## Project Design Phase-I Proposed Solution Document

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Date	04 OCTOBER 2022
Team ID	PNT2022TMID15746
Project Name	IOT BASED CROP PROTECTION SYSTEM FOR
	AGRICULTURE
Maximum Marks	2 Marks

C N -	Danamatan	Description
S.No.	Parameter	Description
1.	Problem Statement (Problem to be solved)	<ul> <li>Crops are not irrigated properly due to insufficient labour forces.</li> <li>Improper maintenance of crops against various environmental factors such as temperature climate, topography and soil quality which results in crop destruction.</li> <li>Lack of knowledge among farmers in usage of fertilizers and hence crops are affected due to high ammonia, urea, potassium and high PH level fertilizers.</li> <li>Requires protecting crops from Wild animals attacks, birds and pests.</li> </ul>
2.	Idea / Solution description	<ul> <li>Moisture sensor is interfaced with Arduino Microcontroller to measure the moisture level in soil and relay is used to turn ON and OFF the motor pump for managing the excess water level. It will be updated to authorities through IOT.</li> <li>Temperature sensor connected to microcontroller is used to monitor the temperature in the field. The optimum temperature required for crop cultivation is maintained using sprinklers.</li> <li>IOT based fertilizing methods are followed, to minimize the negative effects on growth of crops while using fertilizers.</li> <li>Image processing techniques with IOT is followed for crop protection against animal attacks.</li> </ul>
3.	Novelty / Uniqueness	Automatic crop maintenance and protection using embedded and IOT technology.
4.	Social Impact / Customer Satisfaction	This proposed system provides many facilities which helps the farmers to maintain the crop field without much loss.
5.	Business Model (Revenue Model)	This prototype can be developed as product with minimum cost with high performance.
6.	Scalability of the Solution	This can be developed to a scalable product by using sensors and transmitting the data through Wireless Sensor Network and Analysing the data in cloud and operation is performed using robots