## Assignment-4

AssignmentDate	29October2022
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StudentRoll Number	211719106006
Maximum Marks	2Marks

## Question-1:

Writecodeandconnectionsinwokwifortheultrasonicsensor.

Whenever the distance is less than 100 cmss end an "alert" to the IBM cloud and display in the device recent events.

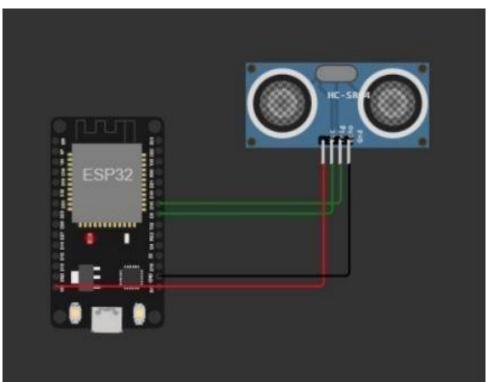
Upload documentwithwokwisharelinkandimages of IBM cloud

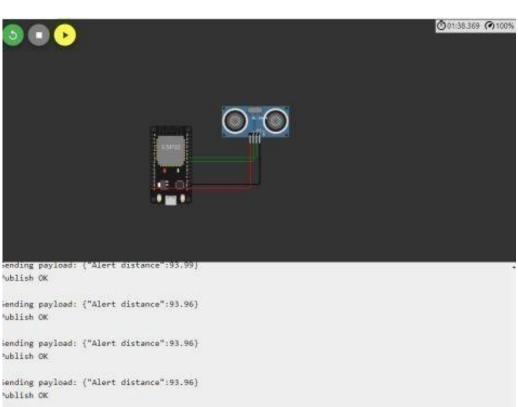
## Solution:

```
#include<WiFi.h>#include<</pre>
PubSubClient.h>#include<A</pre>
rduinoJson.h>
WiFiClientwifiClient;
#defineORG"nhpwjc"
#defineDEVICE_TYPE"raspberypi"#
defineDEVICE_ID"12345"
#defineTOKEN"123456789"
#definespeed0.034
char server[] = ORG
".messaging.internetofthings.ibmcloud.com"; charpublishTopic[]="
iot-2/evt/Data/fmt/json";
chartopic[]="iot-
2/cmd/home/fmt/String";char
authMethod[]="use-token-auth";
chartoken[]=TOKEN;
char clientId[]="d:"ORG":"DEVICE_TYPE":"DEVICE_ID;
PubSubClientclient(server, 1883, wifiClient); vo
idpublishData();
const int
trigpin=5;constintec
hopin=18;Stringcomma
nd;Stringdata="";
long
duration; int
dist;
voidsetup()
 Serial.begin(115200);pinM
 ode(trigpin,OUTPUT);pinMo
 de(echopin,
 INPUT);wifiConnect();mqtt
 Connect();
voidloop(){
```

```
publishData();delay(500)
;
```

```
if(!client.loop()){m
    qttConnect();
 }
}
voidwifiConnect(){
 Serial.print("Connectingto"); Serial.print("Wifi"); Wi
 Fi.begin("Wokwi-GUEST","",6);
 while(WiFi.status()!=WL_CONNECTED){del
    ay(500);
    Serial.print(".");
 }
 Serial.print("WiFiconnected,IPaddress:");Serial.println(WiFi.localIP());
}
voidmqttConnect(){
  if(!client.connected()){
    Serial.print("Reconnecting MQTT client to ");
    Serial.println(server); while(!client.connect(clientId,
    authMethod,token)){
      Serial.print(".");d
      elay(1000);
    initManagedDevice();
    Serial.println();
 }
voidinitManagedDevice(){
 if (client.subscribe(topic))
    {Serial.println(client.subscribe(topic)); Serial.println("subs
    cribeto cmdOK");
 }else{
    Serial.println("subscribetocmdFAILED");
 }
}
voidpublishData()
 digitalWrite(trigpin,LOW);digitalWrite(t
 rigpin,HIGH);delayMicroseconds(10);digit
  alWrite(trigpin,LOW);duration=pulseIn(echo
 pin,HIGH);dist=duration*speed/2;
  if(dist<100){DynamicJsonDocument</pre>
    doc(1024);Stringpayload;doc["
    AlertDistance:"]=dist;seriali
    zeJson(doc,
    payload);delay(3000);Serial.p
    rint("\n");
    Serial.print("Sendingpayload:");
    Serial.println(payload);
    if(client.publish(publishTopic,(char*)payload.c_str())){
      Serial.println("PublishOK");
    }else{
     Serial.println("PublishFAILED");
    }
 }
}
```





ending payload: ("Alert distance":93.96)

ending payload: {"Alert distance":93.96}

Publish OK

hublish OK

