Date	18 NOV 2022
Team ID	PNT2022TMID46295
Project Name	Signs with smart connectivity for Better road safety

Sprint 01

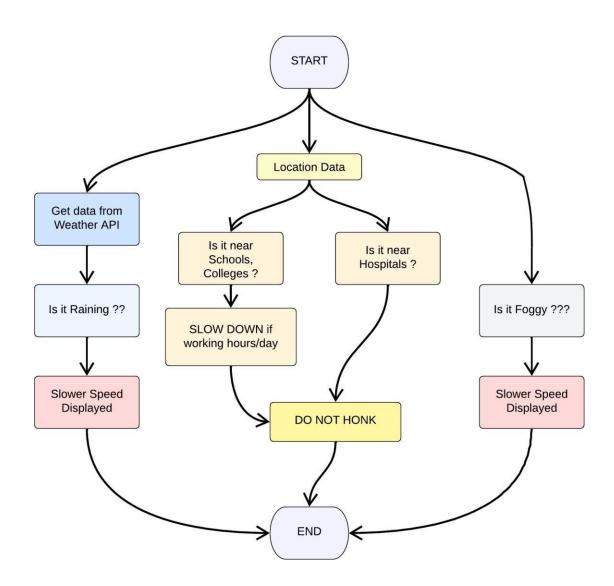
Signs with Smart Connectivity for Better Road Safety

Team ID - PNT2022TMID46295

Sprint Goals:

- 1. Create and initialize accounts in various public APIs like OpenWeather API.
- 2. Write a Python program that outputs results given the inputs like weather and location.

Code Flow:



Program Code:

> weather.py

This file is a utility function that fetches the weather from OpenWeatherAPI. It returns only certain required parameters of the API response.

```
# Python code
import requests as reqs

def get(myLocation,APIKEY):
    apiURL =
f"https://api.openweathermap.org/data/2.5/weather?q={myLocation}&appid={APIKEY}"
    responseJSON = (reqs.get(apiURL)).json()
    returnObject = {
```

> brain.py

This file is a utility function that returns only essential information to be displayed at the hardware side and abstracts all the unnecessary details. This is where the code flow logic is implemented.

```
# Python code
# IMPORT SECTION STARTS
import weather
from datetime import datetime as dt
# IMPORT SECTION ENDS
# ------
# UTILITY LOGIC SECTION STARTS
def processConditions(myLocation,APIKEY,localityInfo):
    weatherData = weather.get(myLocation,APIKEY)
   finalSpeed = localityInfo["usualSpeedLimit"] if "rain" not in weatherData else
localityInfo["usualSpeedLimit"]/2
   finalSpeed = finalSpeed if weatherData["visibility"]>35 else finalSpeed/2
    if(localityInfo["hospitalsNearby"]):
       # hospital zone
       doNotHonk = True
   else:
       if(localityInfo["schools"]["schoolZone"]==False):
           # neither school nor hospital zone
           doNotHonk = False
       else:
           # school zone
           now = [dt.now().hour,dt.now().minute]
           activeTime = [list(map(int,_.split(":"))) for _ in
localityInfo["schools"]["activeTime"]]
            doNotHonk = activeTime[0][0]<=now[0]<=activeTime[1][0] and</pre>
activeTime[0][1]<=now[1]<=activeTime[1][1]</pre>
    return({
       "speed" : finalSpeed,
       "doNotHonk" : doNotHonk
    })
# UTILITY LOGIC SECTION ENDS
```

> main.py

The code that runs in a forever loop in the micro-controller. This calls all the util functions from other python files and based on the return value transduces changes in the output hardware display.

```
# Python code
# IMPORT SECTION STARTS
import brain
# IMPORT SECTION ENDS
# USER INPUT SECTION STARTS
myLocation = "Chennai,IN"
APIKEY = "bf4a8d480ee05c00952bf65b78ae826b"
localityInfo = {
    "schools" : {
        "schoolZone" : True,
        "activeTime" : ["7:00","17:30"] # schools active from 7 AM till 5:30 PM
    "hospitalsNearby" : False,
    "usualSpeedLimit" : 40 # in km/hr
}
# USER INPUT SECTION ENDS
# MICRO-CONTROLLER CODE STARTS
print(brain.processConditions(myLocation,APIKEY,localityInfo))
. . .
MICRO CONTROLLER CODE WILL BE ADDED IN SPRINT 3 AS PER OUR PLANNED SPRINT SCHEDULE
# MICRO-CONTROLLER CODE ENDS
Output:
# Code Output
{'speed': 40, 'doNotHonk': False}
```

Image:

Thank You