# **ASSIGNMENT 4**

Assignment Date	15 November 2022
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Team Id	PNT2022TMID04753
Maximum Marks	2 Marks

#### Ultrasonic sensor simulation in Wokwi

#### **Question:**

Write a code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100cms send an "Alert" to IBM cloud and display in the device recent events.

#### Code:

```
#include <WiFi.h>
#include <PubSubClient.h> void callback(char* subscribetopic,
byte* payload, unsigned int payloadLength);
//-----credentials of IBM Accounts-----
#define ORG "kotoq5"//IBM ORGANITION ID
#define DEVICE_TYPE "ESP32"//Device type mentioned in ibm watson IOT Platform
#define DEVICE_ID "12345"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "12345678" //Token
String data3;
```

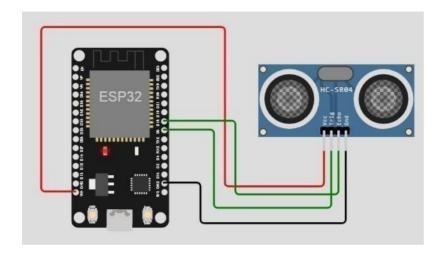
```
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
   char publishTopic[] = "iot-2/evt/Data/fmt/json"; char
   subscribetopic[] = "iot-2/cmd/test/fmt/String"; char
   authMethod[] = "use-token-auth";
char token[] = TOKEN;
   char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
   WiFiClient wifiClient;
   PubSubClient client(server, 1883, callback ,wifiClient);
   const int trigPin = 5; const int echoPin = 18; #define
   SOUND SPEED 0.034 long duration; float distance; void
   setup() { Serial.begin(115200); pinMode(trigPin,
   OUTPUT); pinMode(echoPin, INPUT); wificonnect();
   mqttconnect(); } void loop() { digitalWrite(trigPin,
   LOW); delayMicroseconds(2); digitalWrite(trigPin,
   HIGH); delayMicroseconds(10); digitalWrite(trigPin,
   LOW); duration = pulseIn(echoPin, HIGH); distance =
   duration *
   SOUND SPEED/2;
   Serial.print("Distance (cm): ");
   Serial.println(distance);
   if(distance<100)</pre>
   Serial.println("ALERT!!")
   ; delay(1000);
   PublishData(distance);
   delay(1000); if
   (!client.loop())
   { mqttconnect();
   } } delay(1000); } void
   PublishData(float dist)
   { mattconnect();
   String payload = "{\"Distance\":"; payload += dist; payload
   += ",\"ALERT!!\":""\"Distance less than 100cms\""; payload
   += "}";
   Serial.print("Sending payload: ");
   Serial.println(payload);
```

```
if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");
    } else {
    Serial.println("Publish failed");
         } } void
    mattconnect() { if
    (!client.connected()) {
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while (!!!client.connect(clientId, authMethod, token)) {
    Serial.print(".")
    ; delay(500);
    }
initManagedDevice();
Serial.println();
} }
void wificonnect()
Serial.println(); Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "", 6); while (WiFi.status()
!= WL CONNECTED) { delay(500);
Serial.print(".");
}
Serial.println(""); Serial.println("WiFi
connected"); Serial.println("IP address:
"); Serial.println(WiFi.localIP());
} void initManagedDevice() { if
(client.subscribe(subscribetopic)) {
Serial.println((subscribetopic)); Serial.println("subscribe to cmd
OK");
} else {
Serial.println("subscribe to cmd FAILED");
} } void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength)
Serial.print("callback invoked for topic: ");
```

```
Serial.println(subscribetopic); for (int i =
0; i < payloadLength; i++) {
//Serial.print((char)payload[i]); data3 +=
(char)payload[i];
    }
    Serial.println("data: "+ data3); data3="";
    } } void mattconnect() {
    if (!client.connected()) {
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while (!!!client.connect(clientId, authMethod, token)) {
    Serial.print(".")
    ; delay(500);
    }
initManagedDevice();
Serial.println();
} }
void wificonnect()
Serial.println(); Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "", 6); while (WiFi.status()
!= WL CONNECTED) { delay(500);
Serial.print(".");
}
Serial.println(""); Serial.println("WiFi
connected"); Serial.println("IP address:
"); Serial.println(WiFi.localIP());
} void initManagedDevice() { if
(client.subscribe(subscribetopic)) {
Serial.println((subscribetopic)); Serial.println("subscribe to cmd
OK");
} else {
Serial.println("subscribe to cmd FAILED");
} } void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength)
Serial.print("callback invoked for topic: ");
```

```
Serial.println(subscribetopic); for (int i =
0; i < payloadLength; i++) {
//Serial.print((char)payload[i]); data3 +=
(char)payload[i];
   }
   Serial.println("data: "+ data3); data3="";
    }
 Diagram.json:
      "version": 1,
      "author":
      "sweetysharon",
      "editor": "wokwi",
      "parts":
       { "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": -4.67, "left": -114.67, "attrs": {} },
        { "type": "wokwi-hc-sr04", "id": "ultrasonic1", "top": 15.96, "left": 89.17, "attrs": {} }
      "connections": [
        [ "esp:TX0", "$serialMonitor:RX", "", [] ],
        [ "esp:RX0", "$serialMonitor:TX", "", []
        ],[
          "esp:VIN",
          "ultrasonic1:VCC",
          "red",
          [ "h-37.16", "v-178.79", "h200", "v173.33", "h100.67" ]
        [ "esp:GND.1", "ultrasonic1:GND", "black", [ "h39.87", "v44.04", "h170" ] ],
        [ "esp:D5", "ultrasonic1:TRIG", "green", [ "h54.54", "v85.07", "h130.67" ] ],
        [ "esp:D18", "ultrasonic1:ECHO", "green", [ "h77.87", "v80.01", "h110" ] ]
    }
```

# **Circuit Diagram:**



#### **Output:**

# Wokwi output:

```
Connecting to ....
WiFi connected
IP address:
10.10.0.2
Reconnecting client to ytluse.messaging.internetofthings.ibmcloud.com
iot-2/cmd/test/fmt/String
subscribe to cmd OK

Distance (cm): 399.92
Distance (cm): 399.94
Distance (cm): 399.98
Distance (cm): 399.98
Distance (cm): 399.94
Distance (cm): 399.94
Distance (cm): 399.94
Distance (cm): 399.94
```

# IBM cloud output:

