

PROJECT DEVELOPMENT PHASE

SPRINT 4

TEAM ID	PNT2022TMID18919
PROJECT NAME	IOT BASED SMART CROP PROTECTION SYSTEM FOR AGRICULTURE

STEP 1: First open python code and run code, this capture the image in video and identify which animal or object are captured.



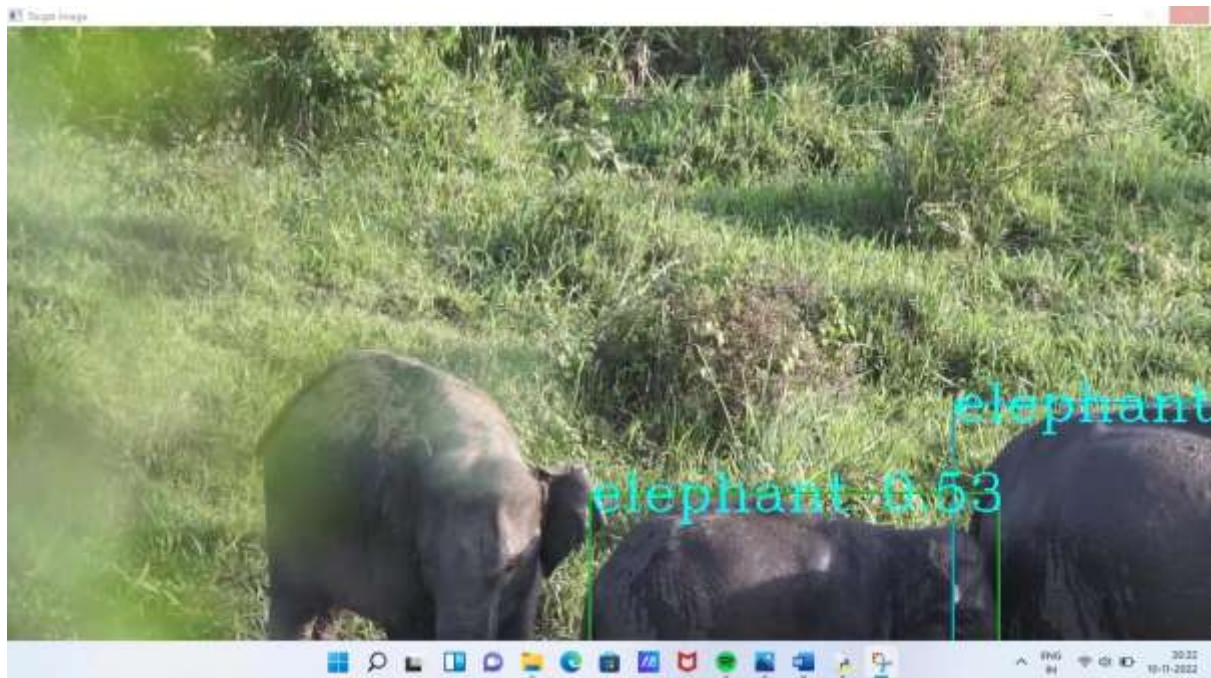
```
import cv2
import numpy as np

net=cv2.dnn.readNet('yolov3.weights','yolov3.cfg')
classes=[]
with open('coco.names','r') as f:
    classes=f.read().splitlines()
# import cv2.imread('elephant.jpg')
cap=cv2.VideoCapture('video.mp4')
# cap=cv2.VideoCapture('person.jpg')
# cap=cv2.VideoCapture(0)
while True:
    _,img=cap.read()
    height,width,_=img.shape
    blob=cv2.dnn.blobFromImage(img,1/255,(416,416),(0,0,0),swapRB=True,crop=False) #img, reduction the pixel size, size of the image, rgb colour
    net.setInput(blob)
    output_layer_names=net.getUnconnectedOutLayersNames()
    layerOutputs=net.forward(output_layer_names)
    boxes=[]
    confidences=[]
    class_ids=[]
    for output in layerOutputs:
        for detection in output:
            scores=detection[4:]
            class_id=np.argmax(scores)
            confidence=scores[class_id]
            if confidence>0.5:
                center_x=int(detection[0]*width)
                center_y=int(detection[1]*height)
                w=int(detection[2]*width)
                h=int(detection[3]*height)

                x1=int(center_x-w/2)
                y1=int(center_y-h/2)

                boxes.append([x1,y1,w,h])
                confidences.append(float(confidence))
                class_ids.append(class_id)
```

STEP 2: It shows the detected animal or object name which is represented by square with the name of the animal or object.



PYTHON CODE:

```
import cv2
import numpy as np

net=cv2.dnn.readNet('yolov3.weights','yolov3.cfg')
classes=[]
with open('coco.names','r') as f:
    classes=f.read().splitlines()
# img=cv2.imread('elephant.jpg')
cap=cv2.VideoCapture('video.mp4')
# cap=cv2.VideoCapture('person.jpg')
# cap=cv2.VideoCapture(0)
```

```
while True:
```

```
    _,img=cap.read()
```

```
    height,width,_=img.shape
```

```
    blob=cv2.dnn.blobFromImage(img,1/255,(416,416),(0,0,0),swapRB=True,crop
    =False) #(img,reduction the pixels size,size of the image,rgb colour)
```

```
    net.setInput(blob)
```

```
    output_layers_names=net.getUnconnectedOutLayersNames()
```

```
    layeroutput=net.forward(output_layers_names)
```

```
    boxes=[]
```

```
    confidences=[]
```

```
    class_ids=[]
```

```
    for output in layeroutput:
```

```
        for detection in output:
```

```
            scores=detection[5:]
```

```
            class_id=np.argmax(scores)
```

```
            confidence=scores[class_id]
```

```
            if confidence > 0.5:
```

```
                center_x=int(detection[0]*width)
```

```
                center_y =int(detection[1]*height)
```

```
                w=int(detection[2]*width)
```

```
                h=int(detection[3]*height)
```

```
                x=int(center_x - w/2)
```

```
                y=int(center_y - h/2)
```

```
                boxes.append([x,y,w,h])
```

```

        confidences.append((float(confidence)))
        class_ids.append(class_id)

indexes=cv2.dnn.NMSBoxes(boxes,confidences,0.5,0.4)
font=cv2.FONT_HERSHEY_COMPLEX
colors=np.random.uniform(0,255,size=(len(boxes),3))
for i in indexes.flatten():
    x,y,w,h=boxes[i]
    label=str(classes[class_ids[i]])
    confidence=str(round(confidences[i],2))
    color=colors[i]
    cv2.rectangle(img,(x,y),(x+w ,y+h),color,2)
    cv2.putText(img,label + " "+confidence,(x,y+20),font,2,(255,255,0),2)

cv2.imshow('Target Image',img)

key=cv2.waitKey(1)
if key ==ord('q'):
    break
cap.release()
# cv2.waitKey(0)
cv2.destroyAllWindows()

```