

TEST CASE REPORT

Team ID	PNT2022TMID03917
Project Name	Smart Waste Management System for MetropolitanCities

Test case	Feature Type- Bin Level	Component	Test Case Scenario	Pre- Requisite	Availability	Test Condition	Expected Result	Actual Result	Status	Comments	Accessed By
Test case 1	Empty	Ultrasonic Sensor	When Bin is empty	Ultrasonic sensor PIR Motion Sensor Garbage Bins	Bin is accessible to users	Bin Level == 0	Displays Bin level and space left	Working as expected	Pass		User
Test case 2	Accessible	Ultrasonic Sensor	When bin level is below 50 %	Ultrasonic sensor , PIR Motion Sensor , Garbage Bins	Bin is accessible to users	Bin Level < 50	Displays Bin level and space left	Working as expected	Pass		User
Test case 3	Accessible	Ultrasonic Sensor	When bin level is above 50	Ultrasonic sensor , PIR Motion sensor , Garbage Bins	Bin is accessible to users and the admin gets warning about the bin level	Bin Level > 50	Displays Bin level and space left	Working as expected	Pass		User
Test case 4	Accessible	Ultrasonic Sensor	When bin level is below 75 %	Ultrasonic sensor , PIR Motion sensor , Garbage Bins	Bin is accessible to users and the admin gets warning about the bin level	Bin Level < 75	Displays Bin level and space left	Working as expected	Pass		User
Test case 5	Limit exceeded	Ultrasonic Sensor	When bin level is above 75 %	Ultrasonic sensor , PIR Motion sensor , Garbage Bins	Bin is not accessible to the users, the admin recieves High alert and seals the the bin to avoid overflow.	Bin Level > 75	Displays Bin is FULL and Seals the bin.	Working as expected	Pass	The system starts to sense the level once the Bin is emptied partially or fully	User/Admin