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## ASSIGNMENT 4-BUZZER FOR ULTRASONIC SENSOR

## **SOURCE CODE:**

```
int t=2;
int e=3;

void setup()
{
    Serial.begin(9600);
    pinMode(t,OUTPUT);
    pinMode(e,INPUT);
    pinMode(12,OUTPUT);
}

void loop()
{
    //ultrasonic sensor
    digitalWrite(t,LOW);
    digitalWrite(t,HIGH);
    delayMicroseconds(10);
    digitalWrite(t,LOW);
```

```
float dur=pulseIn(e,HIGH);
float dis=(dur*0.0343)/2;
Serial.print("Distance is:
");Serial.println(dis);
 //LED ON
if(dis > = 100)
 digitalWrite(8,HIGH
 );
 digitalWrite(7,HIGH
 );
}
//Buzzer For ultrasonic Sensor
if(dis >= 100)
for(int i=0; i<=30000; i=i+10)
{
tone(12,i);
delay(1000);
noTone(12);
delay(1000);
}
```

