## Assignment 4

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## **Question-1:**

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less 100 cms send "alert" to ibm cloud and display in device recent events.

## **Solution:**

```
#include <WiFi.h>//library for wifi
#include <PubSubClient.h>//library for MQtt
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);
//----credentials of IBM Accounts-----
#define ORG "rdegyk"//IBM ORGANITION ID
#define DEVICE_TYPE "weather1 "//Device type mentioned in ibm watson IOT Platform
#define DEVICE_ID "weather1 "//Device ID mentioned in ibm watson IOT Platform
#define TOKEN " _oa-3bajxqvCrO(6kW "
String data3; float dist;
//----- Customise the above values ----- char server[] = ORG
".messaging.internetofthings.ibmcloud.com";// Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event perform and format
in which data to be send char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd
REPRESENT command type AND COMMAND IS TEST OF FORMAT STRING char
authMethod[] = "use-token-auth";// authentication method
char token[] = TOKEN; char clientId[] = "d:" ORG ":" DEVICE_TYPE
":" DEVICE_ID;//client id
```

```
//_____
```

WiFiClient wifiClient; // creating the instance for wificlient

PubSubClient client(server, 1883, callback ,wifiClient); //calling the predefined client id by passing parameter like server id,portand wificredential

```
int LED = 4;
int trig = 5;
int echo = 18;
void setup()
Serial.begin(115200);
pinMode(trig,OUTPUT);
pinMode(echo,INPUT);
pinMode(LED, OUTPUT);
delay(10); wificonnect(); mqttconnect();
}
void loop()// Recursive Function
{
digitalWrite(trig,LOW);
digitalWrite(trig,HIGH);
delayMicroseconds(10);
digitalWrite(trig,LOW);
                           float
           pulseIn(echo,HIGH);
dur
float dist = (dur * 0.0343)/2;
Serial.print ("Distancein cm");
Serial.println(dist);
PublishData(dist);
delay(1000);
(!client.loop()) {
mqttconnect();
 }
```

```
}
/*....retrieving to Cloud. .....*/
void PublishData(float dist) { mqttconnect();//function
call for connecting to ibm
      creating the String in in form JSon to update the data to ibm cloud
 */ String
object; if
(dist < 100)
  digitalWrite(LED,HIGH);
Serial.println("object is near");
                                 object
= "Near";
 }
 else
  digitalWrite(LED,LOW);
Serial.println("no object found"); object
= "No";
 }
 String payload = "{\"distance\":";
payload += dist; payload += ","
"\"object\":\""; payload += object;
payload += "\"}";
Serial.print("Sending payload: ");
Serial.println(payload); if (client.publish(publishTopic,
(char*) payload.c_str())) {
  Serial.println("Publish ok");// if it sucessfully upload data on the cloud then it will print publish ok
in Serial monitor or else it will print publish failed
 } else {
  Serial.println("Publish failed");
 }
```

```
}
void mqttconnect() { if
(!client.connected()) {
  Serial.print("Reconnecting client to ");
                        while (!!!client.connect(clientId, authMethod,
Serial.println(server);
token)) {
             Serial.print(".");
                                 delay(500);
  }
   initManagedDevice();
  Serial.println();
 }
void wificonnect() //function defination for wificonnect
 Serial.println();
 Serial.print("Connecting to ");
 WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
while (WiFi.status() != WL_CONNECTED) { delay(500);
  Serial.print(".");
 Serial.println("");
 Serial.println("WiFi connected");
 Serial.println("IP address: ");
 Serial.println(WiFi.localIP());
void initManagedDevice() { if
(client.subscribe(subscribetopic)) {
Serial.println((subscribetopic));
  Serial.println("subscribe to cmd OK");
 } else {
  Serial.println("subscribe to cmd FAILED");
```

```
}
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{
    Serial.print("callback invoked for topic: ");
    Serial.println(subscribetopic); for (int i =
    0; i < payloadLength; i++) {
    //Serial.print((char)payload[i]); data3 +=
    (char)payload[i];
    }
    data3="";
}
</pre>
```



