## Assignment 4

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Team ID	PNT2022TMID31852
Maximum Mark	2

```
#define ECHO_PIN 2
#define TRIG_PIN 3
void setup() {
Serial.begin(9600);
pinMode(TRIG_PIN, OUTPUT);
pinMode(ECHO_PIN, INPUT);
}
float readDistanceCM() {
digitalWrite(TRIG_PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
int duration = pulseIn(ECHO_PIN, HIGH);
return duration * 0.034 / 2;
}
void loop() {
float distance = readDistanceCM();
if(distance <= 100)
{
Serial.println("person detected ");
}
else{
Serial.print("Measured distance: ");
Serial.println(readDistanceCM());
}
```

```
delay(1000);
}
```

## Simulation:

