Assignment -4

Python Programming

Assignment Date	21 OCTOBER 2022
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Maximum Marks	2

Ouestion

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events

CODE:

```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "udeo3r"
#define DEVICE_TYPE "abi"
#define DEVICE_ID "131313"
#define TOKEN "Wja?4cr1fbZIxqT2JY"
#define speed 0.034 #define led 14 char server[] = ORG
".messaging.internetofthings.ibmcloud.com"; char publishTopic[] = "iot-2/evt/Data/fmt/json"; char topic[] = "iot-2/cmd/home/fmt/String"; char authMethod[] = "use-token-auth";
```

```
char token[] = TOKEN;
```

```
char clientId[] = "d:" ORG ":" DEVICE TYPE ":"
DEVICE_ID; PubSubClient client(server, 1883,
wifiClient); void publishData();
const int trigpin=2; const
int echopin=4;
String command;
String data="";
 long
duration;
float dist;
void setup()
 Serial.begin(115200);
pinMode(led, OUTPUT);
pinMode(trigpin, OUTPUT);
pinMode(echopin, INPUT);
wifiConnect(); mqttConnect();
} void loop() { bool
isNearby = dist < 100;</pre>
digitalWrite(led, isNearby);
publishData();
```

```
delay(500);
if (!client.loop()) {
mqttConnect();
```

```
void wifiConnect() {
 Serial.print("Connecting to ");
Serial.print("Wifi"); WiFi.begin("Wokwi-GUEST", "",
6); while (WiFi.status() != WL_CONNECTED) {
delay(500);
   Serial.print(".");
 Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
mqttConnect() {
 if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to ");
Serial.println(server); while (!client.connect(clientId, authMethod,
token)) {
              Serial.print("."); delay(500);
initManagedDevice();
   Serial.println();
```

serial.printin(),
}
void
initManagedDevice() {

```
if (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic));
    Serial.println("IBM subscribe to cmd OK");
} else {
    Serial.println("subscribe to cmd FAILED");
```

```
} } void
publishData()
{ digitalWrite(trigpin,LOW);
digitalWrite(trigpin,HIGH);
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2;
if(dist<100){
    String payload = "{\"Normal
Distance\":";
                payload += dist;
payload += "}";
    Serial.print("\n");
    Serial.print("Sending payload: ");
Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str())) {
      Serial.println("Publish OK");
   if(dist>101 && dist<111){</pre> String
payload = "{\"Alert distance\":";
payload += dist;
    payload += "}";
```

Serial.print("\n");

Serial.println(payload);

Serial.print("Sending payload: ");

```
if(client.publish(publishTopic, (char*) payload.c_str())) {
```

data3="";





