Sprint 2

Software- Created evice in the IoTW at son Platform, workflow for IoT Scenarios using Local Node

| Date | 11-11-2022 |
|--------------|--|
| Team ID | PNT2022TMID04650 |
| Project Name | Project – Smart Farmer-IoT Enabled smart |
| | Farming Application |

Program:

```
#include <Adafruit_LiquidCrystal.h> //Includes the library for LCD Display
#include <Wire.h>
                              //Includes the library for connections
#include <Servo.h>
                              //Includes the library for Servo Motor
Servo s;
int e = 4;
int t=5;
int r = 12;
int b = 11;
int g = 10;
int sec = 0;
int Sensor = 0;
int soil = 0;
int motorPin=9;
Adafruit_LiquidCrystal lcd(0);
void setup()
{
  Wire.begin();
  pinMode(A0, INPUT);
                                     // Temperature Sensor
                                     // Soil Moisture Sensor
  pinMode(A1, INPUT);
  pinMode(t, OUTPUT);
                                     // Ultra sonic Trigger
```

```
pinMode(e, INPUT);
                                   // Ultra sonic Echo
                                   // GREEN light for LED
  pinMode(b, OUTPUT);
                                   // BLUE light for LED
  pinMode(g, OUTPUT);
  pinMode(r, OUTPUT);
                                   // RED light for LED
  pinMode(motorPin, OUTPUT); // DC motor
  s.attach(3);
                                   // Servo Motor
  lcd.begin(16, 2);
                                   // LCD 16x2 Display
  lcd.setBacklight(0);
  Serial.begin(9600);
}
float readDistanceCM()
{
  digitalWrite(t, LOW);
delayMicroseconds(2);
                        digitalWrite(t,
HIGH); delayMicroseconds(10);
  digitalWrite(t, LOW); int
duration = pulseIn(e, HIGH);
return duration * 0.034 / 2;
}
void loop()
{
  // Soil Moisture:
  Sensor = analogRead(A1);
                                   //
Reads data from Soil Moisture
soil = map(Sensor, 0, 1023, 0, 117);
```

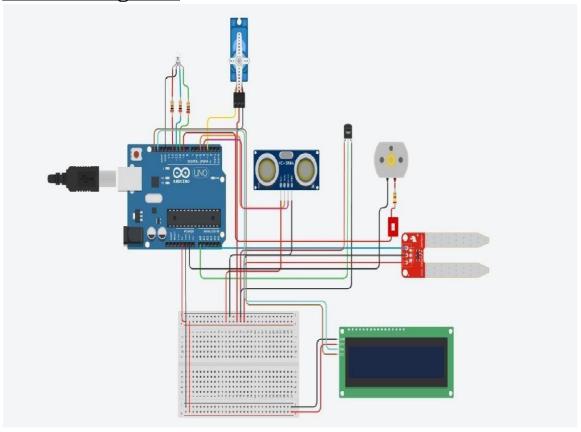
```
// Low analog value indicates HIGH moisture level and High analog value
indicates LOW moisture level
  // data = map(analogValue,fromLOW,fromHIGH,toLOW,toHIGH)
  Serial.print("Soil Moisture value:");
  Serial.println(soil);
  //'data = 0' indicates total wetness and 'data = 100' indicates total dryness
  // Temperature:
                     double a = analogRead(A0);
                                                        // Reads data from
                      double t = (((a / 1024) * 5) - 0.5) * 100;
Temperature sensor
  Serial.print("Temperature value:"); //Temperature value in Celsius
Serial.println(t);
  // Ultrasonic sensor: float distance = readDistanceCM(); //Reads
data from Ultrasonic sensor
  Serial.print("Measured distance: ");
Serial.println(readDistanceCM());
  // LCD Display:
                       lcd.setBacklight(1);
                                                        //ON the
background light in LCD
                           lcd.clear();
  // Conditions:
  /*If the temperature is Greater than 20 and less than 35 and also the moisture
of soil is less than 60 then the GREEN light will be turned ON indicating the
Normal condition */ if (t \ge 20 \&\& t < 35 \&\& soil \ge 40 \&\& soil < 50)
  {
     digitalWrite(b, 0);
digitalWrite(g, 1);
digitalWrite(r, 0);
                        s.write(90);
```

```
digitalWrite(motorPin, HIGH);
lcd.setCursor(3, 0);
lcd.print("ON MOTOR");
delay(1000);
                  lcd.clear();
    Serial.println("Water Partially Flows");
  }
  /*If the temperature is Greater than 35 and less than 45, then the BLUE light
will be turned ON indicating the Intermediate risk condition due to slightly
warm weather */
  else if (t \ge 35 \&\& t < 45)
  {
    digitalWrite(b, 1);
digitalWrite(g, 0);
digitalWrite(r, 0);
                        s.write(90);
digitalWrite(motorPin, HIGH);
lcd.setCursor(3, 0);
lcd.print("ON MOTOR");
delay(1000);
                  lcd.clear();
    Serial.println("Water Partially Flows");
  }
  /*If the temperature is Greater than 45 or the moisture of soil is less than 30,
then the RED light will be turned ON indicating the Critical condition due to
highly warm weather or the low moisture content in soil */
                                                            else if (t >= 45 ||
soil < 30)
  {
```

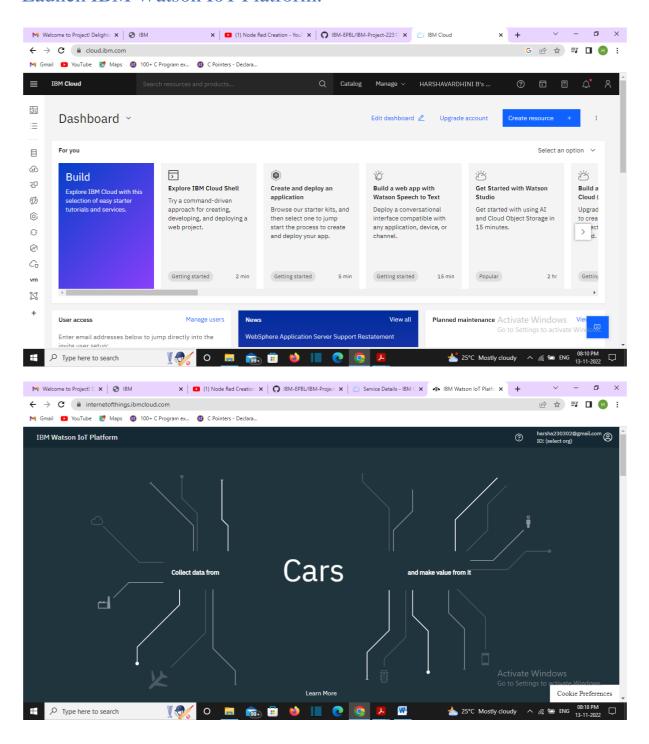
```
digitalWrite(b, 0);
digitalWrite(g, 0);
digitalWrite(r, 1);
                       s.write(180);
    digitalWrite(motorPin, HIGH);
Serial.println("Water Fully Flows");
                         lcd.print("ON
lcd.setCursor(2, 0);
MOTOR!!!");
    lcd.setCursor(3, 1);
    lcd.print("Low Water");
delay(1000);
                 lcd.clear();
  }
  /*If the level of water is MORE in the field it will be indicated by distance
sensor for less than 10cm and also the moisture of soil is greater than 80, then
the
YELLOW light will be turned ON indicating the high water level */
else if (distance<10 && soil> 80)
  {
    digitalWrite(b, 0);
digitalWrite(g, 1);
digitalWrite(r, 1);
                       s.write(0);
    digitalWrite(motorPin, LOW);
Serial.println("Water Does Not Flow");
lcd.clear();
                lcd.setCursor(3, 0);
lcd.print("OFF MOTOR");
delay(1000);
                 lcd.clear();
lcd.setCursor(1, 0);lcd.print("DRAIN
WATER!!!");
                   delay(1000);
lcd.clear();
```

```
}
  else
  {
    digitalWrite(b, 1);
digitalWrite(g, 1);
digitalWrite(r, 0);
                     s.write(0);
    digitalWrite(motorPin, LOW);
lcd.setCursor(3, 0);
lcd.print("OFF MOTOR");
delay(1000);
                lcd.clear();
    Serial.println("Water Does Not Flow");
  }
  lcd.setCursor(0, 0);
lcd.print("Temp:");
lcd.print(t);
lcd.print("degree");
lcd.setCursor(0, 1);
lcd.print("SoilWetness:");
lcd.print(soil); lcd.print("%");
  Serial.println(" ------ ");
delay(1000);
}
```

Circuit Diagram:



Launch IBM Watson IoT Platform:



Steps to configure:

- Create an account in IBM cloud using your email ID
- Create IBM Watson Platform in services in your IBM cloud account
- Launch the IBM Watson IoT Platform
- Create a new device
- Give credentials like device type, device ID, Auth. Token
- Create API key and store API key and token elsewhere.

