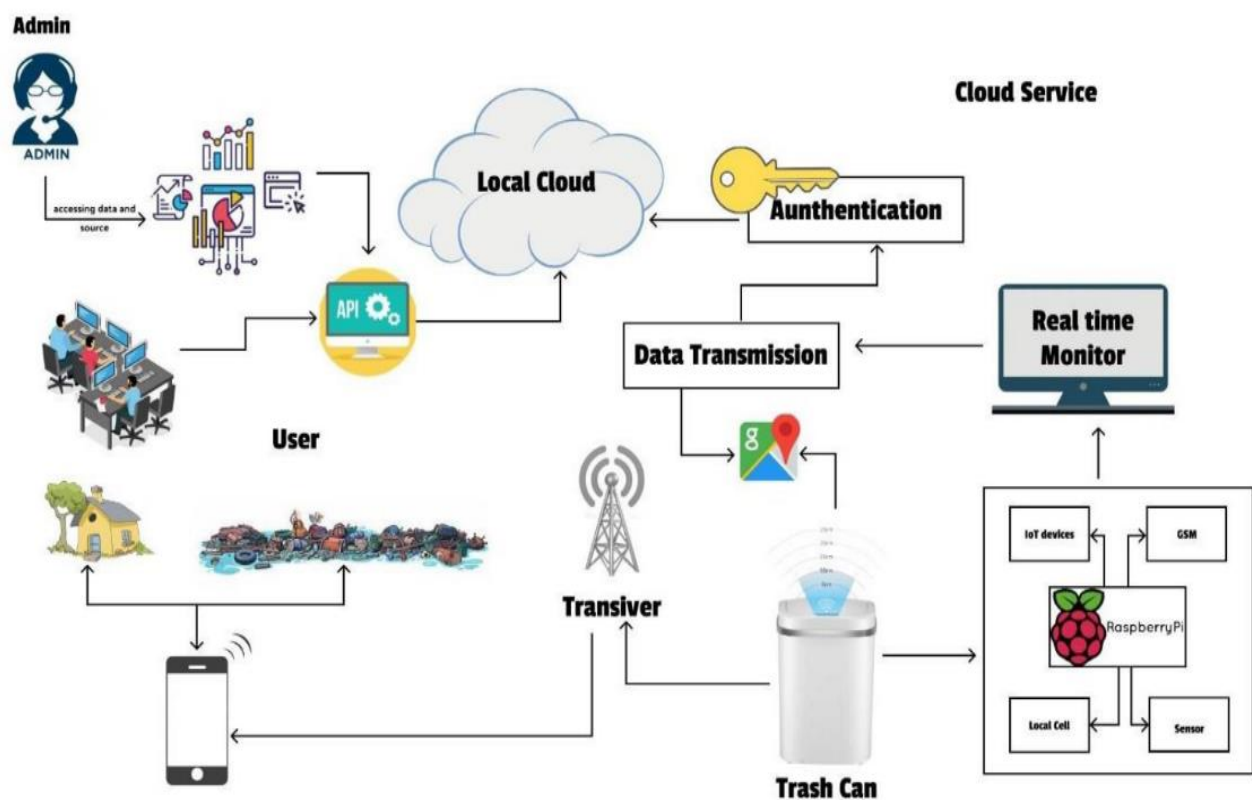
A Data Flow Diagram (DFD) is a traditional visual representation of the information flows within a system. A neat and clear DFD can depict the right amount of the system requirement graphically. It shows how data enters and leaves the system, what changes the information, and where data is stored.



5.2 SOLUTION AND TECHNICAL ARCHITECTURE

1. Summary:

The smart bins are constructed based on the sensor application and raspberry pi . It can also act as a transceiver since it is connected to the mobile phone of the user . The overall process of the sensors and raspberry pi is monitored using real time monitor which can help data transmission. This is stored and formulated using cloud data . Through which the admin can access the data and then track the location from GPS .



2. Components & Technologies:

S.No	Component	Description	Technology
1.	Raspberry pi controller	The Arduino Uno is an open-source microcontroller board based on the Microchip ATmega 328P microcontroller.	Arduino programming itself is done in python.
2.	Application Logic-1	Logic for Ultrasonic sensor data	Python
3.	GPRS	To track the location of the bin	Python
4.	IoT	To collect the data and alert the users	IBM Watson IoT Platform, Node Red.
5.	Cloud Database	Stores the collected data in cloud	Cloudant DB

3. Application Characteristics:

S.No	Characteristics	Description	Technology
1.	Open Source Microcontroller	Arduino UNO is used to make the IoT device.	Python
2.	Security	Encryption/Decryption used for security purpose.	Surface Mount Sensor
3.	Scalable Architecture	New features can be added	Node Red
4.	Availability	Web application can be accessed from anywhere	IBM Watson IoT Platform, NodeRed
5.	Performance	All truck drivers can access the application at sametime.	Cloudant DB, IBM Watson IoT Platform.

5.3 User Stories

Use the below template to list all the user stories for the product.

User Type	Functional Requirement (Epic)	User Story Number	User Story / Task	Acceptance criteria	Priority	Release
Admin (Web manage web server)	Login	USN-1	As a admin, I gave the user Id and Password for every worker and manage them.	I can manage web accountant/ dashboard	Medium	Sprint-1
Co-admin	Login	USN-2	As a Co-admin, I will manage the garbage level and monito the smart bins. If the garbage gets filled, the alert notification will be received and I'll post location and garbage id to the truck and will go and collect the trash	I can manage the smart bins and garbage level.	High	Sprint-2
Truck driver	Login	USN-3	As a truck driver, I'll follow the route send by Co-admin to reach the particular garbage through its id.	I can drive to reach the filled garbage in shortest route given	Medium	Sprint-3
Total Garbage	Login	USN-4	As a waste collector, I'll collect all the waste from the smart bins and load them into the truck and send them to landfill.	I can collect trash and load them into the truck and send off	Medium	Sprint-4
Municipality	Login	USN-5	As a municipality, I will check the process of waste collecting and sending them in a disciplined manner without any issues	I can manage all these process and supervise it	High	Sprint-5

6.**PROJECT PLANNING AND SCHEDULING****6.1 SPRINT PLANNING & SCHEDULING:**

TITLE	DESCRIPTION	DATE
Literature Survey & Information Gathering	Literature survey on the selected project is done by gathering information about related details on technical papers and web browsing.	28 SEPTEMBER 2022
Prepare Empathy Map	Prepared Empathy Map Canvas to capture the user Pains & Gains list of problem statements.	24 SEPTEMBER 2022
Ideation	List the organizing the brainstorming session and prioritize the top 3 ideas based on the feasibility and importance.	25 SEPTEMBER 2022
Proposed Solution	Prepared the proposed solution document, which includes the novelty, feasibility of idea, business model, social impact, scalability of solution, etc.	23 SEPTEMBER 2022
Problem Solution Fit	Prepared problem - solution fit document.	30 SEPTEMBER 2022
Solution Architecture	Prepare solution architecture document.	28 SEPTEMBER 2022

6.2 SPRINT DELIVERY SCHEDULE

Product Backlog, Sprint Schedule, and Estimation

Use the below template to create product backlog and sprint schedule.

Sprint	Functional Requirement (Epic)	User Story Number	User Story / Task	Story Points	Priority	Team Members
Sprint-1	Registration	USN-1	As a user, we must register for an IBM cloud account , IoT platform ,RED node service and cloudant DB.	2	High	Mystica,Raghul
Sprint-2		USN-2	As a user, we develop a python script to publish random sensor data.	2	High	Santhoshshivan,Shanmugakamalesh
Sprint-3		USN-3	As a user send the sensor data to IBM Watson IoT platform,install palette for nodes available in Node red.	2	Medium	Santhoshshivan,Shanmugakamalesh Mystica,Raghul
Sprint-4	Dashboard	USN-4	Configure the Node-RED flow to receive data from the IBM IoT platform and a web UI should be created in Node-RED	1	High	Santhoshshivan,Shanmugakamalesh Mystica,Raghul

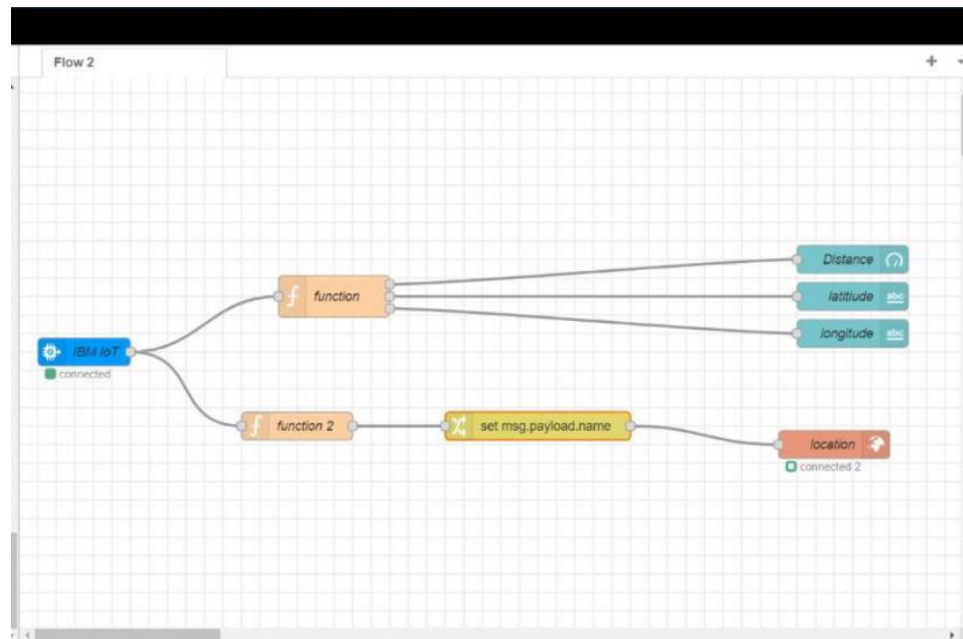
Project Tracker, Velocity & Burndown Charts

Sprint	Total Story Points	Duration	Sprint Start Date	Sprint End Date (Planned)	Story Points Completed(as on Planned End Date)	Sprint Release Date (Actual)
Sprint-1	20	6 Days	24 Oct 2022	29 Oct 2022	20	29 Oct 2022
Sprint-2	20	6 Days	31 Oct 2022	05 Nov 2022	30	30 Oct 2022
Sprint-3	20	6 Days	07 Nov 2022	12 Nov 2022	49	04 Nov 2022
Sprint-4	20	6 Days	14 Nov 2022	19 Nov 2022	50	09 Nov 2022

Velocity:

$$AV = \frac{\text{sprint duration}}{\text{velocity}} = \frac{20}{10} = 2$$

7.

CODING AND SOLUTIONING**NODE RED SERVICE ASSOCIATED WITH IBM CLOUD:**

Browse Action Device Types Interfaces Add Device

Browse Devices

All Devices Diagnose

This table shows a summary of all devices that have been added. It can be filtered, organized, and searched on using different criteria. To get started, you can add devices by using the Add Device button, or by using API.

Search by Device ID Device Simulator

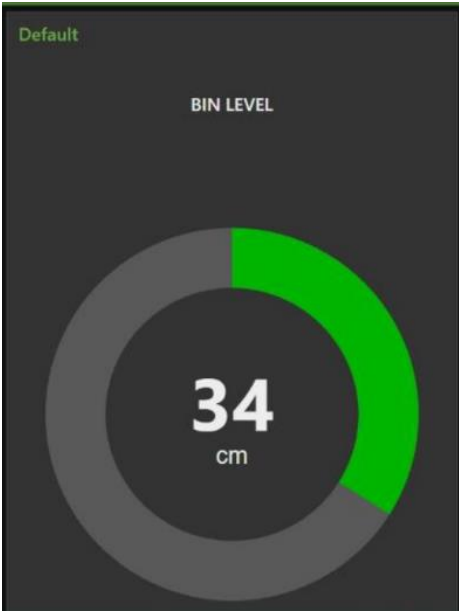
Device ID	Status	Device Type	Class ID	Date Added	Descriptive Location	Added By	Device Class
ssr_123	Connected	ssr	Device	Nov 14, 2022 12:09 PM		513419106034@smartinternz.com	

Items per page: 50 | 1-1 of 1 item

1 of 1 page

1 Simulation running

Node red Dashboard:



<input type="checkbox"/>	Device ID	Status	Device Type	Class ID	Date Added	Descriptive Location	Added By	Device Class
▼	■	ssr_123	Disconnected	ssr	Device	Nov 14, 2022 12:09 PM	513419106034@smartinfernz.com	→ ...
IdentifyDevice InformationRecent EventsStateLogs								
The recent events listed show the live stream of data that is coming and going from this device.								
Event	Value	Format	Last Received					
status	[{"Distance":40,"latitude":9.9261153,"longitude":...	json	a few seconds ago					
status	[{"Distance":35,"latitude":9.9261153,"longitude":...	json	a few seconds ago					
status	[{"Distance":37,"latitude":9.9261153,"longitude":...	json	a few seconds ago					
status	[{"Distance":61,"latitude":9.9261153,"longitude":...	json	a few seconds ago					
status	[{"Distance":59,"latitude":9.9261153,"longitude":...	json	a minute ago					

1 Simulation running

8.ADVANTAGES AND DISADVANTAGES

ADVANTAGES:

- ✓ Meet the increasing demand for sustainable solutions
- ✓ Transportation Management System and reduce the use of fuel
- ✓ Intelligent Route Optimization.
- ✓ Customer Service System.
- ✓ Customer Self-Service App.
- ✓ Clean and healthy environment
- ✓ Automated Workflows.

DISADVANTAGES:

- ✓ This results into high initial cost due to expensive smart dustbins compare to other methods.
- ✓ Sensor nodes used in the dustbins have limited memory size.
- ✓ Wireless technologies used in the system such as zigbee and wifi have shorter range and lower data speed.

9.

CONCLUSION

We presented an intelligent waste collection system. The system is based on IoT sensors. It is responsible for measuring the waste level in the smart bins. When the smart bins gets filled almost there will be information received by the admin, Since the admin can access the data and location of the bin. Later send this data (through Internet) to a server for storage and processing. This data helps to compute the optimized collection routes for the workers. In future, we would like to enhance the system for different kind of wastes, namely solid and liquid wastes.

10. FUTURE SCOPE

The advantage of this work is its contribution in making a Smart city. Among the many challenges that a city faces, waste management is of utmost importance. This is because, it is directly related to health of people living in the area. We are further extending this work to address problems of segregating different kind of wastes (e.g., solid, liquid etc.), and identifying different vehicles for collecting it. The optimization algorithms may be devised accordingly depending on the requirements. In future, we would like to enhance the system for different kind of wastes, namely solid and liquid wastes.

11.APPENDIX

11.1 SOURCE CODE:

PYTHON CODE TO PUBLISH DATA

```
#IBM Watson IOT Platform
#pip install wiotp-sdk from geopy.geocoders import Nominatim
import wiotp.sdk.device
import time
import random
myConfig = {
    "identity": {
        "orgId": "n7xtmx",
        "typeId": "ssr",
        "deviceId": "ssr_123"
    },
    "auth": {
        "token": "12345678"
    }
}
def myCommandCallback(cmd):
    print("Message received from IBM IoT Platform: %s" % cmd.data['command'])
    m=cmd.data['command']
    client = wiotp.sdk.device.DeviceClient(config=myConfig, logHandlers=None)
    client.connect()
    while True:
        dist1=random.randint(0,100)
        loc = Nominatim(user_agent="GetLoc")
        getLoc1 = loc.geocode("madurai")
```

```
lat=getLoc1.latitude
log=getLoc1.longitude
f="alert"
if dist1>=80:
    a=print("The bin1 level is high")
    type(a)
    myData={'name':f,'Distance':dist1,'latitude':lat,'longitude':log}
else:
    a=print("The bin1 level is low")
    type(a)
    myData={'Distance':dist1,'latitude':lat,'longitude':log}
client.publishEvent(eventId="status", msgFormat="json", data=myData, qos=0,
onPublish=None) print("Published data Successfully: %s", myData)
client.commandCallback = myCommandCallback
time.sleep(10)
client.disconnect()
```

```

Python 3.7.9 Shell
File Edit Shell Debug Options Window Help
RESTART: C:\Users\USER\Documents\ibm\ibm iot.py =====
2022-11-18 15:49:23,939 wiotp.sdk.device.client.DeviceClient INFO Connected successfully: d:n7atmx:ssr:ssr_123
The binl level is high
Published data Successfully: %s {'name': 'alert', 'Distance': 95, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is high
Published data Successfully: %s {'name': 'alert', 'Distance': 83, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is low
Published data Successfully: %s {'Distance': 71, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is low
Published data Successfully: %s {'Distance': 75, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is high
Published data Successfully: %s {'name': 'alert', 'Distance': 85, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is high
Published data Successfully: %s {'name': 'alert', 'Distance': 99, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is low
Published data Successfully: %s {'Distance': 60, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is high
Published data Successfully: %s {'name': 'alert', 'Distance': 97, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is low
Published data Successfully: %s {'Distance': 31, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is low
Published data Successfully: %s {'Distance': 6, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is low
Published data Successfully: %s {'Distance': 53, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is high
Published data Successfully: %s {'name': 'alert', 'Distance': 83, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is low
Published data Successfully: %s {'Distance': 37, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is low
Published data Successfully: %s {'Distance': 78, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is low
Published data Successfully: %s {'Distance': 45, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is low
Published data Successfully: %s {'Distance': 50, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is low
Published data Successfully: %s {'Distance': 11, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is low
Published data Successfully: %s {'Distance': 27, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is low
Published data Successfully: %s {'Distance': 3, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is high
Published data Successfully: %s {'name': 'alert', 'Distance': 95, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is low
Published data Successfully: %s {'Distance': 6, 'latitude': 9.9261153, 'longitude': 78.1140983}
The binl level is high
Published data Successfully: %s {'name': 'alert', 'Distance': 86, 'latitude': 9.9261153, 'longitude': 78.1140983}

```

Device ID

Status

Device Type

Class ID

Date Added

Descriptive Location

Added By

Device Class

ssr_123

Disconnected

ssr

Device

Nov 14, 2022 12:09 PM

513419106034@smartinternz.com

→

...

Identity

Device Information

Recent Events

State

Logs

The recent events listed show the live stream of data that is coming and going from this device.

Event

Value

Format

Last Received

status

{\"Distance\":40,\"latitude\":9.9261153,\"longitude\":...}

json

a few seconds ago

status

{\"Distance\":35,\"latitude\":9.9261153,\"longitude\":...}

json

a few seconds ago

status

{\"Distance\":37,\"latitude\":9.9261153,\"longitude\":...}

json

a few seconds ago

status

{\"Distance\":61,\"latitude\":9.9261153,\"longitude\":...}

json

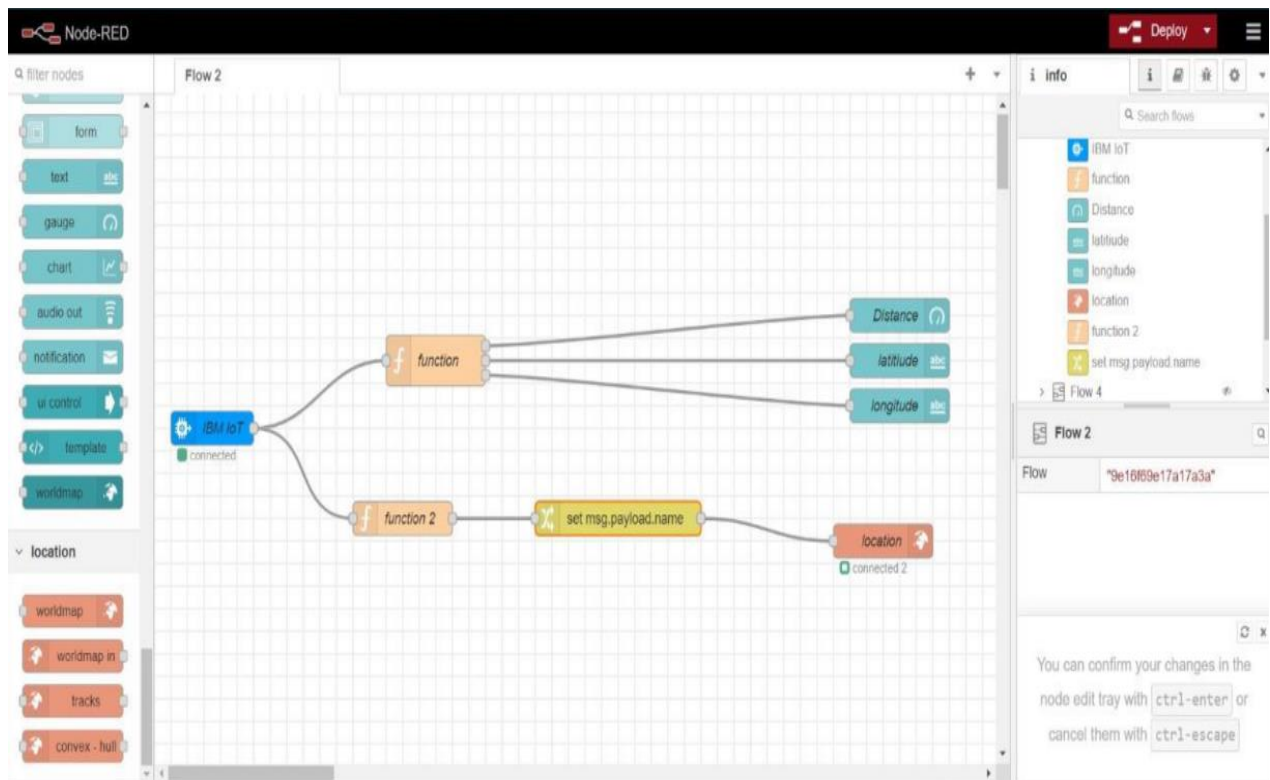
a few seconds ago

status

{\"Distance\":59,\"latitude\":9.9261153,\"longitude\":...}

json

a minute ago



JSON CODE:

```
[
  {
    "id": "9e16f69e17a17a3a",
    "type": "tab",
    "label": "Flow 2",
    "disabled": false,
    "info": "",
    "env": []
  },
  {
    "id": "3a1b64499b64086e",
    "type": "ibmiot in",
    "z": "9e16f69e17a17a3a",
    "authentication": "apiKey",
    "apiKey": "d3d241d760be32e9",
    "inputType": "evt",
    "logicalInterface": "",
    "ruleId": "",
    "deviceId": "",
    "applicationId": "",
    "deviceType": "+",
    "eventType": "+",
    "commandType": "",
    "format": "json",
    "name": "IBM IoT",
    "service": "registered",
    "allDevices": "",
    "allApplications": "",
    "allDeviceTypes": true,
    "allLogicalInterfaces": "",
    "allEvents": true,

```



```

    "allCommands": "",
    "allFormats": "",
    "qos": 0,
    "x": 70,
    "y": 300,
    "wires": [
      [
        "864c73fbd8df5b8b",
        "b77a9b3e8f3fb252"
      ]
    ]
  },
  {
    "id": "864c73fbd8df5b8b",
    "type": "function",
    "z": "9e16f69e17a17a3a",
    "name": "function ",
    "func": "var msg1={};\nvar msg2={};\nvar msg3={};\nmsg1.payload = msg.payload.Distance;\nmsg2.payload = msg.payload.latitude;\nmsg3.payload = msg.payload.longitude;\nreturn [msg1, msg2,\nmsg3];\n",
    "outputs": 3,
    "noerr": 0,
    "initialize": "",
    "finalize": "",
    "libs": [],
    "x": 340,
    "y": 240,
    "wires": [
      [
        "53694b0547a04328"
      ],
      [
        "d39c51e2d12e96f0"
      ],
      [
        "de6ce8c8f71af009"
      ]
    ]
  },
  {
    "id": "53694b0547a04328",
    "type": "ui_gauge",
    "z": "9e16f69e17a17a3a",
    "name": "Distance",
    "group": "e1f7ae7916f8d6e2",
    "order": 1,
    "width": "6",
    "height": "9",
    "gtype": "donut",
    "title": "BIN LEVEL",
    "label": "cm",
    "format": "{{value}}",
    "min": 0,
    "max": "100",
    "colors": [

```

```

    "#00b500",
    "#e6e600",
    "#ca3838"
  ],
  "seg1": "50",
  "seg2": "80",
  "x": 900,
  "y": 200,
  "wires": []
},
{
  "id": "d39c51e2d12e96f0",
  "type": "ui_text",
  "z": "9e16f69e17a17a3a",
  "group": "f9ef24bc62beb59f",
  "order": 2,
  "width": "6",
  "height": "3",
  "name": "latitude",
  "label": "latitude",
  "format": "{{msg.payload}}",
  "layout": "row-spread",
  "x": 900,
  "y": 240,
  "wires": []
},
{
  "id": "de6ce8c8f71af009",
  "type": "ui_text",
  "z": "9e16f69e17a17a3a",
  "group": "f9ef24bc62beb59f",
  "order": 1,
  "width": "6",
  "height": "3",
  "name": "longitude",
  "label": "longitiude",
  "format": "{{msg.payload}}",
  "layout": "row-spread",
  "x": 900,
  "y": 280,
  "wires": []
},
{
  "id": "46d8538fcca24a22",
  "type": "worldmap",
  "z": "9e16f69e17a17a3a",
  "name": "location",
  "lat": "",
  "lon": "",
  "zoom": "",
  "layer": "OSMC",
  "cluster": "",
  "maxage": "",
  "usermenu": "show",
  "layers": "show",

```

```

"panit": "false",
"panlock": "false",
"zoomlock": "false",
"hiderrightclick": "false",
"coords": "none",
"showgrid": "false",
"showruler": "false",
"allowFileDrop": "true",
"path": "/map",
"overlist": "DR,CO,RA,DN,HM",
"maplist": "OSMG,OSMC,EsriC,EsriS,EsriT,EsriDG,UKOS",
"mapname": "GOOGLE MAPS",
"mapurl": "https://www.google.com/maps",
"mapopt": "",
"mapwms": true,
"x": 880,
"y": 400,
"wires": []
},
{
  "id": "b77a9b3e8f3fb252",
  "type": "function",
  "z": "9e16f69e17a17a3a",
  "name": "function 2",
  "func": "msg.payload = { latitude: msg.payload.latitude,\n  longitude: msg.payload.longitude}\nreturn
msg;",
  "outputs": 1,
  "noerr": 0,
  "initialize": "",
  "finalize": "",
  "libs": [],
  "x": 300,
  "y": 380,
  "wires": [
    [
      "65823a0aa9c0e974"
    ]
  ]
},
{
  "id": "65823a0aa9c0e974",
  "type": "change",
  "z": "9e16f69e17a17a3a",
  "name": "",
  "rules": [
    {
      "t": "set",
      "p": "payload.name",
      "pt": "msg",
      "to": "worldmap",
      "tot": "str"
    }
  ],
  "action": "",
  "property": "",

```

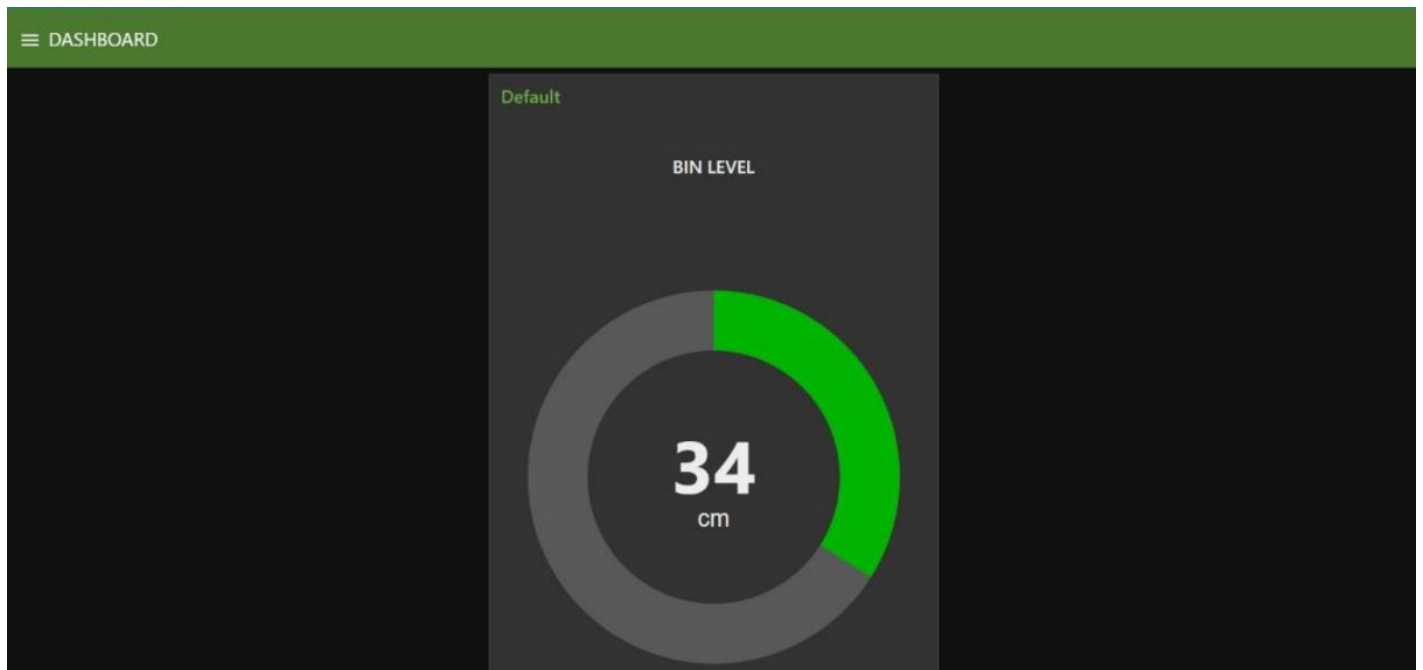
```

"from": "",
"to": "",
"reg": false,
"x": 560,
"y": 380,
"wires": [
  [
    "46d8538fcca24a22"
  ]
]
},
{
  "id": "d3d241d760be32e9",
  "type": "ibmiot",
  "name": "IOT",
  "keepalive": "60",
  "serverName": "",
  "cleansession": true,
  "appId": "",
  "shared": false
},
{
  "id": "e1f7ae7916f8d6e2",
  "type": "ui_group",
  "name": "Default",
  "tab": "004f558216ec7811",
  "order": 1,
  "disp": true,
  "width": "6",
  "collapse": false
},
{
  "id": "f9ef24bc62beb59f",
  "type": "ui_group",
  "name": "bin1",
  "tab": "e8096443afed3ad3",
  "order": 1,
  "disp": true,
  "width": "6",
  "collapse": false
},
{
  "id": "004f558216ec7811",
  "type": "ui_tab",
  "name": "DASHBOARD",
  "icon": "dashboard",
  "disabled": false,
  "hidden": false
},
{
  "id": "e8096443afed3ad3",
  "type": "ui_tab",
  "name": "LOCATION",
  "icon": "dashboard",
  "order": 2,

```

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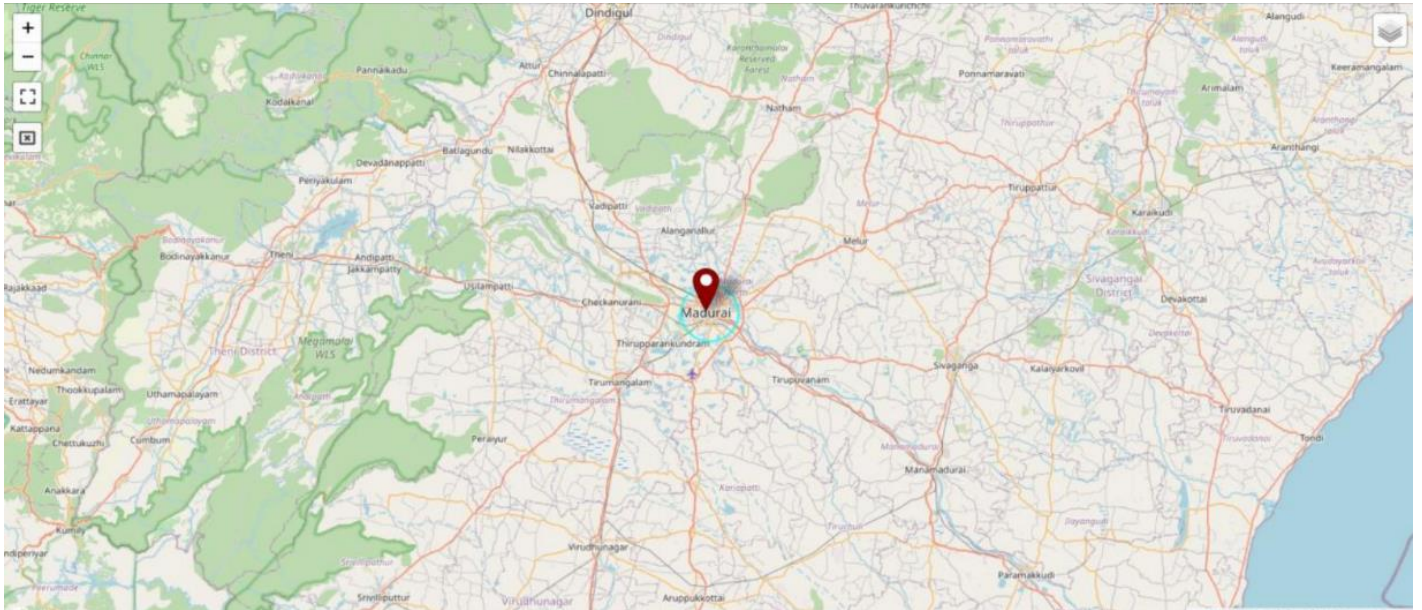
```
"disabled": false,  
"hidden": false  
}  
]
```



LOCATION

bin1	
longitude	78.1140983
latitude	9.9261153

Location(detection):



11.2 GIT-HUB LINK: [GitHub-Repo](#)

PROJECT DEMO LINK:

1. https://node-red-qltdp-2022-11-07.eu-gb.mybluemix.net/ui/#!/0?socketid=WzX3XVVK_oZjhjBAAAAI
2. <https://possible-wheat-booth.glitch.me/>

