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PIR Sensor:

A passive infrared sensor (PIR) is an electronic sensor which is used to detect motion. The sensor measures infrared (IR) light radiating from objects in its field of view. Mainly they have used in PIR based motion detectors.

Piezo Alarm:

Piezo Buzzers and Alarms The piezo buzzer is a watch beeper on steroids. Once exotic and pricey, it is now a useful and ubiquitous commodity. The piezo element itself consists of nothing more than a thin disk of piezo bonded to a thin disk of metal (typically brass, but sometimes stainless steel).

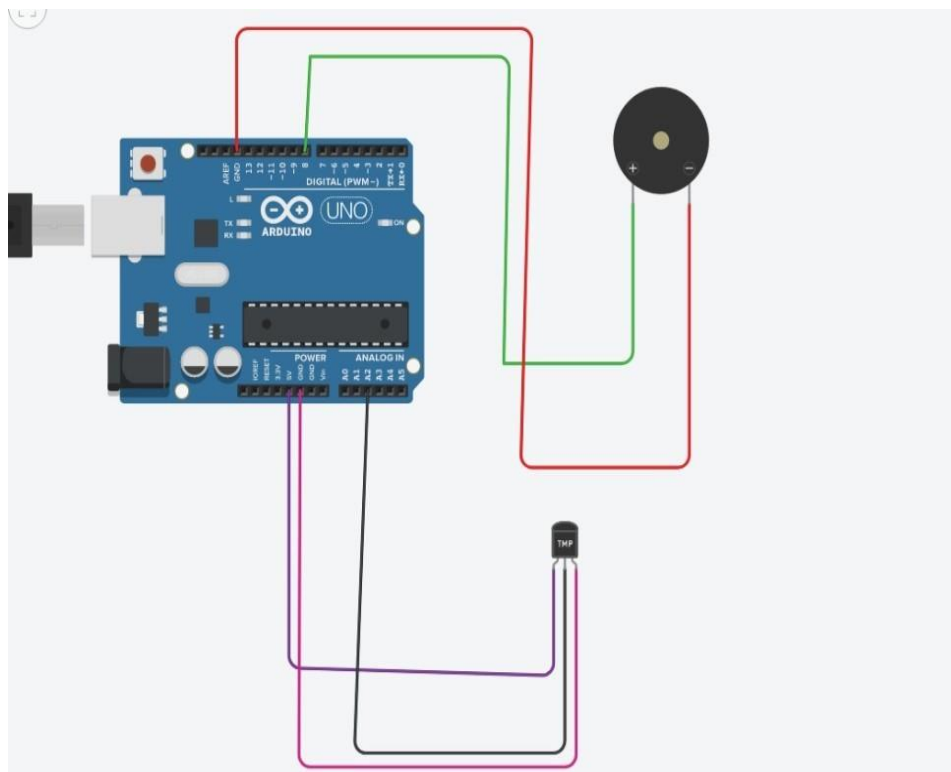
Temperature sensor:

Temperature sensor is a device, used to measure the temperature using an electrical

signal. It requires a **thermocouple** or **RTD (Resistance temperature Detector)**. It is the most common and most popular sensor. Temperature sensor, the change in the temperature correspond to change in its physical property like resistance or voltage.

1) Temperature detection using temperature sensor

Circuit diagram:



Coding:

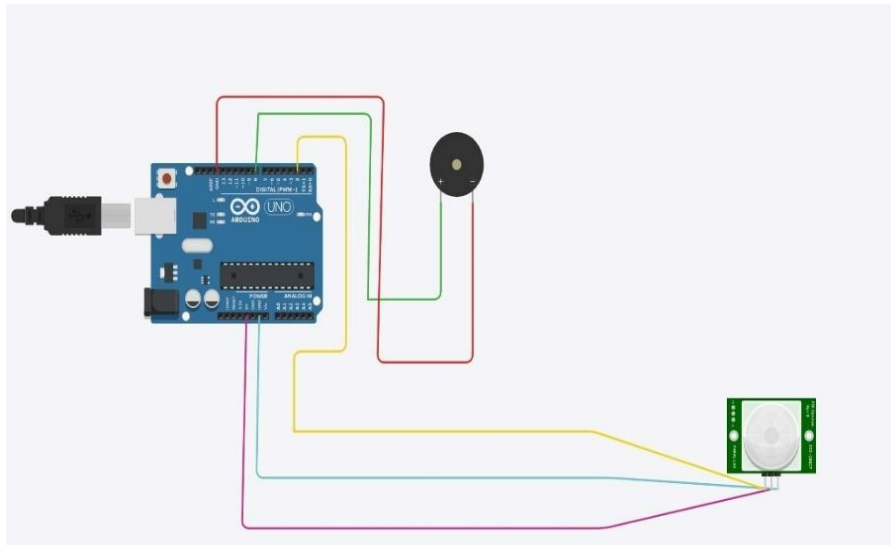
```
1 void setup()
2 {
3   Serial.begin(9600);
4   pinMode(8,OUTPUT);
5 }
6 void loop
7 {
8   for(int freq=0; freq<=30000;freq++)
9   {
10    tone(8,freq);
11    delay(1000);
12    notone(8);
13    delay(500);
14    double data=analogRead(A2);
15    double n=data/1024;
16    Serial.print("Converted to analog data:");
17    Serial.println(n);
18    double volt=n*5;
19    Serial.print("Voltage data");
20    Serial.print(volt);
21    double off=volt-0.5;
22    Serial.print("Serial off set data:");
23    int temp=freq;
24    if(temp>=60)
25    {
26      Serial.print("The tmperature is high");
27    }
28    else
29    {
30      Serial.println("The tmperature is low");
31    }
```

Output:

```
After offset data:0.25
The Tmparature is highConverted analog data:0.15
voltage data:0.75
After offset data:0.25
The Tmparature is highConverted analog data:0.15
voltage data:0.75
After offset data:0.25
The Tmparature is high
```

2) Motion detection using PIR sensor

Circuit digram:



Coding:

```
void setup()
{
  Serial.begin(9600);
  pinMode(8,OUTPUT);
  pinMode(2,INPUT);
}
void loop()
{
  for(int freq=0;freq<=30000;freq++)
  {
    tone(8,freq);
    delay(1000);
    noTone(8);
    delay(500);
  }
  int motion=digitalRead(2);
  Serial.print("Position is:");
  Serial.println(motion);
  if (motion==1)
  {
    Serial.print("Motion is detected");
  }
  else
  {
    Serial.print("No Motion");
  }
}
```

Output:

No MotionPosition is:0

No MotionPosition is:0

No MotionPosition is:1

Motion is detectedPosition is:1

Motion is detectedPosition is:1

Motion is detectedPosition is:1

Motion is detectedPosition is:1

Motion is detectedPosition is:1
