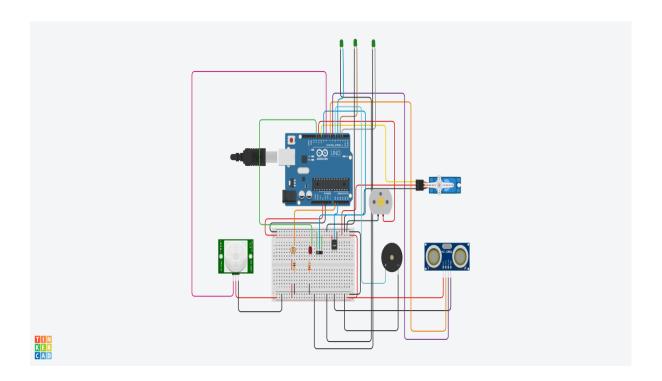
Nalaiya Thiran (IBM)

ASSIGNMENT - 1

Make a Smart Home in Tinker cad, using 2+ sensors, Led, Buzzer in single code and circuit.

Smart Home Automation Tinker cad link:

https://www.tinkercad.com/things/8YxEElo0U7U-epic-wolt/editel?sharecode=JF0FR96XAQGh_7L50L00wq3eIIL_zenWZHug-Jz8cO8



Program Code:

```
#include <Servo.h>
const int PIR_Sensor = 8;
Servo doorservo;
int Idr = A0;
int led = 12;
int tmp = A1;
int motor = 11;
int d;
int const trigPin = 7;
int const echoPin = 6;
int const buzzPin = 5;
void setup()
{
 pinMode(ldr,INPUT);
 pinMode(led,OUTPUT);
 pinMode(tmp,INPUT);
 pinMode(motor,OUTPUT);
 doorservo.attach(10);
 pinMode(trigPin, OUTPUT);
 pinMode(echoPin, INPUT);
 pinMode(buzzPin, OUTPUT);
 pinMode(2, OUTPUT);
 pinMode(3, OUTPUT);
 pinMode(4, OUTPUT);
 pinMode(9,INPUT);
}
```

```
void loop()
{
 int ldrs = analogRead(ldr);
 if(ldrs <= 300)
 {
  digitalWrite(led,HIGH);
  digitalWrite(2,HIGH);
  digitalWrite(3,HIGH);
  digitalWrite(4,HIGH);
 }
 else
 {
  digitalWrite(led,LOW);
  digitalWrite(2,LOW);
  digitalWrite(3,LOW);
  digitalWrite(4,LOW);
 int reading = analogRead(tmp);
 float voltage = reading * 5.0;
 voltage /= 1024.0;
 float temperatureC = (voltage - 0.5) * 100;
 if(temperatureC >= 30)
 {
  digitalWrite(motor,HIGH);
 }
 else
 {
```

```
digitalWrite(motor,LOW);
 d = digitalRead(9);
  if(d==1){}
  doorservo.write(100);
 }
 else{
  doorservo.write(0);
 }
int duration, distance;
      digitalWrite(trigPin, HIGH);
       delay(1);
      digitalWrite(trigPin, LOW);
      duration = pulseIn(echoPin, HIGH);
       distance = (duration/2) / 29.1;
  if (distance <= 50 && distance >= 0) {
      digitalWrite(buzzPin, HIGH);
  } else {
      digitalWrite(buzzPin, LOW);
  }
  delay(60);
 if (digitalRead(PIR_Sensor)==HIGH)
   {digitalWrite(buzzPin, HIGH);}
 else {digitalWrite(buzzPin, LOW);}
}
```