

Assignment 4

WOKWI PROGRAM

Assignment Date	23 OCT 2022
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Maximum Marks	2 Matts

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Smart Waste Management System for Metropolitan Cities
ASSIGNMENT 4:

Write code and connections in wokwi for ultrasonic sensors.
Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.
Upload document with wokwi share link and images of ibm cloud

```
EBBE
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "4yi0vc"
#define DEVICE_TYPE "nodeMcu"
#define DEVICE_ID "Assignment4"
#define TOKEN "123456789"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin= 5;
const int echopin= 18;
String command;
String data="";
long duration;
float dist;
void setup()

    Serial. begin(115200);
    pinMode(led, OUTPUT);
    pinMode(trigpin, OUTPUT);
    pinMode(echopin, INPUT);
    wifiConnect();
    mqttConnect();

void loop()
    bool isNearby = dist < 100;
    digitalWrite(led, isNearby);

    publishData();
    delay(500);

    if (!client.loop())
        mqttConnect();

void wifiConnect()
    Serial. print("Connecting to "); Serial. print("Wifi");
    WiFi. begin("Wokwi-GUEST", "", s);
    while (WiFi. status() != WL_CONNECTED) {
        delay(500);
        Serial. print(".");
```

```
Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
```

```
void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);

      initManagedDevice();
      Serial.println();
    }
  }
}
```

```
void initManagedDevice() {
  if (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic));
    Serial.println("IBM subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}
```

```
void publishData()
```

```
digitalWrite(trigpin,LOW);
digitalWrite(trigpin,HIGH);
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2;
if(dist< 100){
  String payload = "("Normal Distance\":";
  payload += dist;
  payload += "}";
}
```

```
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
  Serial.println("Publish OK");
}
```

```
if(dist> 101 && dist< 111){
  String payload = "("Ale1 distance\":";
  payload += dist;
  payload += "}";
}
```

```
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str())) {
  Serial.println("Warning crosses 110cm -- it automaticaly of the loop");
  digitalWrite(led,HIGH);
}else {
  Serial.println("Publish FAILED");
}
```

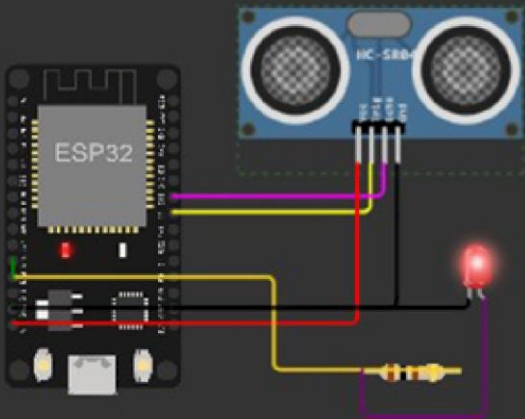
```
void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength){
  Serial.print("callback invoked for topic:");
  Serial.println(subscribeTopic);
  for(int i=0; i<payloadLength; i++){
    dist += (char)payload[i];
  }
}
```

```
Serial.println("data:"-I- data 3);
if(data 3=="lighton"){
  Serial.println(data 3);
  digitalWrite(led,HIGH);
}
```

```
data 3="";
```

Output

Editing Ultrasonic Distance Sensor
Distance: 90cm



Sending payload: {"Normal Distance":89.95}
Publish OK

Sending payload: {"Normal Distance":89.95}
Publish OK

Sending payload: {"Normal Distance":89.95}
Publish OK

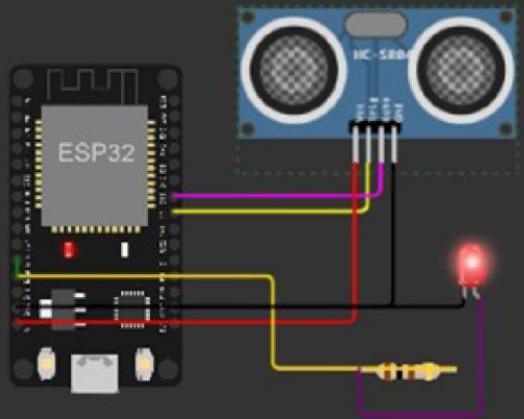
Sending payload: {"Normal Distance":89.98}
Publish OK

Sending payload: {"Normal Distance":89.95}
Publish OK

Sending payload: {"Normal Distance":89.95a}
Publish OK

1) when distance under 100 cm
it will show normal distance

Editing Ultrasonic Distance Sensor
Distance: 107cm



Sending payload: {"Alert distance":106.98}
Warning crosses 110cm -- it automatically of the loop

Sending payload: {"Alert distance":106.98}
Warning crosses 110cm -- it automatically of the loop

Sending payload: {"Alert distance":106.98}
Warning crosses 110cm -- it automatically of the loop

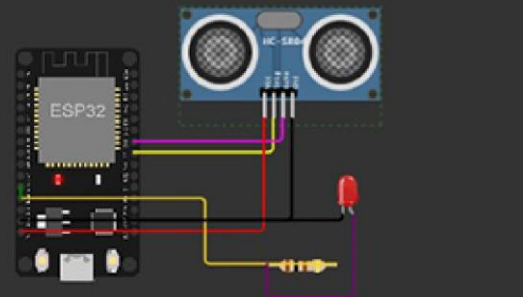
Sending payload: {"Alert distance":106.98}
Warning crosses 110cm -- it automatically of the loop

Sending payload: {"Alert distance":106.98}
Warning crosses 110cm -- it automatically of the loop

Sending payload: {"Alert distance":106.98}
Warning crosses 110cm -- it automatically of the loop

2) when distance cross 100 cm
it will show ALERT with warning message
distance

Editing Ultrasonic Distance Sensor
Distance: 125cm



Sending payload: {"Alert distance":106.98}
Warning crosses 110cm -- it automatically of the loop

Sending payload: {"Alert distance":106.98}
Warning crosses 110cm -- it automatically of the loop

Sending payload: {"Alert distance":106.98}
Warning crosses 110cm -- it automatically of the loop

Sending payload: {"Alert distance":106.98}
Warning crosses 110cm -- it automatically of the loop

Sending payload: {"Alert distance":106.98}
Warning crosses 110cm -- it automatically of the loop

Sending payload: {"Alert distance":106.98}
Warning crosses 110cm -- it automatically of the loop

when it cross above 100 cm it totally
move to if state once it reduce to 100 it on again

IBM CLOUD OUTPUT

Recent Events

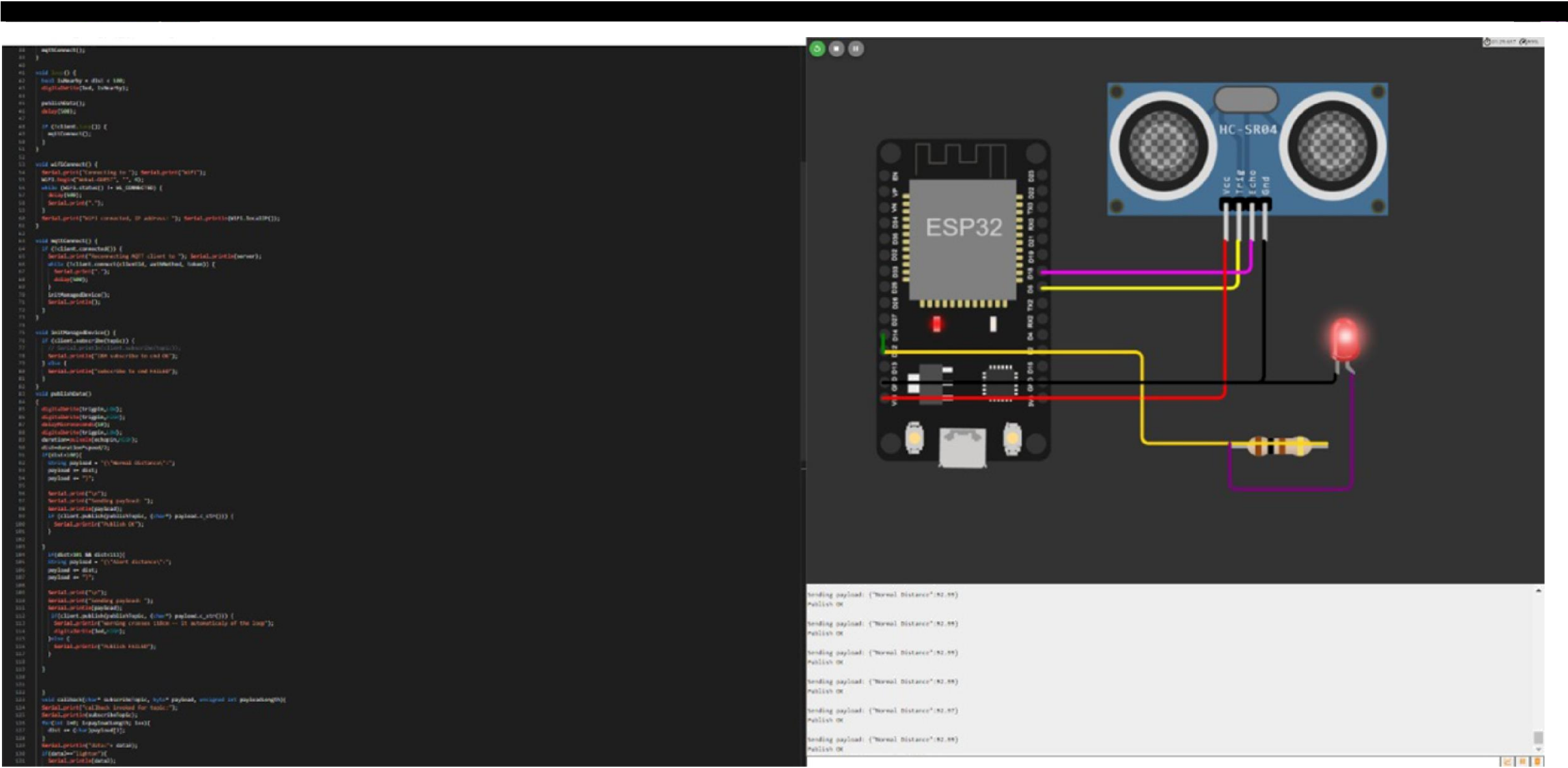
The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Last Received
Data	Normal Distance:89.95	a few seconds ago
Data	Normal Distance:69.95	a few seconds ago
Data	Normal Distance:89.95	a few seconds ago
Data	Normal Distance:89.95	a few seconds ago
Data	Normal Distance:89.95	a few seconds ago

Received Events

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
Data	Alert distance:106.98	json	a few seconds ago
Data	Alert distance:107.03	json	a few seconds ago
Data	Alert distance:106.98	json	a few seconds ago
Data	Alert distance:106.98	json	a few seconds ago
Data	Alert distance:106.96	json	a few seconds ago



Connection Information

Basic connection information about this device.

Device ID	Assignment4
Device Type	nodeMcu
Date Added	23 Oct 2022 07:20
Added @	920219104302 t3'smar\internz.com
Connection Status	Disconnected
	Last Connected: 23 Oct 2022 16:57
	Client Address: 145.40.94.93 Insecure
	Duration: 3 minutes
	Data Transferred: 14.4 KB

Recent Events

The recent events listed show the payload of data that is coming and going from the device.

Event	Value	Format	Last Received
Data	"Normal Distance":92,99/	json	a few seconds ago
Data	{"Normal Distance":92,99/	json	a few seconds ago
Data	{"Normal Distance":92,99:	json	a few seconds ago
Data	{"Normal Distance":92,99:	json	a few seconds ago
Data	{"Normal Distance":92,99/	json	a few seconds ago

WORKING FLOW LISTED IN description