ASSIGNMENT 4

WOKWI

TEAM ID	PNT2022TMID21422	
Project name	IOT Based Smart Crop Protection For	
	Agriculture	
Student Name	Sneha S R	

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cm send an "alert" to the IBM cloud and display in the device recent events. Upload document with wokwi share link and images of IBM cloud

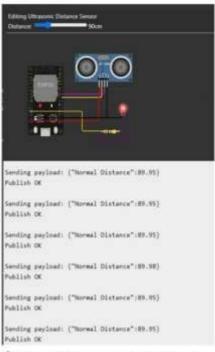
```
Program:
```

```
#include <WiFi.h>
#include <PubSubClient.h>
#include <ArduinoJson.h>
WiFiClient wifiClient;
#define ORG "kr9fjo"
#define DEVICE_TYPE "TestDeviceType"
#define DEVICE_ID "12345"
#define TOKEN "VJsSC148dk1dCN3UqS"
#define speed 0.034
char server[] = ORG
".messaging.internetofthings.ibmcloud.com"; char publishTopic[]
= "iot-2/evt/abcd_1/fmt/json"; char topic[] = "iot-
2/cmd/home/fmt/String";
                          char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
PubSubClient client(server, 1883, wifiClient); void
publishData();
 const int trigpin=5;
const int echopin=18;
String command;
String data="";
String lat="14.167589";
String lon="80.248510";
String name="point2";
String icon="";
```

```
long
duration; int
dist;
void setup()
  Serial.begin(115200);
pinMode(trigpin, OUTPUT);
pinMode(echopin, INPUT);
wifiConnect();
               mqttConnect();
}
void loop() {
publishData();
delay(500);
   if (!client.loop())
{
      mqttConnect();
  }
}
void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST", "", 6);
                                    while
(WiFi.status() != WL_CONNECTED) {
                                       delay(500);
    Serial.print(".");
  }
  Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
} void mqttConnect() {
                          if
(!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);
while (!client.connect(clientId, authMethod, token)) {
Serial.print(".");
                         delay(1000);
    }
    initManagedDevice();
    Serial.println();
  }
}
 void initManagedDevice() {
(client.subscribe(topic)) {
     Serial.println(client.subscribe(topic));
    Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  } }
void publishData()
{ digitalWrite(trigpin,LOW);
digitalWrite(trigpin,HIGH);
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2;
     if(dist<100){</pre>
dist=100-dist;
```

```
icon="fa-trash";
}else{
         dist=0;
icon="fa-trash-o";
 }
 DynamicJsonDocument doc(1024);
String payload; doc["Name"]=name;
doc["Latitude"]=lat;
doc["Longitude"]=lon;
doc["Icon"]=icon;
doc["FillPercent"]=dist;
serializeJson(doc, payload);
delay(3000);
 Serial.print("\n");
 Serial.print("Sending payload: ");
Serial.println(payload);
 if (client.publish(publishTopic, (char*) payload.c_str())) {
   Serial.println("Publish OK");
 } else {
   Serial.println("Publish FAILED");
 }
}
```

OUTPUT



when distance under 100 cm
 it wil show normal distance



Distance Unitarios Sensor

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Narming crosses librs -- it automatically of the loop

 when distance cross 100 cm it wil show ALERT with warning message distance

when it cross above 110 cm it totaly move to iff state once it reduce to 110 it on again

IBM CLOUD OUPUT

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