



```

int pinSensor =2;
int pinBuzzer =7;
int pirSensor =0;
float sensor=A3;
float analog;
float tempv;
float tempc;
float tempf;
void setup()
{
  pinMode(pinSensor, INPUT);
  pinMode(sensor, INPUT);
  pinMode(pinBuzzer, OUTPUT);
  Serial.begin(9600);
}
void loop()
{
  analog=analogRead(sensor);
  tempv=analog*5.0/1023;
  tempc=(tempv-0.5)*100.0;
  tempf=((tempc*9.0)/5.0)+32.0;
  Serial.print("temperature:");

  Serial.println(tempc);
  if (tempc >=60)
  {
    tone(pinBuzzer, 200, 100);
  }
  delay(100);
  pirSensor = digitalRead(pinSensor);
  if (pirSensor == HIGH)
  {
    tone(pinBuzzer, 1000, 500);
  }
  delay(100);
}

```