```
unport agairuit ant
import psutil
for proc in psutil.process iter():
   if proc_name() == 'lipgpiod pulsein' or proc_name() == 'libgpiod_pulsei'::
        proc.kill()
sensor=adafruit dht.DHT11(board.D23)
while true:
   try:
        temp = sensor.temperature
       humidity = sensor.humidity
       print("Temperature:{}*c Humidity:{}% ".format(temp.humidity))
   except Run time error as error:
       print (error.args[0])
        time.sleep(2.0)
        continue
   except Exception as error:
        sensor.exit()
        raise error
   time.sleep(2.0)
```