Date	18 NOV 2022
Team ID	PNT2022TMID46295
Project Name	Signs with smart connectivity for Better road safety

Sprint 03

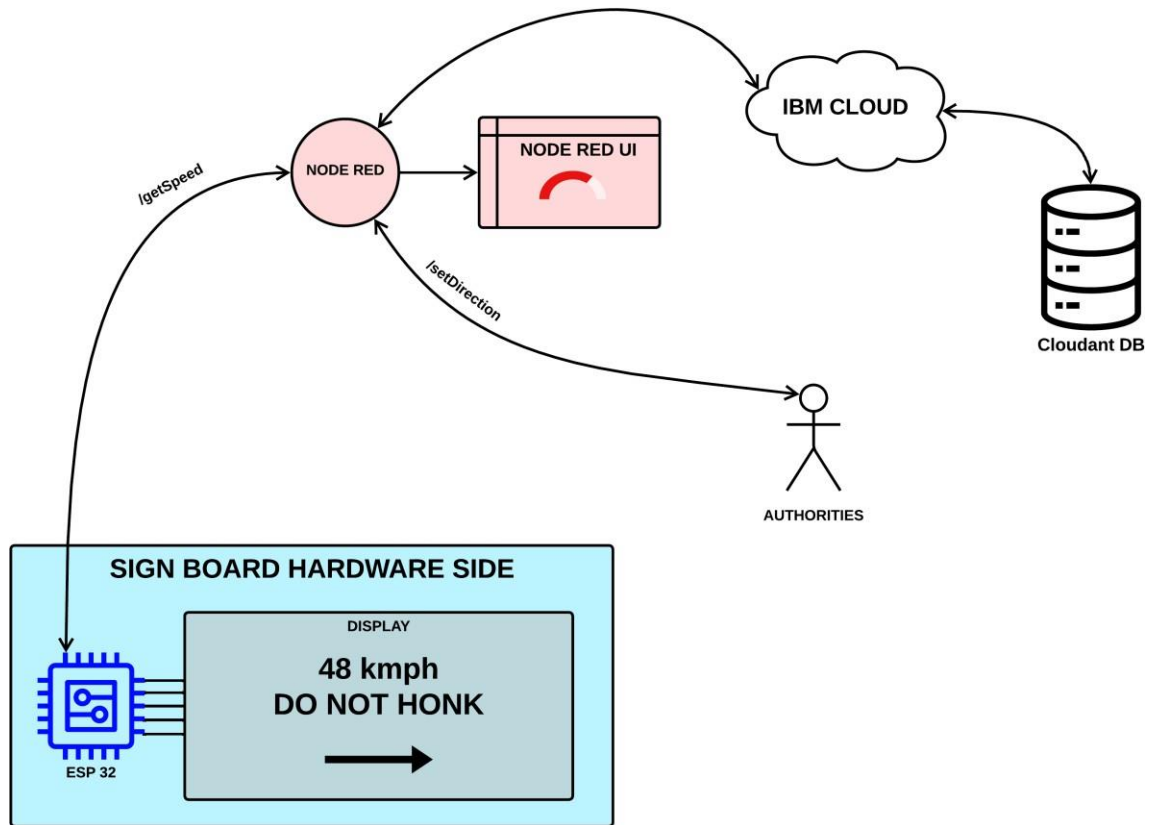**Signs with Smart Connectivity for Better Road Safety**

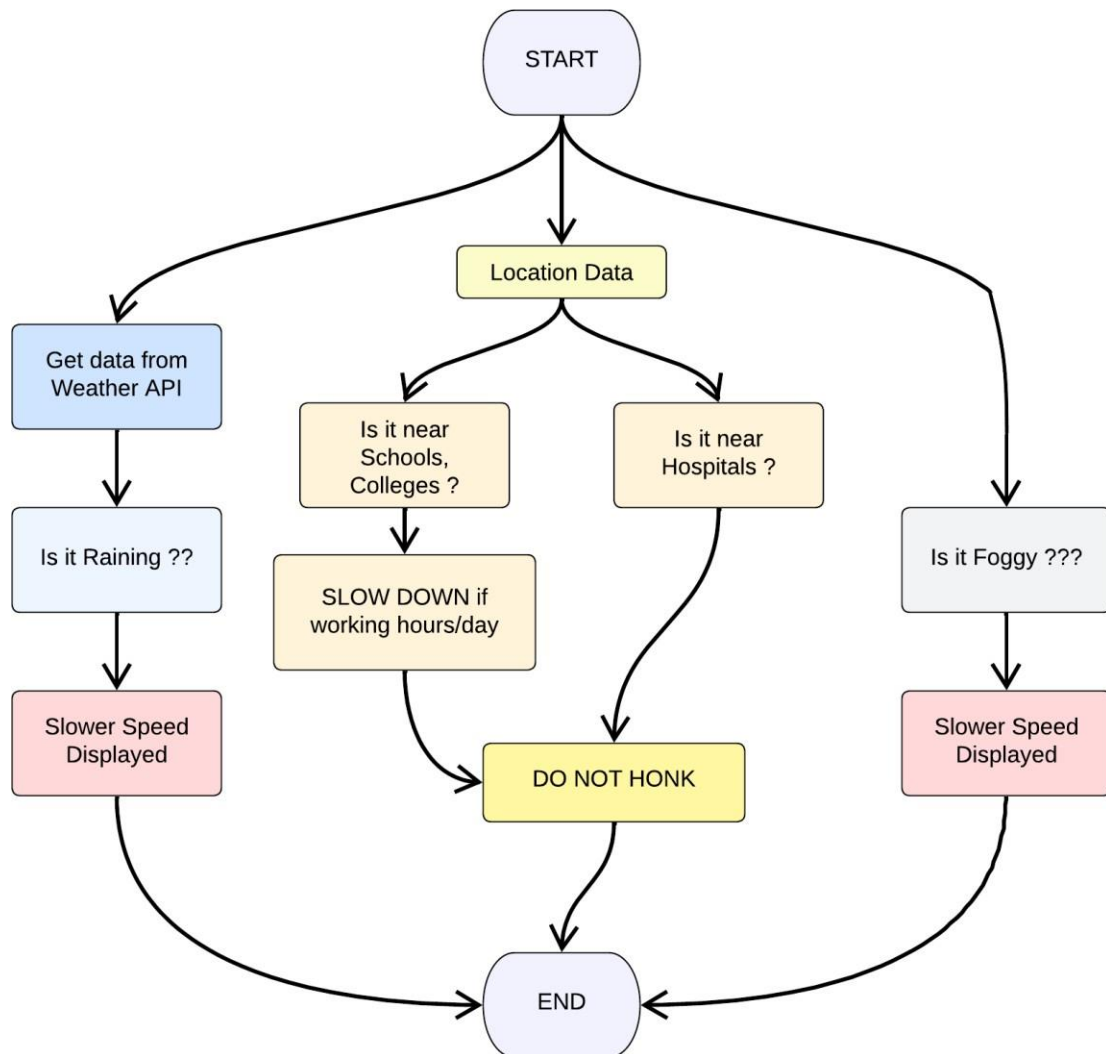**Team ID -** PNT2022TMID10531

Sprint Goals :
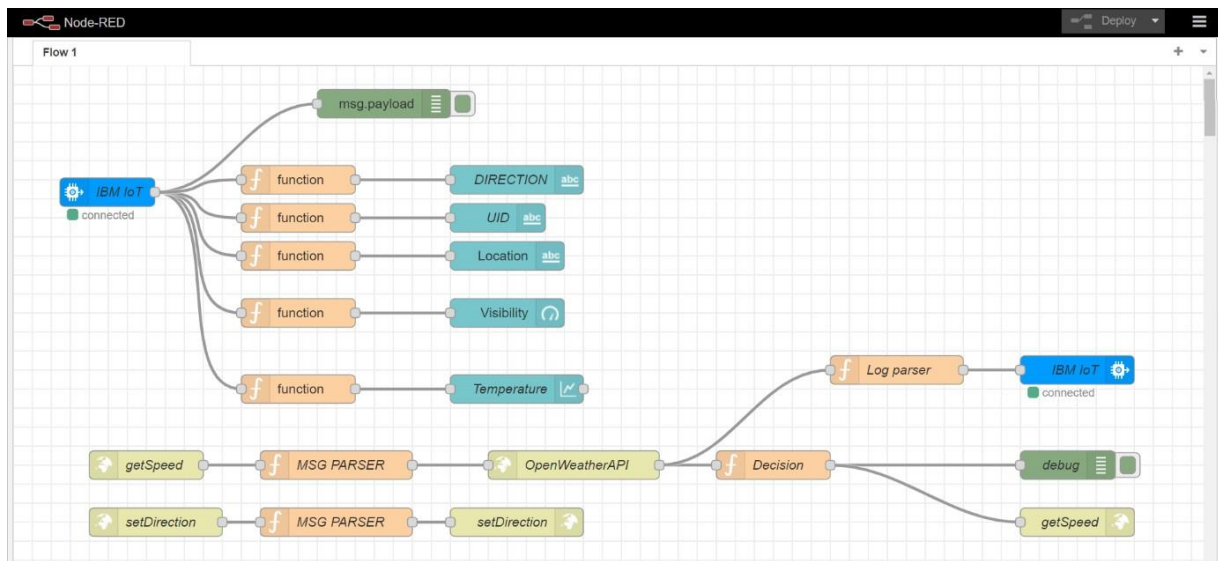
1. Hardware & Cloud integration

Process Flow :

NODE RED

/getSpeed

NODE RED UI

IBM CLOUD

Cloudant DB

/setDirection

AUTHORITIES

SIGN BOARD HARDWARE SIDE

DISPLAY

48 kmph
DO NOT HONK

ESP 32

Code Flow :

START

Location Data

Get data from
Weather API

Is it near
Schools,
Colleges ?

Is it near
Hospitals ?

Is it Foggy ???

Is it Raining ??

SLOW DOWN if
working hours/day

Slower Speed
Displayed
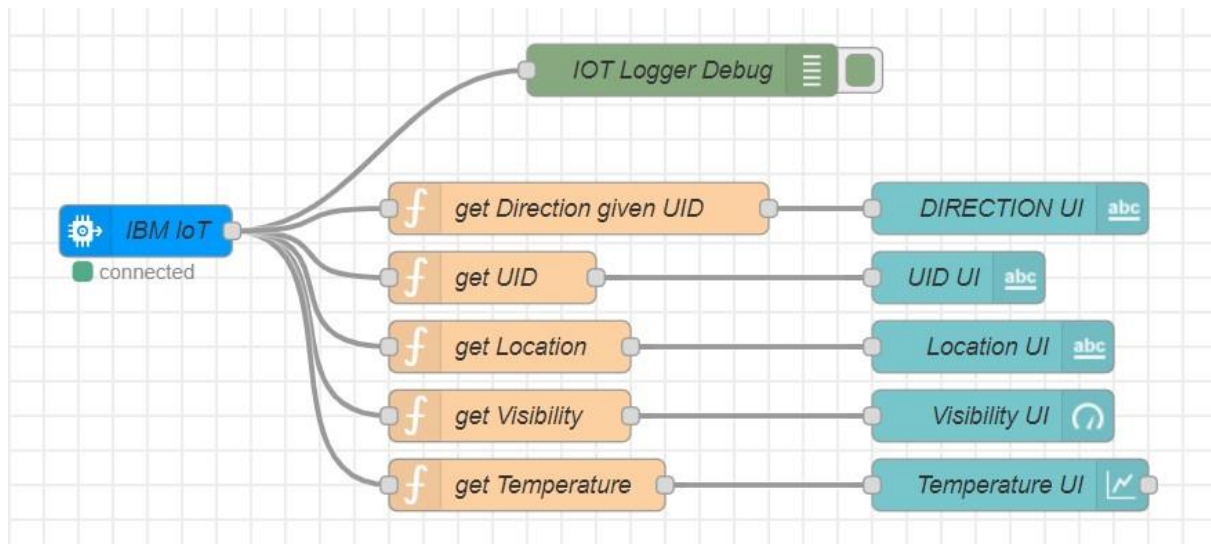
Slower Speed
Displayed

DO NOT HONK

END

Node RED :

Node RED flow :

There are 3 flows in the above Node RED flow. They are

1. Node RED UI flow
2. /getSpeed API flow
3. /setDirection API flow

1. Node RED UI flow :

1. **"IBM IOT"** node connects the backend to Node RED UI
2. The function nodes such as **"get Direction given UID"**, **"get UID"**, **"get Location"**, **"get Visibility"** & **"get Temperature"** extract the respective data out and provides them to the UI nodes **"Direction UI"**, **"UID UI"**, **"Location UI"**, **"Visibility UI"** & **"Temperature UI"**.

```
// get Direction given UID
msg.payload = global.get(String(msg.payload.uid));
return msg;

// get UID
msg.payload = msg.payload.uid;
return msg;

// get Location
msg.payload = msg.payload.location;
return msg;

// get Visibility
msg.payload = msg.payload.visibility;
return msg;

// get Temperature
msg.payload = msg.payload.temperature;
return msg;
```
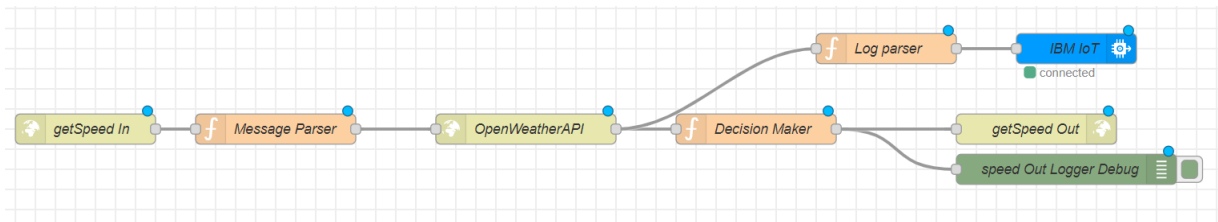
3. **"IOT Logger Debug"** node logs the data at debugger.

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2. /getSpeed API flow :

1. **"getSpeed In"** node is an http end point. It accepts parameters like microcontroller UID, location, school & hospital zones info.

2. **"Message Parser"** node parses the data and passes on only required information to the next node

```
global.set("data",msg.payload);

msg.payload.q = msg.payload.location;
msg.payload.appid = "bf4a8d480ee05c00952bf65b78ae826b";
return msg;
```

3. **"OpenWeatherAPI"** node is a http request node which calls the OpenWeather API and send the data to the next node.

4. **"Log Parser"** node extracts specific parameters from the weather data and and sends it to the next node.

```
weatherObj = JSON.parse(JSON.stringify(msg.payload));
localityObj = global.get("data");

var suggestedSpeedPercentage = 100;

var preciseObject = {
    temperature : weatherObj.main.temp - 273.15,
    location : localityObj.location,
    visibility : weatherObj.visibility/100,
    uid : localityObj.uid,
    direction : global.get("direction")
};

msg.payload = preciseObject;

return msg;
```

5. **"IBM IoT"** node here (IBM IoT OUT)connects the **"IBM IoT"** node (IBM IoT IN) metioned in the **Node RED UI flow** which enables UI updation and logging.

6. **"Decision Maker"** node processes the weather data and other information from the micro controller to form the string that is to be displayed at the Sign Board

```
weatherObj = JSON.parse(JSON.stringify(msg.payload));
localityObj = global.get("data");
```

```
var suggestedSpeedPercentage = 100;

var preciseObject = {
    temperature : weatherObj.main.temp - 273.15,
    weather : weatherObj.weather.map(x=>x.id).filter(code => code<700),
    visibility : weatherObj.visibility/100
};

if(preciseObject.visibility<=40)
    suggestedSpeedPercentage -=30

switch(String(preciseObject.weather)[-1]) // https://openweathermap.org/weather-
conditions refer weather codes meaning here
{
    case "0" : suggestedSpeedPercentage -=10;break;
    case "1" : suggestedSpeedPercentage -=20;break;
    case "2" : suggestedSpeedPercentage -=30;break;
}

msg.payload = preciseObject;

var doNotHonk = 0;
if(localityObj.hospitalZone=="1"||localityObj.schoolZone=="1")
    doNotHonk = 1;

var returnObject = {
    suggestedSpeed : localityObj.usualSpeedLimit*(suggestedSpeedPercentage/100),
    doNotHonk : doNotHonk
}

msg.payload = String(returnObject.suggestedSpeed) + " kmph \n\n" +
(returnObject.doNotHonk==1?"Do Not Honk":"") + "$" +
global.get(String(localityObj.uid));

return msg;
```
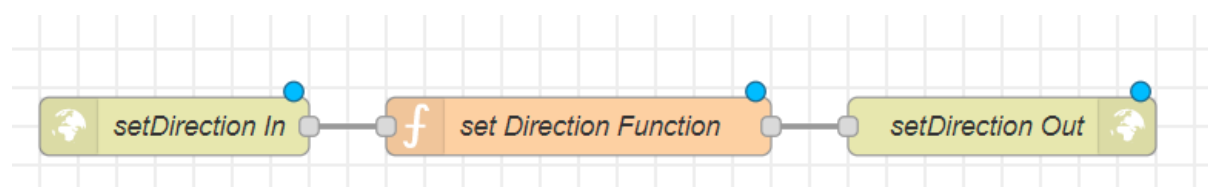
7. **"getSpeed Out"** node returns a http response for the request at
   node **"getSpeed In"**.

8. **"speed Out Logger Debug"** logs the data for debugging.

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3. /setDirection API flow :

1. **"setDirection In"** node is an http end point. It accepts parameters like
   microcontroller UID & direction.

2. **"set Direction Function"** node sets the direction for the given UID.

```
global.set(String(msg.payload.uid),msg.payload.dir);
return msg;
```

3. **"setDirection Out"** node returns a http response for the request at node **"setDirection In"**.

[Click on this link to change direction to Straight](#)

[Click on this link to change direction to Left](#)

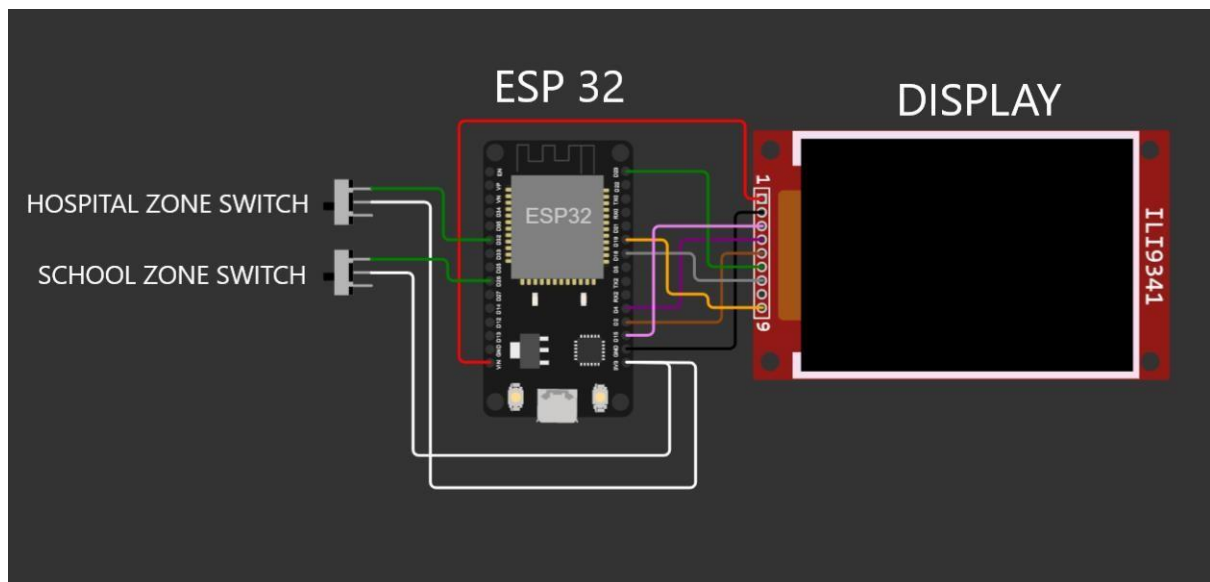[Click on this link to change direction to Right](#)

Wokwi Circuit :

[Wokwi Code](#)

[Wokwi Link](#)

Circuit Diagram :

ESP 32 CODE :

```
#include <WiFi.h>
#include <HTTPClient.h>
#include <Adafruit_GFX.h>
#include <Adafruit_ILI9341.h>
#include <string.h>
```

```
const char* ssid = "Wokwi-GUEST";
const char* password = "";

#define TFT_DC 2
#define TFT_CS 15
Adafruit_ILI9341 tft = Adafruit_ILI9341(TFT_CS, TFT_DC);

String myLocation = "Chennai,IN";
String usualSpeedLimit = "70"; // kmph

int schoolZone = 32;
int hospitalZone = 26;

int uid = 2504; // ID Unique to this Micro Contoller

String getString(char x)
{
    String s(1, x);
    return s;
}

String stringSplitter1(String fullString,char delimiter='$')
{
    String returnString = "";
    for(int i = 0; i<fullString.length();i++) {
        char c = fullString[i];
        if(delimiter==c)
            break;
        returnString+=String(c);
    }
    return(returnString);
}

String stringSplitter2(String fullString,char delimiter='$')
{
    String returnString = "";
    bool flag = false;
    for(int i = 0; i<fullString.length();i++) {
        char c = fullString[i];
        if(flag)
            returnString+=String(c);
        if(delimiter==c)
            flag = true;
    }
    return(returnString);
}

void rightArrow()
{
  int refX = 50;
  int refY = tft.getCursorY() + 40;

  tft.fillRect(refX,refY,100,20,ILI9341_RED);
  tft.fillTriangle(refX+100,refY-
30,refX+100,refY+50,refX+40+100,refY+10,ILI9341_RED);
}

void leftArrow()
{
```

```
    int refX = 50;
    int refY = tft.getCursorY() + 40;

    tft.fillRect(refX+40,refY,100,20,ILI9341_RED);
    tft.fillTriangle(refX+40,refY-30,refX+40,refY+50,refX,refY+10,ILI9341_RED);
}

void upArrow()
{
    int refX = 125;
    int refY = tft.getCursorY() + 30;

    tft.fillTriangle(refX-40,refY+40,refX+40,refY+40,refX,refY,ILI9341_RED);
    tft.fillRect(refX-15,refY+40,30,20,ILI9341_RED);
}

String APICall() {
    HTTPClient http;

    String url = "https://node-red-grseb-2022-11-05-test.eu-
gb.mybluemix.net/getSpeed?";
    url += "location="+myLocation+"&";
    url += "schoolZone="+(String)digitalRead(schoolZone)+(String)"&";
    url += "hospitalZone="+(String)digitalRead(hospitalZone)+(String)"&";
    url += "usualSpeedLimit="+(String)usualSpeedLimit+(String)"&";
    url += "uid="+(String)uid;
    http.begin(url.c_str());
    int httpResponseCode = http.GET();

    if (httpResponseCode>0) {
      String payload = http.getString();
      http.end();
      return(payload);
    }
    else {
      Serial.print("Error code: ");
      Serial.println(httpResponseCode);
    }
    http.end();
}

void myPrint(String contents) {
    tft.fillScreen(ILI9341_BLACK);
    tft.setCursor(0, 20);
    tft.setTextSize(4);
    tft.setTextColor(ILI9341_RED);
    //tft.println(contents);

    tft.println(stringSplitter1(contents));
    String c2 = stringSplitter2(contents);
    if(c2=="s") // represents Straight
    {
      upArrow();
    }
    if(c2=="l") // represents left
    {
      leftArrow();
    }
    if(c2=="r") // represents right
```

```
  {
    rightArrow();
  }
}

void setup() {
  WiFi.begin(ssid, password, 6);

  tft.begin();
  tft.setRotation(1);

  tft.setTextColor(ILI9341_WHITE);
  tft.setTextSize(2);
  tft.print("Connecting to WiFi");

  while (WiFi.status() != WL_CONNECTED) {
    delay(100);
    tft.print(".");
  }

  tft.print("\nOK! IP=");
  tft.println(WiFi.localIP());
}

void loop() {
  myPrint(APICall());
  delay(100);
}
```
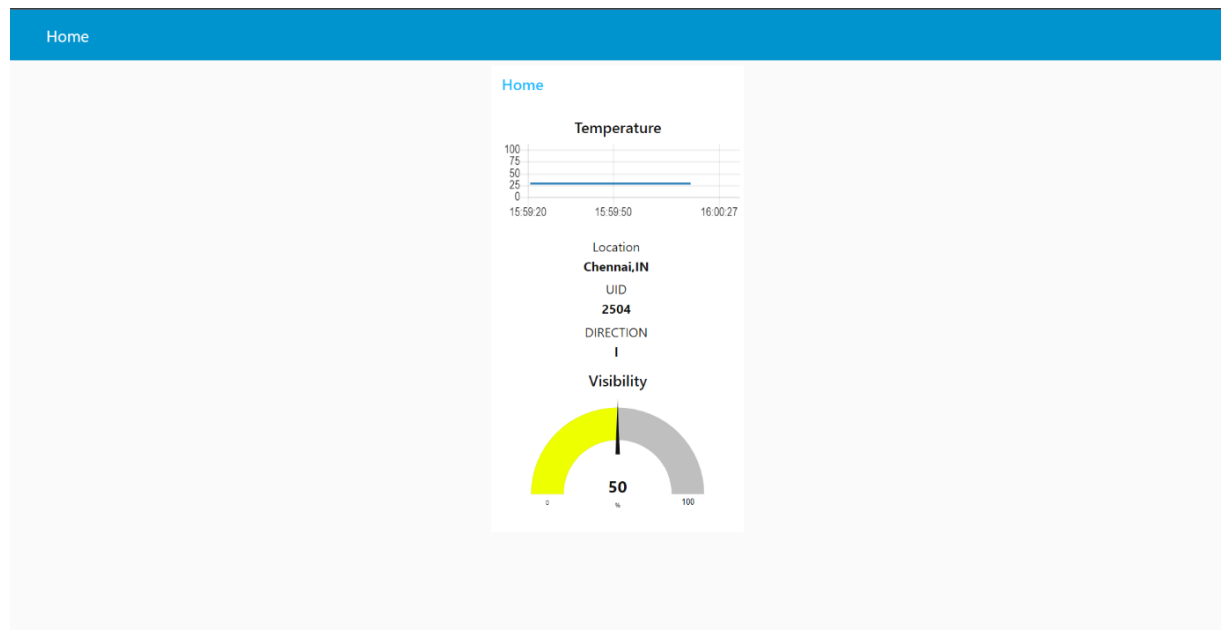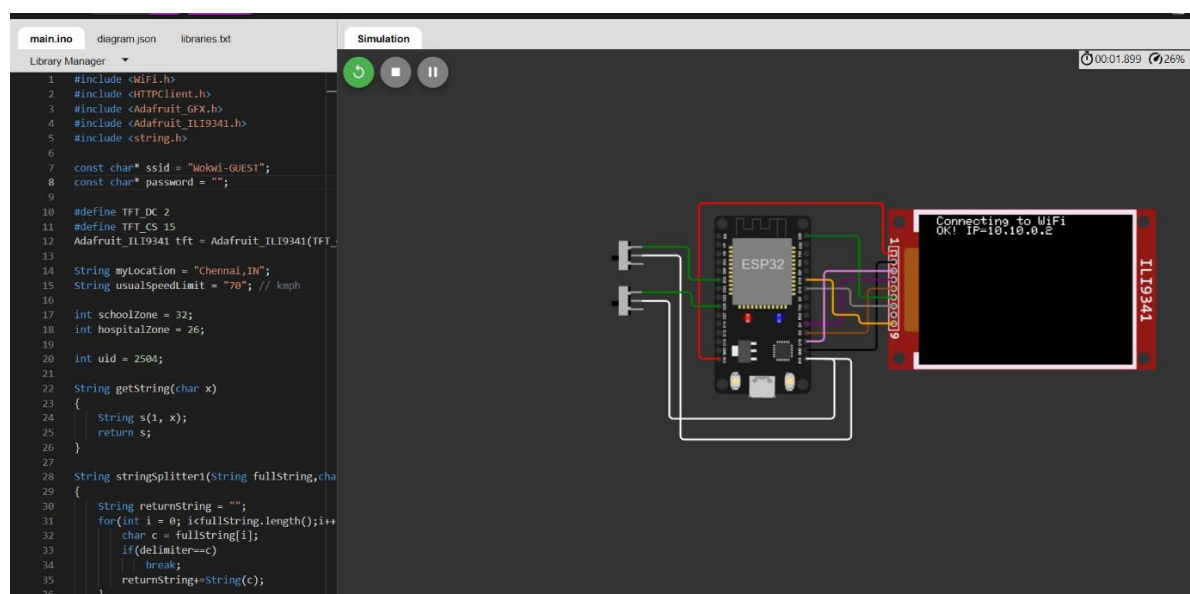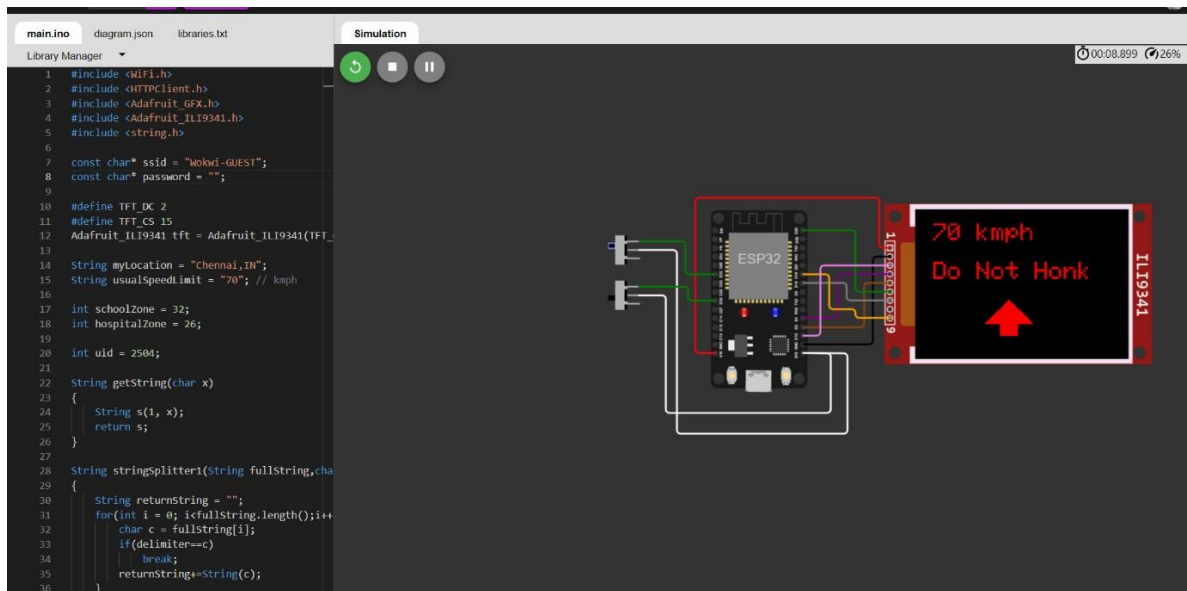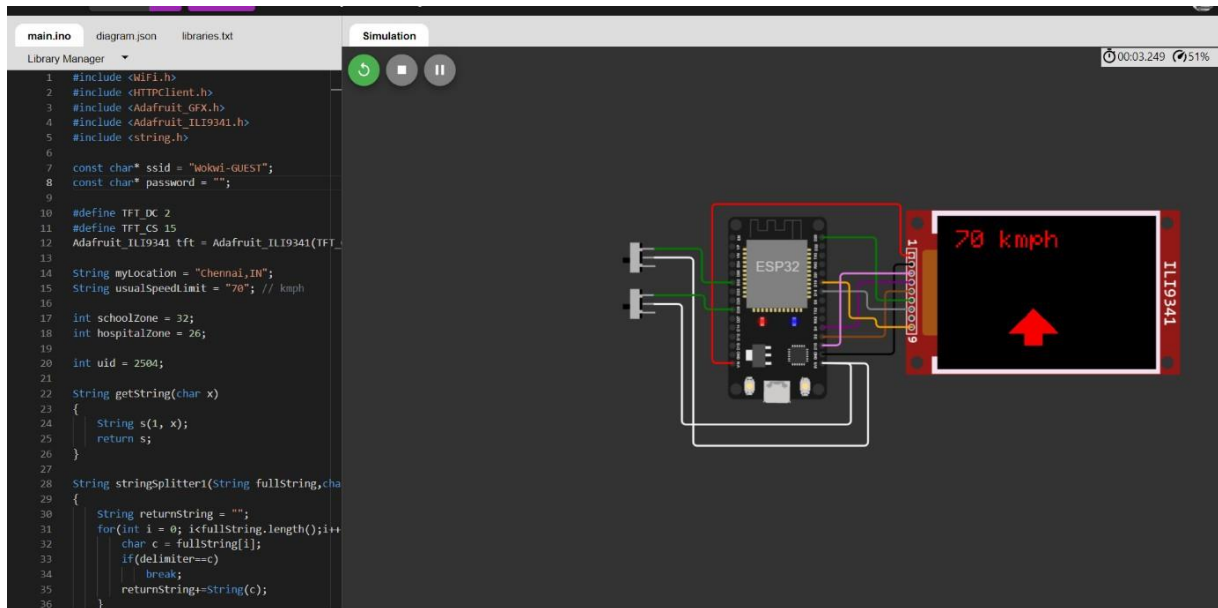
Output :
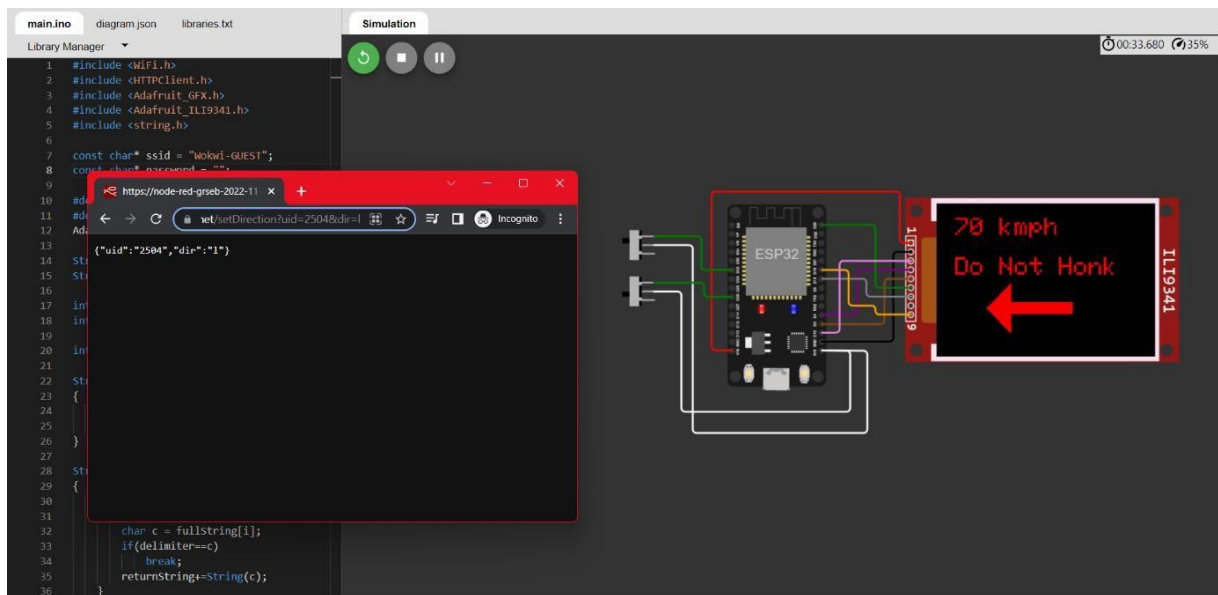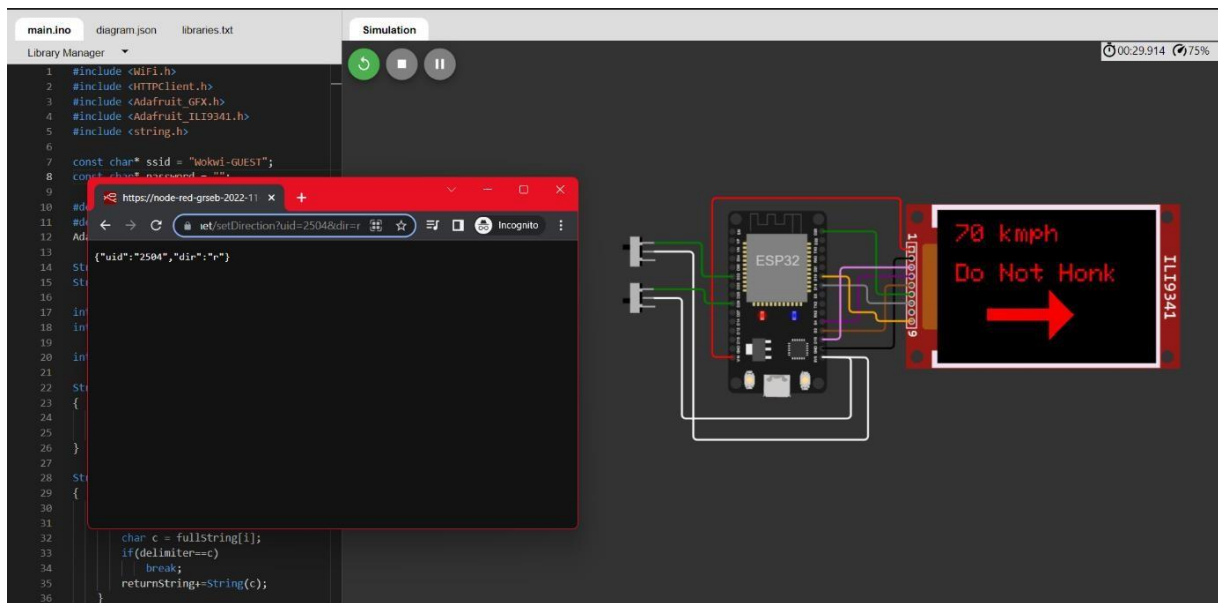
Node RED Dashboard :

LINK TO NODE RED DASHBOARD

Wokwi Output :

[LINK TO WOKWI PROJECT](#)

Simulation

⏱ 00:03.249 ◉ 51%

70 kmph

---

main.ino diagram.json libraries.txt

Library Manager ▾

```
1   #include <WiFi.h>
2   #include <HTTPClient.h>
3   #include <Adafruit_GFX.h>
4   #include <Adafruit_ILI9341.h>
5   #include <string.h>
6
7   const char* ssid = "Wokwi-GUEST";
8   const char* password = "";
9
10  #define TFT_DC 2
11  #define TFT_CS 15
12  Adafruit_ILI9341 tft = Adafruit_ILI9341(TFT_
13
14  String myLocation = "Chennai,IN";
15  String usualSpeedLimit = "70"; // kmph
16
17  int schoolZone = 32;
18  int hospitalZone = 26;
19
20  int uid = 2504;
21
22  String getString(char x)
23  {
24      String s(1, x);
25      return s;
26  }
27
28  String stringSplitter1(String fullString,cha
29  {
30      String returnString = "";
31      for(int i = 0; i<fullString.length();i++
32          char c = fullString[i];
33          if(delimiter==c)
34              break;
35          returnString+=String(c);
36      }
```

Simulation

⏱ 00:08.899 ◉ 26%

70 kmph

Do Not Honk

Thank You

+