Assignment-4

AssignmentDate	8 November 2022
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Maximum Marks	2Marks

Question-1:

Writecodeandconnectionsinwokwifortheultrasonicsensor.

Whenever the distance is less than 100 cmss end an "alert" to the IBM cloud and display in the device recent events.

Upload documentwithwokwisharelinkandimages of IBM cloud

Solution:

```
#include<WiFi.h>#include
  <PubSubClient.h>#include
  <ArduinoJson.h>
  WiFiClientwifiClient;
  #defineORG"nhpwjc"
  #defineDEVICE_TYPE"raspberypi"#
  defineDEVICE_ID"12345"
  #defineTOKEN"123456789"
  #definespeed0.034
  char server[] = ORG
  ".messaging.internetofthings.ibmcloud.com"; charpublishTopic[]="
  iot-2/evt/Data/fmt/json";
  chartopic[]="iot-2/cmd/home/fmt/String";cha
  r authMethod[]="use-token-auth";
  chartoken[]=TOKEN;
  char clientId[]="d:"ORG":"DEVICE_TYPE":"DEVICE_ID;
  PubSubClientclient(server,1883,wifiClient);vo
  idpublishData();
  const int
  trigpin=5;constintec
  hopin=18;Stringcomma
  nd;Stringdata="";
  long
  duration; int
  dist;
  voidsetup()
    Serial.begin(115200);pin
    Mode(trigpin,OUTPUT);pin
    Mode(echopin,
    INPUT);wifiConnect();mqt
    tConnect();
  voidloop(){
publishData();delay(500);
```

```
if(!client.loop()){m
    qttConnect();
}
voidwifiConnect(){
 Serial.print("Connectingto");Serial.print("Wifi");Wi
 Fi.begin("Wokwi-GUEST","",6);
 while(WiFi.status()!=WL_CONNECTED){del
    ay(500);
    Serial.print(".");
 }
 Serial.print("WiFiconnected,IPaddress:");Serial.println(WiFi.localIP());
voidmqttConnect(){
 if(!client.connected()){
    Serial.print("Reconnecting MQTT client to ");
    Serial.println(server); while(!client.connect(clientId,
    authMethod,token)){
     Serial.print(".");
     delay(1000);
    initManagedDevice();
    Serial.println();
 }
}
voidinitManagedDevice(){
  if (client.subscribe(topic))
    {Serial.println(client.subscribe(topic));Serial.println("su
    bscribeto cmdOK");
 }else{
    Serial.println("subscribetocmdFAILED");
 }
}
voidpublishData()
 digitalWrite(trigpin,LOW);digitalWrite(tr
  igpin,HIGH);delayMicroseconds(10);digital
 Write(trigpin,LOW);duration=pulseIn(echop
  in,HIGH);dist=duration*speed/2;
  if(dist<100){DynamicJsonDocume</pre>
    ntdoc(1024);Stringpayload;do
    c["AlertDistance:"]=dist;ser
    ializeJson(doc,
    payload);delay(3000);Serial.
    print("\n");
    Serial.print("Sendingpayload:");
    Serial.println(payload);
    if(client.publish(publishTopic,(char*)payload.c_str())){
     Serial.println("PublishOK");
    }else{
     Serial.println("PublishFAILED");
 }
```





