

Name: AVANTHIKA V T Y

Rollno: 727719EUEC023

ASSIGNMENT 1-HOME AUTOMATION

PROGRAM:

```
#include <Servo.h>

int output1Value = 0;
int sen1Value = 0;
int sen2Value = 0;
int const gas_sensor = A1;
int const LDR = A0;
int limit = 400;

long readUltrasonicDistance(int triggerPin, int echoPin)
{
    pinMode(triggerPin, OUTPUT); // Clear the trigger
    digitalWrite(triggerPin, LOW);
    delayMicroseconds(2);
    // Sets the trigger pin to HIGH state for 10 microseconds
    digitalWrite(triggerPin, HIGH);
    delayMicroseconds(10);
    digitalWrite(triggerPin, LOW);
    pinMode(echoPin, INPUT);
    // Reads the echo pin, and returns the sound wave travel time in microseconds
    return pulseIn(echoPin, HIGH);
}

Servo servo_7;

void setup()
{
    Serial.begin(9600);           //initialize serial communication
```

```
pinMode(A0, INPUT);      //LDR
pinMode(A1,INPUT);       //gas sensor
pinMode(13, OUTPUT);     //connected to relay
servo_7.attach(7, 500, 2500); //servo motor

pinMode(8,OUTPUT);       //signal to piezo buzzer
pinMode(9, INPUT);       //signal to PIR
pinMode(10, OUTPUT);     //signal to npn as switch
pinMode(4, OUTPUT);      //Red LED
pinMode(3, OUTPUT);      //Green LED
```

```
}
```

```
void loop()
```

```
{
```

```
    //-----light intensity control-----//
```

```
//-----
```

```
    int val1 = analogRead(LDR);
```

```
    if (val1 > 500)
```

```
    {
```

```
        digitalWrite(13, LOW);
```

```
        Serial.print("Bulb ON = ");
```

```
        Serial.print(val1);
```

```
    }
```

```
    else
```

```
    {
```

```
        digitalWrite(13, HIGH);
```

```
        Serial.print("Bulb OFF = ");
```

```
        Serial.print(val1);
```

```
    }
```

```

//-----
//----- light & fan control -----//
//-----

sen2Value = digitalRead(9);
if (sen2Value == 0)
{
    digitalWrite(10, LOW); //npn as switch OFF
    digitalWrite(4, HIGH); // Red LED ON, indicating no motion
    digitalWrite(3, LOW); //Green LED OFF, since no Motion detected
    Serial.print("    || NO Motion Detected    ");
}

if (sen2Value == 1)
{
    digitalWrite(10, HIGH); //npn as switch ON
    delay(3000);
    digitalWrite(4, LOW); // RED LED OFF
    digitalWrite(3, HIGH); //GREEN LED ON , indicating motion detected
    Serial.print("        || Motion Detected!    ");
}
delay(300);

//-----
// ----- Gas Sensor -----//
//-----

int val = analogRead(gas_sensor); //read sensor value
Serial.print("|| Gas Sensor Value = ");
Serial.print(val); //Printing in serial monitor
//val = map(val, 300, 750, 0, 100);
if (val > limit)
{
    tone(8, 650);
}

```

```

    }

    delay(300);

    noTone(8);

//-----

    //----- servo motor -----//

//-----

    sen1Value = 0.01723 * readUltrasonicDistance(6, 6);

    if (sen1Value < 100)
    {
        servo_7.write(90);

        Serial.print("  || Door Open! ; Distance = ");
        Serial.print(sen1Value);
        Serial.print("\n");

    }

    else

    {
        servo_7.write(0);

        Serial.print("  || Door Closed! ; Distance = ");
        Serial.print(sen1Value);
        Serial.print("\n");
    }

    delay(10); // Delay a little bit to improve simulation performance
}

```

OUTPUT:

