

**REAL TIME RIVER WATER QUALITY  
MONITORING AND CONTROL SYSTEM**

**SUBMITTED BY**

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**ASSIGNMENT-04**

## Question:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100cm send "alert" to IBM Cloud and display in device recent events.

Upload document with wokwi share link and images of IBM Cloud.

## Solution:

```
#include<WiFi.h>//libraryforwifi#include<PubSubClient.h>//libraryforMQTT

#defineECHO_GPIO12
#defineTRIGGER_GPIO13
#defineMAX_DISTANCE_CM100//Maximumof5meters#include"Ultrasonic.h"

Ultrasonicultrasonic(13,12);intdistance;

voidcallback(char*subscribetopic,byte*payload,unsignedintpayloadLength);

//-----credentialsofIBMAccounts-----

#defineORG"dv1snq"//IBMORGANIZATIONID
#defineDEVICE_TYPE"ESP32"//DevicetypementionedinibmwatsonIOTPlatform#defineDEVICE_ID "12345"//Device ID mentioned in ibm watson IOT Platform#defineTOKEN"45682367915" //Token
Stringdata3;floatt;

//-----Customisetheabovevalues-----
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event perform and format in which data to be send
char subscribetopic[]="iot-2/cmd/command/fmt/String";//cmdREPRESENT command type AND COMMAND IS TEST OF FORMAT STRING
```

```

char authMethod[] = "use-token-auth";// authentication
methodchar token[]=TOKEN;
char clientId[]="d:ORG":"DEVICE_TYPE ":"DEVICE_ID";//clientid

//-----
WiFiClient wifiClient; // creating the instance for
wificlientPubSubClient client(server, 1883, callback ,wifiClient);
//calling the predefined client id by passing parameter like server
id,port and wificredential

void setup()//configureing the ESP32
{
    Serial.begin(115200);
    delay(10);Serial.println();
    wifiConnect();
    mqttConnect();
}

void loop()//RecursiveFunction
{
    distance =
    ultrasonic.read(CM);if(distance
    <100){Serial.print("Distance in
    CM:
    ");Serial.println(distance);PublishData(distance);delay(1000);
    if (!client.loop())
        {mqttConnect();
        }

    }

    delay(1000);

}

/*.....retrievingto
Cloud. .... */

void PublishData(float temp)
{mqttConnect();//function call for connecting to ibm
/*
    creating the String in inform JS ontoupdate the data to ibmcloud
    */
    String payload="{\"AlertDistance:\":\"";

```

```

payload +=
temp;payload+="}
";

Serial.print("Sendingpayload:");
Serial.println(payload);

if(client.publish(publishTopic,(char*)payload.c_str())){
    Serial.println("Publish ok");// if it successfully upload data on the
cloudthen it will print publish ok in Serial monitor or else it will print
publishfailed
}else{
    Serial.println("Publishfailed");
}
}

voidmqttconnect(){
    if (!client.connected())
    {Serial.print("Reconnecting client to
");Serial.println(server);
    while(!!!client.connect(clientId,authMethod,token)){
        Serial.print(".");
        delay(500);
    }

    initManagedDevice();
    Serial.println();
}
}

voidwificonnect();//functiondefinationforwificonnect
{
    Serial.println();Serial.print("Co
nnectingto");

    WiFi.begin("Wokwi-
GUEST","",6);//passingthewificredentialstoestablishtheconnection
    while (WiFi.status() != WL_CONNECTED)
    {delay(500);
        Serial.print(".");
    }
    Serial.println("");Serial.println
("WiFi
connected");Serial.println("IP
address:
");Serial.println(WiFi.localIP())
;
}

```

```

void initManagedDevice(){
    if (client.subscribe(subscribetopic))
        {Serial.println((subscribetopic));Serial.println("subscribetocmdOK");}
    else{
        Serial.println("subscribetocmdFAILED");
    }
}

void callback(char*subscribetopic,byte*payload,unsigned intpayloadLength)
{
    Serial.print("callbackinvokedfortopic:");
    Serial.println(subscribetopic);
    for(int i=0;i<payloadLength;i++){
        //Serial.print((char)payload[i]);data
        3+= (char)payload[i];
    }
    Serial.println("data:"+data3);if
    (data3=="lighton")
    {
        Serial.println(data3);
    }
    else
    {
        Serial.println(data3);
    }
    data3="";
}

```

**Wokwi**

**link:**<https://wokwi.com/projects/346659959540286034>

WOKWI

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Docs

sketch.ino

diagram.json

libraries.txt

Ultrasonic.h

Ultrasonic.cpp

Library Manager

callback

1 of 4

Simulation

▶

⏏

⋮

```

1 #include <WiFi.h> //library for wifi
2 #include <PubSubClient.h> //library for MQTT
3
4 #define ECHO_GPIO 12
5 #define TRIGGER_GPIO 13
6 #define MAX_DISTANCE_CM 100 // Maximum of 5 meters
7 #include "Ultrasonic.h"
8
9 Ultrasonic ultrasonic(13, 12);
10 int distance;
11
12 void callback(char* subscribtopic, byte* payload, unsigned int payloadlength);
13
14 //-----credentials of IBM Accounts-----
15
16 #define ORG "dvisng" //IBM ORGANIZATION ID
17 #define DEVICE_TYPE "ESP32" //Device type mentioned in ibm watson IOT Platform
18 #define DEVICE_ID "12345" //Device ID mentioned in ibm watson IOT Platform
19 #define TOKEN "45682367915" //Token
20 String data3;
21 float h, t;
22
23 //----- Customise the above values -----
24
25 char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; // Server Name
26 char publishTopic[] = "iot-2/evt/data/fmt/json"; // topic name and type of event perform
27 char subscribtopic[] = "iot-2/cmd/command/fmt/String"; // cmd REPRESENT command type AND
28 char authMethod[] = "use-token-auth"; // authentication method
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30 char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID; //client id
31

```

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```

Distance: 59cm

Distance in CM: 62

Sending payload: {"Alert Distance":62.00}

Publish ok

Distance in CM: 62

Sending payload: {"Alert Distance":62.00}

Publish ok

IBM Watson IoT Platform

2019504510@smarterintez.com

ID: dv1snq

Browse

Action

Device Types

Interfaces

Add Device

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
Data	{"Alert Distance":62}	json	a few seconds ago
Data	{"Alert Distance":62}	json	a few seconds ago
Data	{"Alert Distance":62}	json	a few seconds ago
Data	{"Alert Distance":62}	json	a few seconds ago
Data	{"Alert Distance":62}	json	a few seconds ago

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WOKWI

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Docs

sketch.ino diagram.json libraries.txt Ultrasonic.h Ultrasonic.cpp Library Manager

> callback Aa Alt 7 of 4

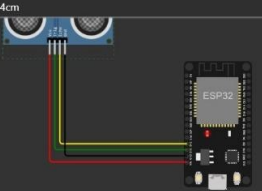
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```

Simulation

00:39:161 100%

Editing Ultrasonic Distance Sensor

Distance: 124cm



Publish ok

Distance in CM: 56

Sending payload: {"Alert Distance":"56.00"}

Publish ok

Distance in CM: 56

Sending payload: {"Alert Distance":"56.00"}

Publish ok