

## SPRINT 2

Date	05 Nov 2022
Team ID	PNT2022TMID26330
Project Name	Smart Farmer – IoT Enabled Farming Application
Maximum Marks	8 Marks

The purpose of smart farmer project is to help farmers in the irrigation process. The system provides various parameters like temperature, humidity etc. to monitor the condition of the fields and to protect the crops. Based on the temperature, soil moisture, water level of the field etc., and system will take necessary action and the entire operation can be controlled by the IoT application.

### Sensor Interfacing:

#### Program:

```
#include <Wire.h>
#include <Servo.h>
#include <Adafruit_LiquidCrystal.h>

Servo s; int e = 4; int t = 5; int r =
12; int g = 11; int b = 10; int sec =
0; int Sensor = 0; int data = 0; int
motorPin = 9;
Adafruit_LiquidCrystal lcd(0);

void setup()
{
  Wire.begin();
  pinMode(A0,INPUT);      //Temperature Sensor
  pinMode(A1,INPUT); //Soil Moisture Sensor  pinMode(t,OUTPUT);
//Ultra sonic Trigger  pinMode(e,INPUT);  //Ultra sonic Echo
  pinMode(b,OUTPUT);      //GREEN light for LED
  pinMode(g,OUTPUT);      //BLUE light for LED
  pinMode(r,OUTPUT); //RED light for LED  pinMode(motorPin,
OUTPUT); //DC motor
  s.attach(3);           // Servo Motor
```

```

    lcd.begin(16, 2);                //LCD 16x2 Display
    lcd.setBacklight(0);    Serial.begin(9600);
}

float readDistanceCM(){
    digitalWrite(t, LOW);
    delayMicroseconds(2);
    digitalWrite(t, HIGH);
    delayMicroseconds(10);
    digitalWrite(t, LOW);    int
    duration = pulseIn(e, HIGH);
    return duration * 0.034 / 2;
}

void loop(){
//Soil Moisture:
    Sensor = analogRead(A1);        //Reads data from Soil Moisture sensor    data =
    map(Sensor,0, 1023, 0, 100);        //Low analog value indicates HIGH moisture level
    and High analog value indicates LOW moisture level    //data =
    map(analogValue,fromLOW,fromHIGH,toLOW,toHIGH)
    Serial.print("Soil Moisture value:");
    Serial.println(data);
    //data = 0' indicates wet and 'data = 100' indicates dry

//Temperature:
    double a = analogRead (A0);        //Reads data from Temperature sensor
    double t = (((a/1024)*5)-0.5)*100;
    Serial.print("Temperature value:");
    Serial.println(t);

//Ultrasonic sensor:
    float distance = readDistanceCM();
    Serial.print("Measured distance: ");
    Serial.println(readDistanceCM());

```

```

//LCD Display:
lcd.setBacklight(1);  lcd.clear();

//Conditions:  if (t>40 & t<50){
digitalWrite(b,0);    digitalWrite(g,1);
digitalWrite(r,0);    s.write(90);
digitalWrite(motorPin, HIGH);
Serial.println("Water Partially Flows");
}

else if (t>50){    digitalWrite(b,1);
digitalWrite(g,1);    digitalWrite(r,0);
s.write(180);
digitalWrite(motorPin, HIGH);
Serial.println("Water Fully Flows");
}

else if (t>30 & data<30){
digitalWrite(b,1);    digitalWrite(g,1);
digitalWrite(r,0);    s.write(90);
digitalWrite(motorPin, HIGH);
Serial.println("Water Partially Flows");
}

else if (data<50){    digitalWrite(b,0);
digitalWrite(g,0);    digitalWrite(r,1);
s.write(90);    digitalWrite(motorPin,
HIGH);    Serial.println("Water Partially
Flows");
}

else if (distance < 10){
digitalWrite(b, 0);    digitalWrite(g, 0);

```

```

digitalWrite(r, 1);    s.write(0);
digitalWrite(motorPin, LOW);
Serial.println("Water Does Not Flow");
lcd.clear();          lcd.println("Drain the
water");
    }

    else{    digitalWrite(b,1);
digitalWrite(g,0);    digitalWrite(r,0);
s.write(0);    digitalWrite(motorPin,
LOW);    Serial.println("Water Does Not
Flow");    }    lcd.setCursor(0,0);
lcd.print("Temp:");
    lcd.println(t);
        lcd.println("degree");
lcd.setCursor(0,1);    lcd.print("Soil
Moisture:");    lcd.println(data);
        lcd.println("%");
        Serial.println("-----");
delay(1000);
}

```

**TinketCad Circuit:**

Smart farmer PNT2022TMID12911

All changes saved

Code Start Simulation Send To

Text 1 (Arduino Uno R3)

```
1 #include <Wire.h>
2 #include <Servo.h>
3 #include <Adafruit_LiquidCrystal.h>
4
5 Servo s;
6 int e = 4;
7 int t = 5;
8 int r = 12;
9 int g = 11;
10 int b = 10;
11 int sec = 0;
12 int Sensor = 0;
13 int data = 0;
14 int motorPin = 9;
15 Adafruit_LiquidCrystal lcd(0);
16
17 void setup()
18 {
19   Wire.begin();
20   pinMode(A0, INPUT); //Temperature Sensor
21   pinMode(A1, INPUT); //Soil Moisture Sensor
22   pinMode(t, OUTPUT); //Ultra sonic Trigger
23   pinMode(e, INPUT); //Ultra sonic Echo
24   pinMode(b, OUTPUT); //GREEN light for LED
25   pinMode(g, OUTPUT); //BLUE light for LED
26   pinMode(r, OUTPUT); //RED light for LED
27   pinMode(motorPin, OUTPUT); //DC motor
28   s.attach(3); // Servo Motor
29   lcd.begin(16, 2); //LCD 16x2 Display
30 }
```

Serial Monitor