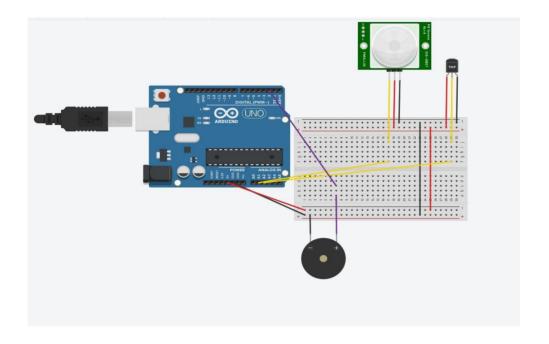
## **ASSIGNMENT\_1**



```
int Buzzer= 2;
int Temperature_sensor= A2;
int PIR= A1;
int val1= 0;
int val2= 0;

void setup() {

pinMode(Buzzer, OUTPUT);
pinMode(FIR, INFUT);
serial.begin(9600);

void loop() {

val1 = analogRead(PIR);
val2 = analogRead(Temperature_sensor);
float temp = ( val2/1024.0)*5000;
float cel = temp/10;
if(val1 == HIGH)

digitalWrite(Buzzer, HIGH);
}
digitalWrite(Buzzer, HIGH);
}
digitalWrite(Buzzer, LOW);
digitalWrite(Buzzer, LOW);
}
Serial Monitor
```

## **CODE**:

```
int Buzzer= 2;
int Temperature_sensor= A2;
int PIR= A1;
int val1= 0;
int val2= 0;
void setup() {
pinMode(Buzzer, OUTPUT);
pinMode(Temperature_sensor, INPUT);
pinMode(PIR, INPUT);
Serial.begin(9600);
}
void loop() {
val1 = analogRead(PIR);
val2 = analogRead(Temperature sensor);
float temp = (val2/1024.0)*5000;
float cel = temp/10;
if(val1 == HIGH)
{
 digitalWrite(Buzzer, HIGH);
}
else if(cel > 60)
{
 digitalWrite(Buzzer,HIGH);
}
else
```

```
{
  digitalWrite(Buzzer, LOW);
}
```