

#### Assignment 4

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Maximum Mark	2

```
#define ECHO_PIN 2
#define TRIG_PIN 3

void setup() {
  Serial.begin(9600);
  pinMode(TRIG_PIN, OUTPUT);
  pinMode(ECHO_PIN, INPUT);
}

float readDistanceCM() {
  digitalWrite(TRIG_PIN, LOW);
  delayMicroseconds(2);
  digitalWrite(TRIG_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);
  int duration = pulseIn(ECHO_PIN, HIGH);
  return duration * 0.034 / 2;
}

void loop() {
  float distance = readDistanceCM();
  if(distance <= 100)
  {
    Serial.println("person detected ");
  }
  else{
    Serial.print("Measured distance: ");
    Serial.println(readDistanceCM());
  }
}
```

```
delay(1000);
```

```
}
```

Simulation:

