

## **ASSIGNMENT 4**

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Write code and connections in wokwi for the ultrasonic sensor.

Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.

Upload document with wokwi share link and images of IBM cloud

### **CODE:**

```
#include <WiFi.h>

#include <PubSubClient.h>

void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);

//-----credentials of IBM Accounts-----

#define ORG "g20wc1"//IBM ORGANITION ID

#define DEVICE_TYPE "h1"//Device type mentioned in ibm watson IOT Platform

#define DEVICE_ID "h1"//Device ID mentioned in ibm watson IOT Platform

#define TOKEN "12345678"//Token

String data3;

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";

char publishTopic[] = "iot-2/evt/Data/fmt/json";

char subscribetopic[] = "iot-2/cmd/test/fmt/String";

char authMethod[] = "use-token-auth";

char token[] = TOKEN;

char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;

WiFiClient wifiClient;

PubSubClient client(server, 1883, callback ,wifiClient);

const int trigPin = 5;

const int echoPin = 18;
```

```
#define SOUND_SPEED 0.034

long duration;
float distance;

void setup() {
  Serial.begin(115200);
  pinMode(trigPin, OUTPUT);
  pinMode(echoPin, INPUT);
  wificonnect();
  mqttconnect();
}

void loop()
{
  digitalWrite(trigPin, LOW);
  delayMicroseconds(2);
  digitalWrite(trigPin, HIGH);
  delayMicroseconds(10);
  digitalWrite(trigPin, LOW);
  duration = pulseIn(echoPin, HIGH);
  distance = duration * SOUND_SPEED/2;
  Serial.print("Distance (cm): ");
  Serial.println(distance);
  if(distance<100)
  {
    Serial.println("ALERT!!");
    delay(1000);
    PublishData(distance);
    delay(1000);
    if (!client.loop()) {
      mqttconnect();
    }
  }
}
```

```

delay(1000);
}
void PublishData(float dist) {
  mqttconnect();
  String payload = "{\"Distance\": ";
  payload += dist;
  payload += ", \"ALERT!!\": \"<100cm\"";
  payload += "}";
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");
  } else {
    Serial.println("Publish failed");
  }
}

void mqttconnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    }
    initManagedDevice();
    Serial.println();
  }
}

void wificonnect()
{
  Serial.println();

```

```

Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED) {
  delay(500);
  Serial.print(".");
}
Serial.println("");
Serial.println("WiFi connected");
Serial.println("IP address: ");
Serial.println(WiFi.localIP());
}

void initManagedDevice() {
  if (client.subscribe(subscribetopic)) {
    Serial.println(subscribetopic);
    Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}

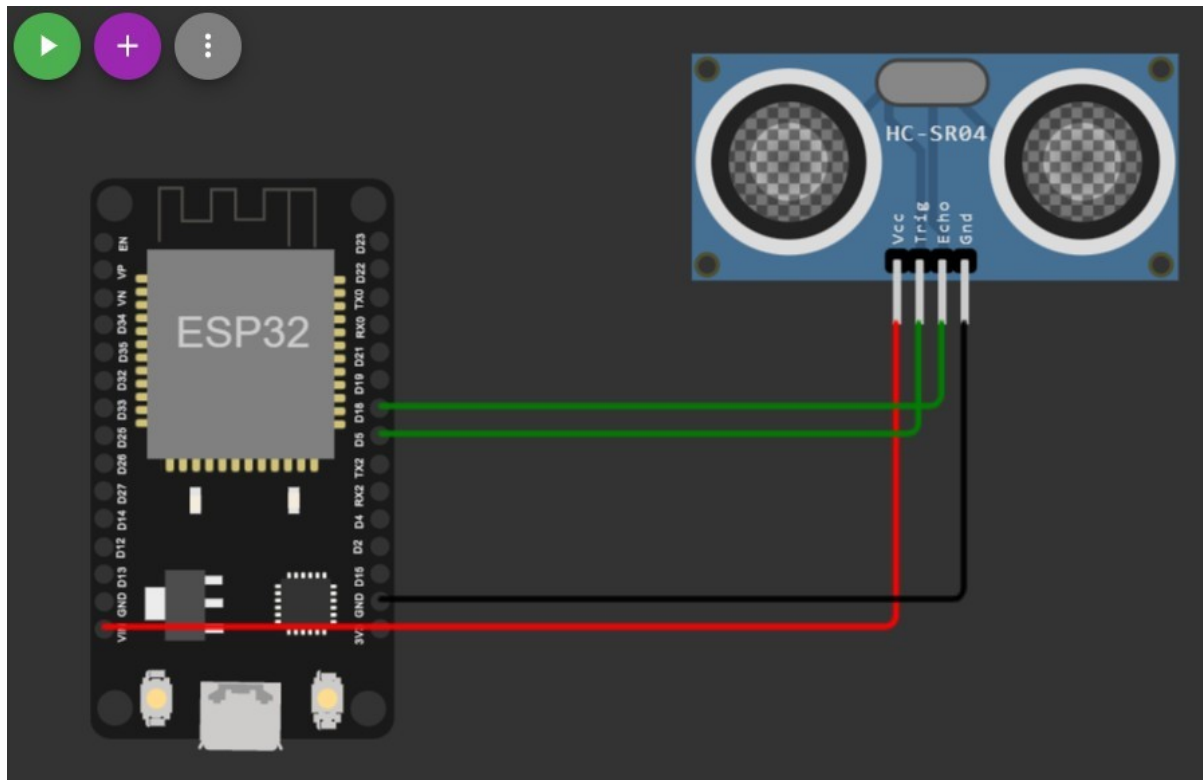
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{
  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {
    data3 += (char)payload[i];
  }
  Serial.println("data: "+ data3);
  data3="";
}

```

## WOKWI URL

<https://wokwi.com/projects/348418351199945299>

## CIRCUIT DIAGRAM



## OUTPUT

```
Distance (cm): 30.96
ALERT!!
Sending payload: {"Distance":30.96,"ALERT!!":"<100cm"}
Publish ok
Distance (cm): 81.97
ALERT!!
Sending payload: {"Distance":81.97,"ALERT!!":"<100cm"}
Publish ok
```

CLOUD OUTPUT

Event	Value	Format	Last Received
Data	{"Distance":22.95,"ALERT!!":"<100cm"}	json	a few seconds ago
Data	{"Distance":27.98,"ALERT!!":"<100cm"}	json	a few seconds ago
Data	{"Distance":81.97,"ALERT!!":"<100cm"}	json	a few seconds ago
Data	{"Distance":81.97,"ALERT!!":"<100cm"}	json	a few seconds ago
Data	{"Distance":30.96,"ALERT!!":"<100cm"}	json	a few seconds ago