Name: VELMURUGAN R Rollno: 727719EUEC171

ASSIGNMENT 4-BUZZER FOR ULTRASONIC SENSOR

CODE:

```
void setup(){
      Serial.begin(9600);
      pinMode(2,OUTPUT);
      pinMode(3,INPUT);
      pinMode(12,OUTPUT);
void loop()
       digitalWrite(2,LOW);
       digitalWrite(2,HIGH);
       delayMicroseconds(10);
       digitalWrite(2,LOW);
      float dur=pulseIn(3,HIGH);
      float dis=(dur*0.0343)/2;
      Serial.print("Distance is: ");
      Serial.println(dis);
      if(dis > = 100){
              digitalWrite(8,HIGH);
              digitalWrite(7,HIGH);
      }
      if(dis > = 100){
              for(int i=0; i<=30000; i=i+10){
                      tone(12,i);
                       delay(1000);
                      noTone(12);
                      delay(1000);
              }
      }
```

OUTPUT:

