# ASSIGNMENT 4 WOKWI SIMULATION

Assignment Date	12th November 2022	
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Maximum Marks	2 Marks	

# **QUESTION:**

Write a code and make a connection in WOKWI for ultrasonic sensor. Whenever distance is less than 100, send "alert" to IBM cloud and display in device recent events.

# **PROGRAM:**

```
#include <WiFi.h> #include
<PubSubClient.h>WiFiClient
wifiClient; String data3;
#define ORG "d5oxwa"
#define DEVICE_TYPE "ibm-device"
#define DEVICE ID "ibmid"
#define TOKEN "vtn5w?t3s?vX-vn8Z8"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";char
publishTopic[] = "iot-2/evt/data/fmt/json";
char topic[] = "iot-2/cmd/led/fmt/String";char
authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);const int
trigpin=5;
const int echopin=18;String
command:
```

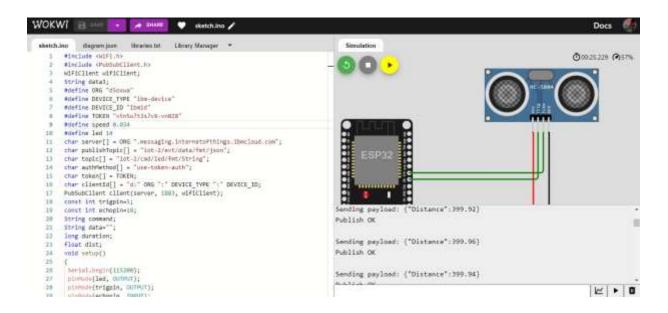
```
String data="";long
duration; float
dist; void setup()
 Serial.begin(115200);
 pinMode(led, OUTPUT);
 pinMode(trigpin, OUTPUT);
 pinMode(echopin, INPUT);
 wifiConnect();
 mqttConnect();
}
void loop() {
 bool isNearby = dist < 100;
 digitalWrite(led, isNearby);
 publishData();
 delay(500);
 if (!client.loop()) {
 mqttConnect();
 }
void wifiConnect() {
 Serial print("Connecting to "); Serial print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
 while (WiFi.status() != WL_CONNECTED) {
 delay(500);
 Serial.print(".");
 Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
void mqttConnect() {
 if (!client.connected()) {
 Serial.print("Reconnecting MQTT client to "); Serial.println(server);
```

```
while (!client.connect(clientId, authMethod, token)) {
 Serial.print(".");
 delay(500);
 initManagedDevice();
 Serial.println();
 }
void initManagedDevice() {
 if (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic));
 Serial.println("IBM subscribe to cmd OK");
 } else {
 Serial.println("subscribe to cmd FAILED");
 }
}
void publishData()
 digitalWrite(trigpin,LOW);
 digitalWrite(trigpin,HIGH);
 delayMicroseconds(10);
 digitalWrite(trigpin,LOW);
 duration=pulseIn(echopin,HIGH);
 dist=duration*speed/2; if(dist<100){
 String payload = "{\"Alert Distance\":";payload +=
 dist;
 payload += "}";
 Serial print("\n"); Serial print("Sending
 payload: ");Serial.println(payload);
 if (client.publish(publishTopic, (char*) payload.c_str())) {
 Serial.println("Publish OK");
```

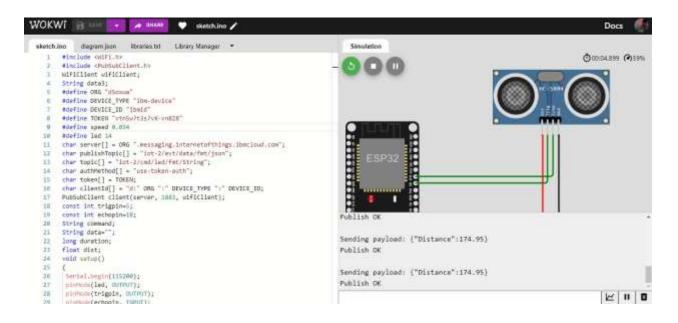
```
if(dist>100){
String payload = "{\"Distance\":";payload +=
dist;
payload += "}";
Serial.print("\n"); Serial.print("Sending
payload: ");Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish OK");
}else {
Serial.println("Publish FAILED");
}
```

## **OUTPUT:**

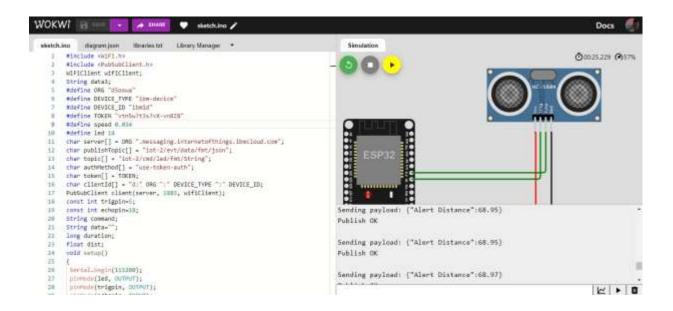
### **WOKWI SIMULATION:**



### When distance>100



#### When distance<100



# **IBM CLOUD OUTPUT:**

#### Recent Events

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format.	Last fleceived
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	įson	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	jeon	a few seconds ago
Data	("Normal Distance":92.99)	json	a few seconds ago