ASSIGNMENT-4

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QUESTION:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events. Upload document with wokwi share link and images of ibm cloud.

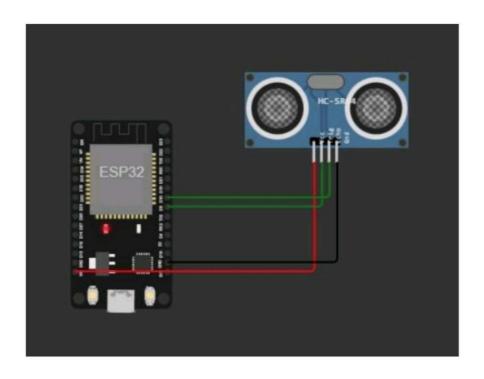
```
CODE:
#include <WiFi.h>
#include < PubSubC1ient.h >
#include <ArduinoJson.h>
WiFiClient wifiClient;
#define ORG "lbklkq"
#define DEVICE TYPE "abcd"
#define DEVICE ID "rasp"
#define TOKEN "12345678"
#define speed 0.034
char
                                             ORG
              server[]
.messaging.internetofthings.ibmcloud.com"; char publishTopic[]
   iot -2/evt/abcd_1/fmt/j son ; char topic [
2/cmd/home/fmt/String"; char authMethod [] - "use-token-auth"
; char token[] = TOKEN; char clientld[] -- ORG DEVICE TYPE
DEVICE ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin=5; const
int echopin=18;
String command;
String data=....
String lat="14.167589";
String lon="80.248510";
```

```
String name= "
       point2";
String icon="";
long duration; int
dist;
void setup()
  Serial. begin (115200);
  pinMode(trigpin,
  OUTPUT)
  pinMode(echopin, INPUT)
             wifiConnect();
  mqttConnect();
void loop() {
  publishData();
  delay(500);
  if (! client. loop()) {mqttConnect()
void wifiConnect() {
  Serial. print("Connecting to "); Serial. print ("Wifi"
  ); WiFi.begin ("Wokwi-GUEST", "", 6) while
  (WiFi.status() != WL CONNECTED) { delay(500);
    Serial. print(".");
  Serial. print("WiFi connected, IP address: ");Serial. print
In(WiFi.10ca11P());
void mqttConnect() { if ( !
  client. connected()) {
    Serial. print("Reconnecting MQTT client to Serial. println(server);
    while (! client. connect(clientld, authMethod, token)) { Serial. print
    (".");delay(1000);
    initManagedDevice();
```

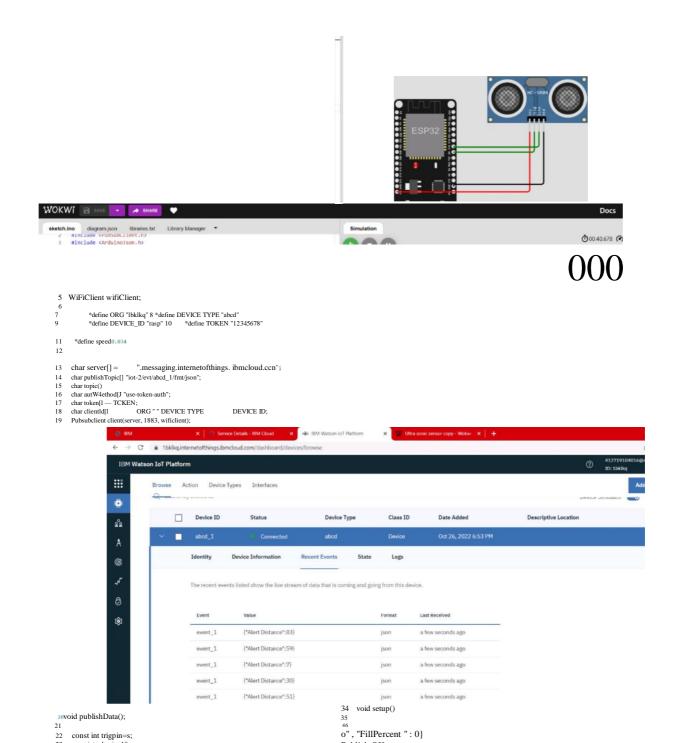
```
Serial . print Ino;
void initManagedDevice() {
  if (client. subscribe(topic)) {
     Serial. print In (client . subscribe (topic));
    Serial println("subscribe to cmd OK");
  } else {
    Serial println("subscribe to cmd FAILED");
void publishData()
  digitalWrite(trigp1n, LOW);
  digitalWrite(trigpin,HIGH);
  delayMicroseconds(10)
  digitalWrite(trigp1n, LOW);
  duration=pulseln(echopin,HI
  GH) :dist=duration*speed/2;
  if(dist< 100) {dist-
    lee-dist; icon="fa-
    trash";
  }else{ dist=e,
    icon="fa-trash-o"
  DynamicJsonDocument doc(1Ø24);
  String payload; doc
  "Name" ]=name; doc [ "
  Latitude" ]=lat; doc [
  Longitude"]=lon; doc
  "Icon" ]=icon; doc
  FillPercent
                  1
                        -dist;
  serializeJson(doc,
  payload); delay (3000);
  Serial. print("\n");
  Serial. print("Sending payload: "); Serial. print In (payload); if
  (client. publish(pub1ishTopic, (char*) payload.c_str())) {
    Serial. print1n("Pub1ish OK");
```

} else {

Serial. print In("Publish FAILED");
CONNECTIONS:



OUTPUT:



Publish OK

| { "Name" : "point2" , "Latitude" : "14.167589" , "Longitude" : "8e.24851B" "Icon" : "fa-trash• o" , "FillPercent" : Publish OK

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23 const int echopin=18•, 24 String c—and; Serial begin(115200); 25 string data=" 26 string lat-"14.167589"; 27 String Ion-"RO.24851Ø";

28 String name="point2";

22 const int trigpin=s;

29 String icon="";

31 long duration;

32 int dist;