## **SPRINT-4**

## **CODE IMPLEMENTATION**

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PROJECT TITLE	REAL-TIME RIVER WATER QUALITY MONITORING AND CONTROL SYSTEM
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```
import serial import time
import csv import numpy
as np import
matplotlib.pyplot as plt ser
=
serial.Serial('/COM6',9600)
ser_bytes =
ser.readline(10) print
(ser_bytes) ser.flushInput()
while True:
try:
```

```
ser_bytes = ser.readline() decoded_bytes =
float(ser_bytes[0:len(ser_bytes)-2].decode("utf-8"))
print(decoded_bytes)
temp = float(decoded bytes(1:3)) turb
= float(decoded_bytes(4:6)) pH =
float(decoded_bytes(6:8)) with
open("test_data.csv","a") as f: writer =
csv.writer(f,delimiter=",")
writer.writerow([time.time(),decoded_b
ytes]) except: print("Keyboard
Interrupt") ser.close() break() t =
np.arange(0.0, 2.0, 0.01) s = 1 +
np.sin(2*np.pi*t) plt.plot(t, s)
plt.xlabel('time (s)') plt.ylabel('Celsisus
(C)') plt.title('Temperature')
plt.grid(True)
plt.savefig("Temperature.png")
plt.show() Serial.begin(9600);
sensors.begin(); int sensorValue =
analogRead(A1); voltage =
sensorValue * (5.0 / 1024.0);
}
void loop(void)
{
```

```
Celcius=sensors.getTempCByIndex(0);
Fahrenheit=sensors.toFahrenheit(Celci
us); for(int i=0;i<10;i++)
{
buf[i]=analogRead(analogInPin);
delay(10);
for(int i=0; i<9; i++)
{
for(int j=i+1; j<10; j++)
{
if(buf[i]>buf[j])
temp=buf[i];
buf[i]=buf[j];
buf[j]=temp;
}
n = 256
X = np.linspace(-np.pi, np.pi, 256,
endpoint=True) C,S = np.cos(X),
np.sin(X) plt.plot(X, C) plt.plot(X,S)
plt.show()
```

sensors.requestTemperatures();

```
print ("Visualization of real time sensor

Data.") print("/n") while True:

try:

ser_bytes = ser.readline() decoded_bytes =

float(ser_bytes[0:len(ser_bytes)-2].decode("utf-8"))

print(decoded_bytes) temp = float(decoded_bytes(1:3))

turb = float(decoded_bytes(4:6)) pH =

float(decoded_bytes(6:8)) with open("test_data.csv","a")

as f: writer = csv.writer(f,delimiter=",")

writer.writerow([time.time(),decoded_bytes]) except:

print("Keyboard Interrupt") ser.close() break() t =

np.arange(0.0, 2.0, 0.01) s = 1 + np.sin(2*np.pi*t) plt.plot(t, s)
```