



```
int pinSensor = 2;
int pinBuzzer = 7;
int pirSensor = 0;
float sensor = A3;
float analog;
float tempv;
float tempc;
float tempf;
void setup()
{
  pinMode(pinSensor, INPUT);
  pinMode(sensor, INPUT);
  pinMode(pinBuzzer, OUTPUT);
  Serial.begin(9600);
}
void loop()
{
  analog = analogRead(sensor);
  tempv = analog * 5.0 / 1023;
  tempc = (tempv - 0.5) * 100.0;
  tempf = ((tempc * 9.0) / 5.0) + 32.0;
  Serial.print("temperature:"); Serial.println(tempc);
  if (tempc >= 60)
  {
    tone(pinBuzzer, 200, 100);
```

```
}  
delay(100);  
pirSensor = digitalRead(pinSensor);  
if (pirSensor == HIGH)  
{  
tone(pinBuzzer, 1000, 500);  
}  
delay(100);  
}
```