

Develop a python script

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Project Name	Smart waste management system for metropolitan cities

Step 1: Open python idle

Step2: Type the program

Step 3: Then click on file and save the document

Step 4: Then click on Run then Run Module

Step 5: output will be appeared in the idle window

Python script

```
import requests
import json
import ibmiotf.application
import ibmiotf.device
import time
import random
import sys
```

```
# watson device details
```

```
organization = "4yi0vc"
devicType = "BIN1"
deviceId = "BIN1ID"
authMethod= "token"
authToken= "123456789"
```

```
#generate random values for randomo variables (temperature&humidity)
```

```

def myCommandCallback(cmd):
    global a
    print("command recieved:%s" %cmd.data['command'])
    control=cmd.data['command']
    print(control)

try:
    deviceOptions={"org": organization, "type": devicType,"id": deviceId,"auth-method":authMethod,"auth-
token":authToken}
    deviceCli = ibmiotf.device.Client(deviceOptions)
except Exception as e:
    print("caught exception connecting device %s" %str(e))
    sys.exit()

#connect and send a datapoint "temp" with value integer value into the cloud as a type of event for every 10 seconds
deviceCli.connect()

while True:

    distance= random.randint(10,70)
    loadcell= random.randint(5,15)
    data= {'dist':distance,'load':loadcell}

    if loadcell < 13 and loadcell > 15:
        load = "90 %"

    elif loadcell < 8 and loadcell > 12:
        load = "60 %"

    elif loadcell < 4 and loadcell > 7:
        load = "40 %"
    else:

```

```

load = "0 %"

if distance < 15:
    dist = 'Risk warning:' 'Dumpster poundage getting high, Time to collect :) 90 %'

elif distance < 40 and distance >16:
    dist = 'Risk warning:' 'dumpster is above 60%'

elif distance < 60 and distance > 41:
    dist = 'Risk warning:' '40 %'
else:
    dist = 'Risk warning:' '17 %'


if load == "90 %" or distance == "90 %":
    warn = 'alert :' ' Dumpster poundage getting high, Time to collect :)'

elif load == "60 %" or distance == "60 %":

    warn = 'alert :' 'dumpster is above 60%'
else :
    warn = 'alert :' 'No need to collect right now '
def myOnPublishCallback(lat=10.678991,long=78.177731):
    print("Gandigramam, Karur")
    print("published distance = %s " %distance,"loadcell:%s " %loadcell,"lon = %s " %long,"lat = %s" %lat)
    print(load)
    print(dist)
    print(warn)

time.sleep(10)

success=deviceCli.publishEvent ("IoTSensor","json",warn,qos=0,on_publish= myOnPublishCallback)

```

```
success=deviceCli.publishEvent ("IoTSensor","json",data,qos=0,on_publish= myOnPublishCallback)
```

```
if not success:  
    print("not connected to ibmiot")  
time.sleep(30)
```

```
deviceCli.commandCallback=myCommandCallback  
#disconnect the device  
deviceCli.disconnect
```

Screenshots Python script:

The image shows a Windows desktop with three Python IDE windows open, each running a different script for IoT device simulation. The windows are titled 'IDLE py - F:\Desktop\bin2.py (3.7.4)', 'IDLE py - F:\Desktop\bin4.py (3.7.4)', and 'IDLE py - F:\Desktop\bin2.py (3.7.4)'. The first window (left) shows code for device initialization and random data generation, with terminal output displaying risk warnings and data points. The second window (middle) shows code for device initialization and random data generation, with terminal output displaying risk warnings and data points. The third window (right) shows code for device initialization and random data generation, with terminal output displaying risk warnings and data points. The desktop background is a standard Windows 10 wallpaper, and the taskbar at the bottom shows various application icons and the system clock.

