## **SOURCE CODE**

```
import time
import sys
import ibmiotf.application
import ibmiotf.device
import random
#Provide your IBM Watson Device Credentials
organization = "hzu4n4"
deviceType = "ajaysarran"
deviceId = "27092002"
authMethod = "token"
authToken = ")onRVxyT7sOrIDrGoh"
global y
# Initialize GPIO
def myCommandCallback(cmd):
print("Command received: %s" % cmd.data['command'])
status=cmd.data['command']
if status=="motoron":
print ("motor is on")
if status=="motoroff":
print ("motor is off")
if status=="manual":
print ("Motor Control is in Manual Mode")
if status=="automatic":
print ("Motor control is in Automatic Mode")
if soilmoisture > 600:
print ("motor is on")
```

```
try:
deviceOptions = {"org": organization, "type": deviceType, "id": deviceId, "auth-method":
authMethod, "auth-token": authToken}
deviceCli = ibmiotf.device.Client(deviceOptions)
#.....
except Exception as e:
print("Caught exception connecting device: %s" % str(e))
sys.exit()
# Connect and send a datapoint "hello" with value "world" into the cloud as an event of type
"greeting" 10
times
deviceCli.connect()
while True:
#Get Sensor Data from DHT11
temp=random.randint(0,100)
Humid=random.randint(0,100)
soilmoisture=random.randint(0,1023)
Phlevel=random.randint(0,14)
y=soilmoisture
data = { 'temp' : temp, 'Humid': Humid, 'soilmoisture' : soilmoisture , 'Phlevel' : Phlevel }
#print data
def myOnPublishCallback():
print ("Published Temperature = %s C" % temp, "Humidity = %s %%" % Humid, "Soil Moisture
%s %%" % soilmoisture,"PH level is %s" %Phlevel ,"to IBM Watson")
success = deviceCli.publishEvent("IoTSensor", "json", data, qos=0,
on_publish=myOnPublishCallback)
if not success:
print("Not connected to IoTF")
time.sleep(10)
deviceCli.commandCallback = myCommandCallback
```

#print(cmd)

# Disconnect the device and application from the cloud deviceCli.disconnect()