# Sprint 02

# Signs with Smart Connectivity for Better Road Safety Team ID - PNT2022TMID03062

```
Sprint Goals:
              Push data from local code to cloud
Program Code:
> weather.py
This file is a utility function that fetches the weather from OpenWeatherAPI. It
returns only certain required parameters of the API response.
# Python code
import requests as reqs
def get(myLocation,APIKEY):
  apiURL =
f"https://api.openweathermap.org/data/2.5/weather?q={myLocation}&appid={API
KEY}"
  responseJSON = (reqs.get(apiURL)).json()
  returnObject = {
    "temperature": responseJSON['main']['temp'] - 273.15,
    "weather": [responseJSON['weather'][_]['main'].lower() for _ in
range(len(responseJSON['weather']))],
     "visibility": responseJSON['visibility']/100, # visibility in percentage where
10km is 100% and 0km is 0%
  if("rain" in responseJSON):
    returnObject["rain"] = [responseJSON["rain"][key] for key in
responseJSON["rain"]]
  return(returnObject)
> publishData.py
This code pushes data to the cloud and logs data. IBM Cloud is configured such
that the data is displayed in the following website: CLICK TO OPEN NODE RED
DASHBOARD
```

```
# Python code
# IMPORT SECTION STARTS
import wiotp.sdk.device # python -m pip install wiotp
import time
# IMPORT SECTION ENDS
# API CONFIG SECTION STARTS
myConfig = {
  "identity" : {
    "orgId": "epmoec",
    "typeId": "testDevice",
    "deviceId": "device0"
  },
  "auth" : {
    "token": "?-KDXUPMvDo_TK2&b1"
}
# API CONFIG SECTION ENDS
#
# FUNCTIONS SECTION STARTS
def myCommandCallback(cmd):
  print("recieved cmd : ",cmd)
def logData2Cloud(location,temperature, visibility):
  client = wiotp.sdk.device.DeviceClient(config=myConfig,logHandlers=None)
  client.connect()
  client.publishEvent(eventId="status",msgFormat="json",data={
    "temperature": temperature,
    "visibility": visibility,
    "location": location
  },qos=0,onPublish=None)
  client.commandCallback = myCommandCallback
  client.disconnect()
  time.sleep(1)
```

#### # FUNCTIONS SECTION ENDS

```
> brain.py
```

This file is a utility function that returns only essential information to be displayed at the hardware side and abstracts all the unnecessary details. This is where the code flow logic is implemented.

from datetime import datetime as dt from publishData import logData2Cloud as log2cloud

```
# IMPORT SECTION ENDS
# UTILITY LOGIC SECTION STARTS
def processConditions(myLocation,APIKEY,localityInfo):
  weatherData = weather.get(myLocation,APIKEY)
  log2cloud(myLocation, weatherData["temperature"], weatherData["visibility"])
  finalSpeed = localityInfo["usualSpeedLimit"] if "rain" not in weatherData else
localityInfo["usualSpeedLimit"]/2
  finalSpeed = finalSpeed if weatherData["visibility"]>35 else finalSpeed/2
  if(localityInfo["hospitalsNearby"]):
    # hospital zone
    doNotHonk = True
  else:
    if(localityInfo["schools"]["schoolZone"]==False):
       # neither school nor hospital zone
       doNotHonk = False
    else:
       # school zone
       now = [dt.now().hour,dt.now().minute]
       activeTime = [list(map(int,_.split(":"))) for _ in
localityInfo["schools"]["activeTime"]]
       doNotHonk = activeTime[0][0]<=now[0]<=activeTime[1][0] and
activeTime[0][1]<=now[1]<=activeTime[1][1]
  return({
    "speed": finalSpeed,
    "doNotHonk": doNotHonk
  })
```

#### # UTILITY LOGIC SECTION ENDS

```
> main.py
```

The code that runs in a forever loop in the micro-controller. This calls all the util functions from other python files and based on the return value transduces changes in the output hardware display.

```
# Python code
#IMPORT SECTION STARTS
import brain
# IMPORT SECTION ENDS
# USER INPUT SECTION STARTS
myLocation = "Chennai,IN"
APIKEY = "bf4a8d480ee05c00952bf65b78ae826b"
localityInfo = {
  "schools": {
    "schoolZone": True,
    "activeTime" : ["7:00","17:30"] # schools active from 7 AM till 5:30 PM
  "hospitalsNearby": False,
  "usualSpeedLimit": 40 # in km/hr
}
# USER INPUT SECTION ENDS
#
# MICRO-CONTROLLER CODE STARTS
while True:
 print(brain.processConditions(myLocation,APIKEY,localityInfo))
MICRO CONTROLLER CODE WILL BE ADDED IN SPRINT 3 AS PER OUR
PLANNED SPRINT SCHEDULE
```

# MICRO-CONTROLLER CODE ENDS

## Output:

#### LINK TO NODE RED DASHBOARD

```
# Code Output
```

2022-11-06 21:38:33,452 wiotp.sdk.device.client.DeviceClient INFO

Connected successfully: d:epmoec:testDevice:device0

2022-11-06 21:38:33,452 wiotp.sdk.device.client.DeviceClient INFO

Disconnected from the IBM Watson IoT Platform

2022-11-06 21:38:33,452 wiotp.sdk.device.client.DeviceClient INFO Closed

connection to the IBM Watson IoT Platform

{'speed': 40, 'doNotHonk': False}

2022-11-06 21:38:35,631 wiotp.sdk.device.client.DeviceClient INFO

Connected successfully: d:epmoec:testDevice:device0

2022-11-06 21:38:35,631 wiotp.sdk.device.client.DeviceClient INFO

Disconnected from the IBM Watson IoT Platform

2022-11-06 21:38:35,631 wiotp.sdk.device.client.DeviceClient INFO Closed

connection to the IBM Watson IoT Platform

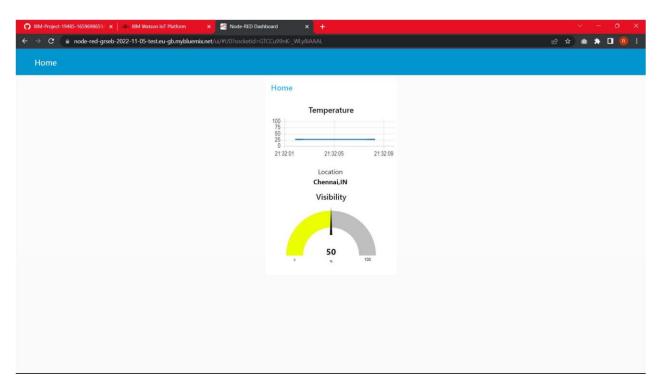
{'speed': 40, 'doNotHonk': False}

.

... repeats every 1 sec

Images:

Output Image 2



### Output Image

