

## Assignment-4

Write code and connections in wokwi for ultra sonic sensor. When ever distance is less than 100 cm send "alert" to IBM cloud and display in device recent events

Date	22-10-2022
Team ID	PNT2022TMID02550
Project Name	Project: Smart Waste management System for Metropolitan Cities
Maximum Marks	2 Marks

### CODE:

```
#include <WiFi.h>
#include <PubSubClient.h>
#include <ArduinoJson.h>
WiFiClient wifiClient;
#define ORG "nafgr4"
#define DEVICE_TYPE "RaspberryPi"
#define DEVICE_ID "12345"
#define TOKEN "12345678"
#define speed 0.034
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/status1/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin=5;
const int echopin=19;
String command;
String data="";
String name="Alert";
String icon="";
long duration;
int dist;
void setup()
{
  Serial.begin(115200);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect();
  mqttConnect();
```

```

}
void loop() {
publishData();
delay(500);
if (!client.loop()) {
mqttConnect();
}
}
void wifiConnect() {
Serial.print("Connecting to ");
Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED) {
delay(500);
Serial.print(".");
}
Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}
void mqttConnect() {
if (!client.connected()) {
Serial.print("Reconnecting MQTT client to "); Serial.println(server);
while (!client.connect(clientId, authMethod, token)) {
Serial.print(".");
Serial.print("*");
delay(1000);
}
initManagedDevice();
Serial.println();
}
}
void initManagedDevice() {
if (client.subscribe(topic)) {
Serial.println(client.subscribe(topic));
Serial.println("subscribe to cmd OK");
}
else {
Serial.println("subscribe to cmd FAILED");
}
}
void publishData()
{
digitalWrite(trigpin, LOW);
digitalWrite(trigpin, HIGH);
delayMicroseconds(10);
digitalWrite(trigpin, LOW);
duration=pulseIn(echopin, HIGH);
dist=duration*speed/2;
if(dist<100){

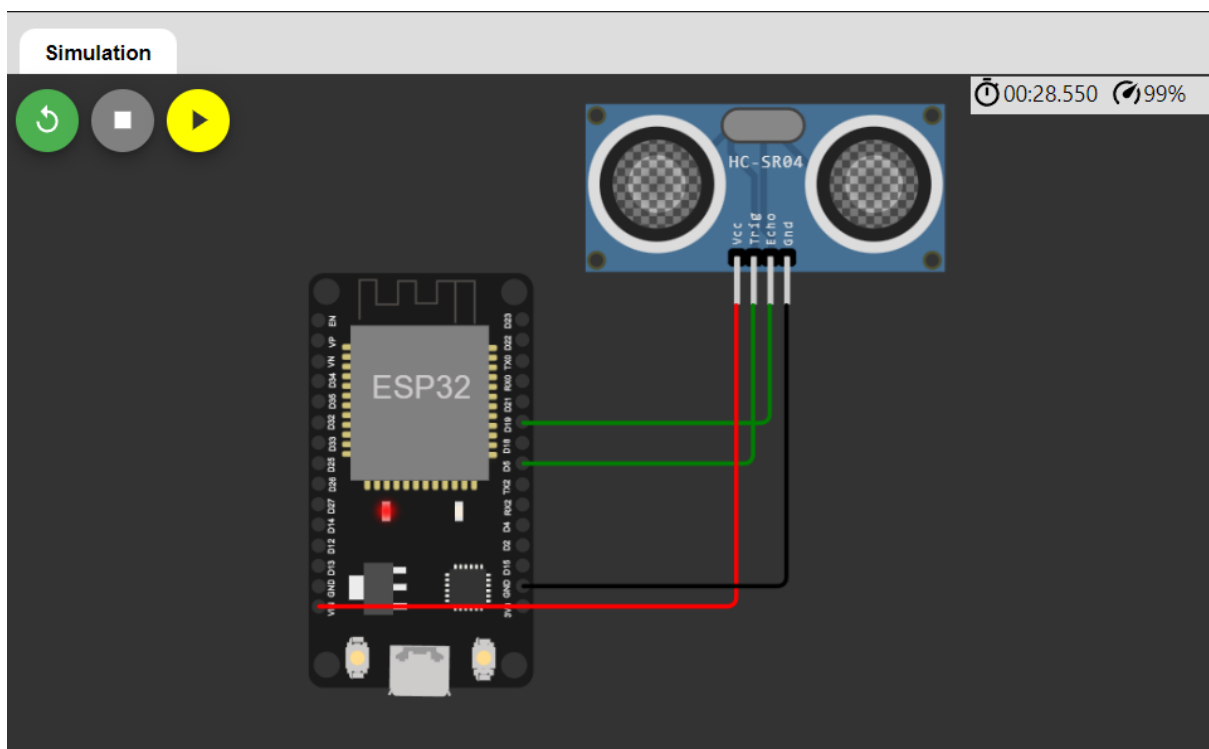
```

```

icon="Crashed";
}
else{
icon="Not-Crashed";
}
DynamicJsonDocument doc(1024);
String payload;
doc["Alert"]=name;
doc["Impact"]=icon;
doc["Distance"]=dist;
serializeJson(doc, payload);
delay(3000);
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish OK");
}
else {
Serial.println("Publish FAILED");
}
}
}

```

## CIRCUIT



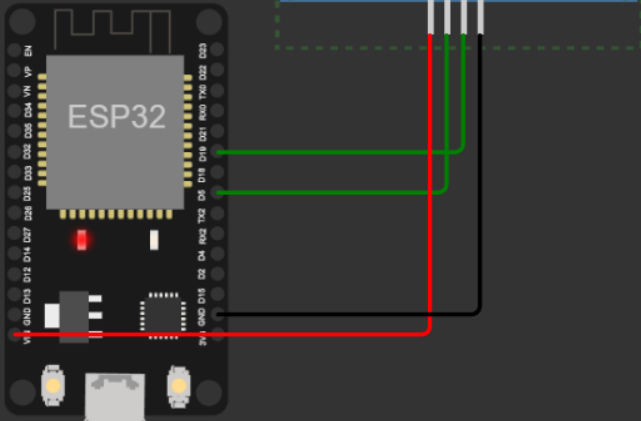
## OUTPUT

Simulation

00:08.266 100%

Editing Ultrasonic Distance Sensor

Distance: 14cm



Reconnecting MQTT client to nafgr4.messaging.internetofthings.ibmcloud.com

1

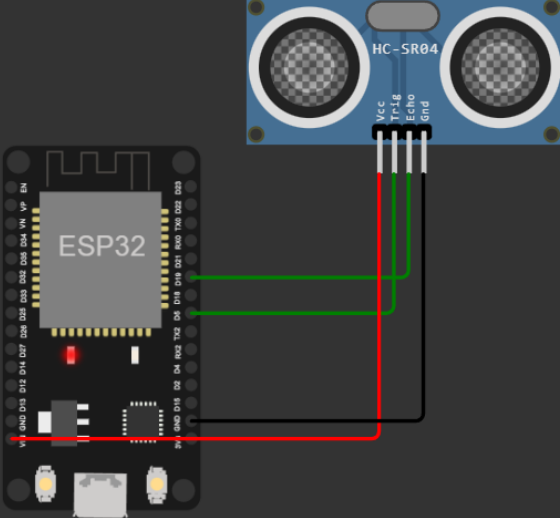
subscribe to cmd OK

Sending payload: {"Alert":"Alert","Impact":"Crashed","Distance":13}

Publish OK

Simulation

00:07.182 100%



The diagram shows an ESP32 microcontroller board connected to an HC-SR04 ultrasonic sensor. The sensor's VCC pin is connected to the ESP32's VCC pin (red wire), its Trig pin is connected to the ESP32's D4 pin (green wire), and its Echo pin is connected to the ESP32's D5 pin (green wire). The sensor's GND pin is connected to the ESP32's GND pin (black wire).

Reconnecting MQTT client to nafgr4.messaging.internetofthings.ibmcloud.com

1

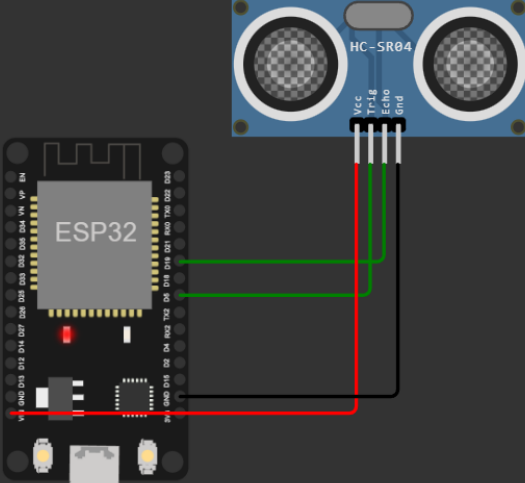
subscribe to cmd OK

Sending payload: {"Alert":"Alert","Impact":"Not-Crashed","Distance":239}

Publish OK

Simulation

00:16.549 103%



The diagram shows an ESP32 microcontroller board connected to an HC-SR04 ultrasonic sensor. The sensor's VCC pin is connected to the ESP32's VCC pin (red wire), its Trig pin is connected to the ESP32's D4 pin (green wire), and its Echo pin is connected to the ESP32's D5 pin (green wire). The sensor's GND pin is connected to the ESP32's GND pin (black wire).

Reconnecting MQTT client to nafgr4.messaging.internetofthings.ibmcloud.com

1

subscribe to cmd OK

Sending payload: {"Alert":"Alert","Impact":"Not-Crashed","Distance":399}

Publish OK

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Sending payload: {"Alert":"Alert","Impact":"Not-Crashed","Distance":399}  
Publish OK

Sending payload: {"Alert":"Alert","Impact":"Not-Crashed","Distance":399}  
Publish OK

Sending payload: {"Alert":"Alert","Impact":"Crashed","Distance":23}  
Publish OK

Sending payload: {"Alert":"Alert","Impact":"Crashed","Distance":10}  
Publish OK

Sending payload: {"Alert":"Alert","Impact":"Crashed","Distance":13}  
Publish OK

Sending payload: {"Alert":"Alert","Impact":"Crashed","Distance":13}  
Publish OK

Sending payload: {"Alert":"Alert","Impact":"Crashed","Distance":13}  
Publish OK

Sending payload: {"Alert":"Alert","Impact":"Not-Crashed","Distance":247}  
Publish OK

BrowseActionDevice TypesInterfaces

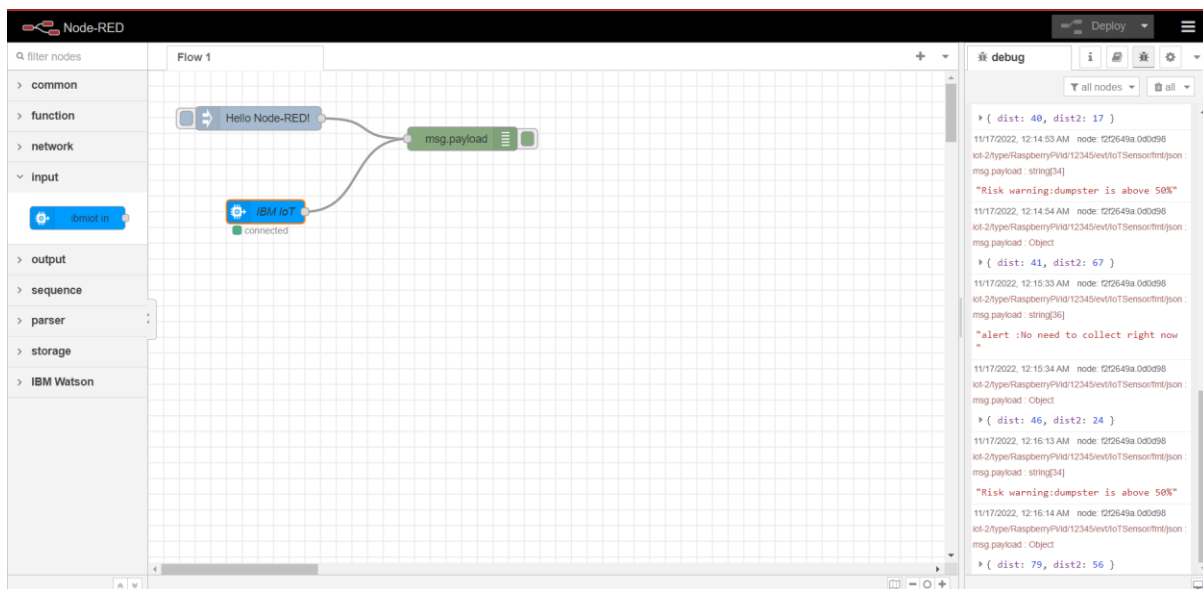
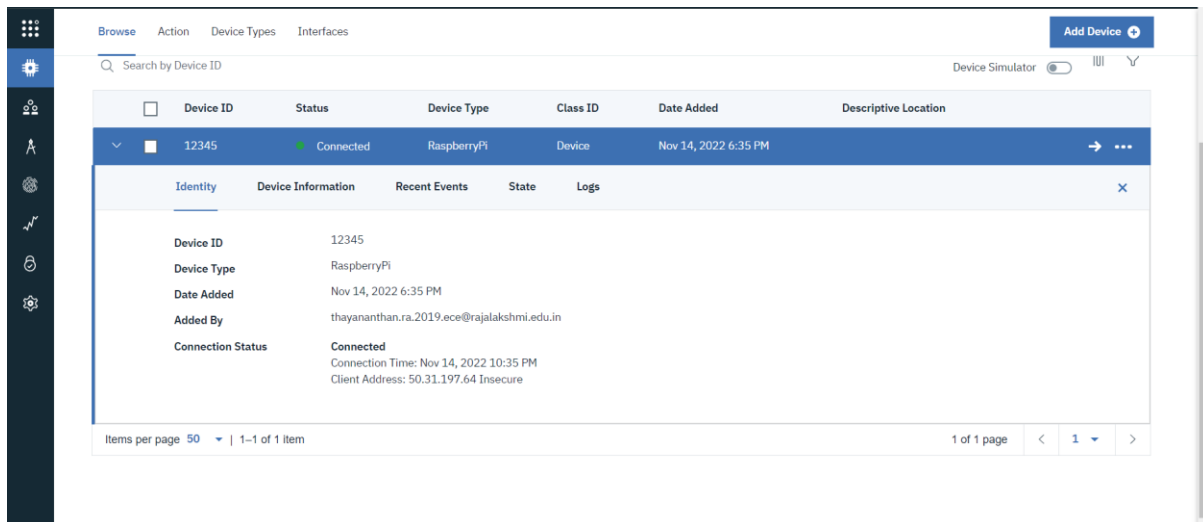
Add Device

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
status1	{"Alert":"Alert","Impact":"Not-Crashed","Distanc...	json	a few seconds ago
status1	{"Alert":"Alert","Impact":"Crashed","Distance":13}	json	a few seconds ago
status1	{"Alert":"Alert","Impact":"Crashed","Distance":13}	json	a few seconds ago
status1	{"Alert":"Alert","Impact":"Crashed","Distance":13}	json	a few seconds ago
status1	{"Alert":"Alert","Impact":"Crashed","Distance":10}	json	a few seconds ago

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Link:

<https://wokwi.com/projects/348322336437437012>