<matplotlib.image.AxesImage at 0x7f9465e88510>



# Reshaping the data

```
X_train =X_train.reshape(60000,28,28,1).astype('float32')
X_test =X_test.reshape(10000,28,28,1).astype('float32')
```

# One Hot Encoding

```
number_of_classes = 10
y_train = np_utils.to_categorical(y_train,number_of_classes)
y_test=np_utils.to_categorical(y_test,number_of_classes)
y_train[0]
array([0., 0., 0., 0., 0., 0., 0., 0., 0.], dtype=float32)
```

## **MODEL BUILDING**

## → ADD CNN LAYERS

```
# CREATING THE MODEL
model = Sequential()
#adding model layer
model.add(Conv2D(64,(3,3),input_shape=(28,28,1),activation='relu'))
model.add(Conv2D(32,(3,3),activation='relu'))
model.add(Flatten())
model.add(Dense(number_of_classes,activation='softmax'))
```

# Compiling the model

```
model.compile(loss='categorical_crossentropy',optimizer='Adam',metrics=['accuracy'])
```

### Train the model

## → OBSERVING THE METRICS

```
metrics= model.evaluate(X_test,y_test,verbose=0)
print("Metrics(Test loss & Test Accuracy): ")
print(metrics)

Metrics(Test loss & Test Accuracy):
   [0.07943267375230789, 0.9800999760627747]
```

### ▼ PREDICTING THE OUTPUT

```
prediction = model.predict(X_test[:4])
print(prediction)
     1/1 [======= ] - 0s 105ms/step
     [[1.92560523e-09 4.01850529e-17 5.50588419e-09 2.96046232e-09
      8.29567738e-14 2.69424494e-14 2.47960087e-20 1.000000000e+00
      9.45855200e-12 3.30721561e-10]
      [2.61439848e-09 1.07959084e-11 1.00000000e+00 1.53540125e-10
       2.90862453e-15 1.13654680e-15 5.82739135e-11 7.71922828e-19
       2.21205207e-11 8.07522963e-17]
      [5.78494564e-06 9.94477868e-01 6.71379121e-06 2.65865587e-08
      1.06376270e-03 4.35107807e-03 6.03496301e-06 6.35672563e-08
      8.86625785e-05 3.47364748e-10]
      [9.99999762e-01 1.14116395e-16 1.04427467e-09 2.66038293e-14
       3.39294669e-11 3.35020171e-11 1.04318076e-07 1.11794697e-11
      4.95246011e-10 1.00263563e-07]]
import numpy as np
print(np.argmax(prediction,axis=1))
print(y_test[:4])
```

```
[7 2 1 0]

[[0. 0. 0. 0. 0. 0. 0. 0. 1. 0. 0.]

[0. 0. 1. 0. 0. 0. 0. 0. 0. 0.]

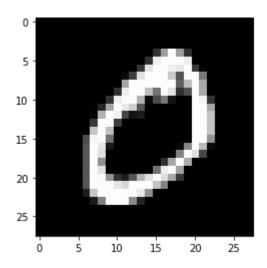
[0. 1. 0. 0. 0. 0. 0. 0. 0. 0.]

[1. 0. 0. 0. 0. 0. 0. 0. 0. 0.]
```

Hard-maxed form of the prediction:

```
[[1. 0. 0. 0. 0. 0. 0. 0. 0. 0.]]
```

----- Prediction -----



Final Output: 0

#### ▼ OBSERVING THE METRICS

```
metrics= model.evaluate(X test,y test,verbose=0)
print("Metrics(Test loss & Test Accuracy): ")
print(metrics)
    Metrics(Test loss & Test Accuracy):
     [0.07943267375230789, 0.9800999760627747]
prediction = model.predict(X_test[:4])
print(prediction)
import numpy as np
print(np.argmax(prediction,axis=1))
print(y test[:4])
     1/1 [=======] - 0s 26ms/step
     [[1.92560523e-09 4.01850529e-17 5.50588419e-09 2.96046232e-09
       8.29567738e-14 2.69424494e-14 2.47960087e-20 1.00000000e+00
       9.45855200e-12 3.30721561e-10]
      [2.61439848e-09 1.07959084e-11 1.00000000e+00 1.53540125e-10
       2.90862453e-15 1.13654680e-15 5.82739135e-11 7.71922828e-19
       2.21205207e-11 8.07522963e-17]
      [5.78494564e-06 9.94477868e-01 6.71379121e-06 2.65865587e-08
       1.06376270e-03 4.35107807e-03 6.03496301e-06 6.35672563e-08
       8.86625785e-05 3.47364748e-10]
      [9.99999762e-01 1.14116395e-16 1.04427467e-09 2.66038293e-14
       3.39294669e-11 3.35020171e-11 1.04318076e-07 1.11794697e-11
       4.95246011e-10 1.00263563e-07]]
     [7 2 1 0]
     [[0. 0. 0. 0. 0. 0. 0. 1. 0. 0.]
      [0. 0. 1. 0. 0. 0. 0. 0. 0. 0.]
      [0. 1. 0. 0. 0. 0. 0. 0. 0. 0.]
      [1. 0. 0. 0. 0. 0. 0. 0. 0. 0.]]
```

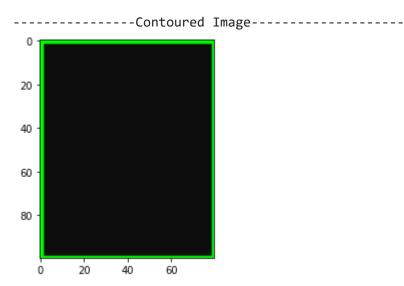
### ▼ SAVE THE MODEL

```
import cv2
image = cv2.imread('test_image.jpg')
image = np.full((100,80,3), 12, dtype = np.uint8)
grey = cv2.cvtColor(image.copy(), cv2.COLOR_BGR2GRAY)
ret, thresh = cv2.threshold(grey.copy(), 75, 255, cv2.THRESH_BINARY_INV)
contours, hierarchy = cv2.findContours(thresh.copy(), cv2.RETR_EXTERNAL, cv2.CHAIN_APPROX_SIMP
preprocessed_digits = []

for c in contours:
    x,y,w,h = cv2.boundingRect(c)

# Creating a rectangle around the digit in the original image (for displaying the digits
    cv2.rectangle(image, (x,y), (x+w, y+h), color=(0, 255, 0), thickness=2)
```

```
# Cropping out the digit from the image corresponding to the current contours in the for
   digit = thresh[y:y+h, x:x+w]
   # Resizing that digit to (18, 18)
   resized_digit = cv2.resize(digit, (18,18))
   # Padding the digit with 5 pixels of black color (zeros) in each side to finally produce
   padded_digit = np.pad(resized_digit, ((5,5),(5,5)), "constant", constant_values=0)
   # Adding the preprocessed digit to the list of preprocessed digits
   preprocessed digits.append(padded digit)
print("\n\n\n-----")
import os, types
import pandas as pd
def iter (self): return 0
print=("\n\n\n-----")
plt.imshow(image, cmap="gray")
plt.show()
inp = np.array(preprocessed_digits)
```



## → SAVE THE MODEL

model.save('model.h5')