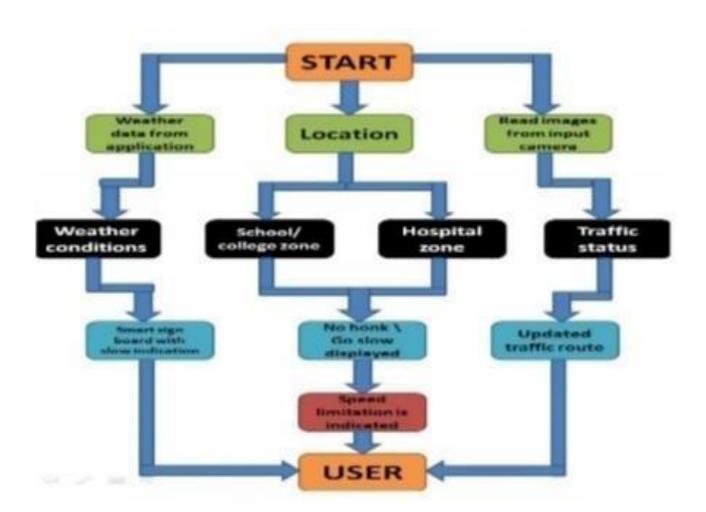
# Sprint 01

Team ID	
	PNT2022TMID41856
Project Title	Signs with smart connectivity for better road
	safety

## **Sprint Goals**

- 1. Create and initialize accounts in various public APIs like OpenWeather API.
- 2. Write a Python program that outputs results given the inputs like weather and location.

### **Code Flow:**



#### **Program Code:**

#### weather

This file is a utility function that fetches the weather from OpenWeatherAPI. It returns only certain required parameters of the API response.

```
import requests as reqs

def get(myLocation,APIKEY):
    apiURL =
f"https://api.openweathermap.org/data/2.5/weather?q={myLocation}&appid={APIKEY}
}"
    responseJSON = (reqs.get(apiURL)).json()
    returnObject = {
        "temperature" : responseJSON['main']['temp'] - 273.15,
        "weather" : [responseJSON['weather'][_]['main'].lower() for _ in
range(len(responseJSON['weather']))],
        "visibility" : responseJSON['visibility']/100, # visibility in
percentage where 10km is 100% and 0km is 0%
    }
    if("rain" in responseJSON):
        returnObject["rain"] = [responseJSON["rain"][key] for key in
responseJSON["rain"]]
    return(returnObject)
```

#### brain.py

> This file is a utility function that returns only essential information to be displayed at the hardwareside and abstracts all the unnecessary details. This is where the code flow logic is implemented.

```
# IMPORT SECTION STARTS
import weather
from datetime import datetime as dt
# IMPORT SECTION ENDS
# -----
# UTILITY LOGIC SECTION STARTS
def processConditions(myLocation,APIKEY,localityInfo):
   weatherData = weather.get(myLocation,APIKEY)
   finalSpeed = localityInfo["usualSpeedLimit"] if "rain" not in weatherData else
localityInfo["usualSpeedLimit"]/2
   finalSpeed = finalSpeed if weatherData["visibility"]>35 else finalSpeed/2
   if(localityInfo["hospitalsNearby"]):
       # hospital zone
       doNotHonk = True
   else:
       if(localityInfo["schools"]["schoolZone"]==False):
           # neither school nor hospital zone
           doNotHonk = False
       else:
           # school zone
           now = [dt.now().hour,dt.now().minute]
           activeTime = [list(map(int,_.split(":"))) for _ in
localityInfo["schools"]["activeTime"]]
           doNotHonk = activeTime[0][0] < = now[0] < = activeTime[1][0] and
activeTime[0][1]<=now[1]<=activeTime[1][1]</pre>
```

```
return({
     "speed" : finalSpeed,
     "doNotHonk" : doNotHonk
})

# UTILITY LOGIC SECTION ENDS
```

### main.py

> The code that runs in a forever loop in the micro-controller. This calls all the until functions from other python files and based on the return value transduces changes in the output hardware display.

```
# IMPORT SECTION STARTS
import brain
# IMPORT SECTION ENDS
# ------
# USER INPUT SECTION STARTS
myLocation = "Chennai,IN"
APIKEY = "bf4a8d480ee05c00952bf65b78ae826b"
localityInfo = {
   "schools" : {
      "schoolZone" : True,
      "activeTime" : ["7:00","17:30"] \# schools active from 7 AM till 5:30 PM
   "hospitalsNearby" : False,
   "usualSpeedLimit" : 40 # in km/hr
}
# USER INPUT SECTION ENDS
# -----
```

```
# MICRO-CONTROLLER CODE STARTS

print(brain.processConditions(myLocation,APIKEY,localityInfo))

...

MICRO CONTROLLER CODE WILL BE ADDED IN SPRINT 2 AS PER OUR PLANNED SPRINT SCHEDULE
...

# MICRO-CONTROLLER CODE ENDS

Output:
```python
# Code Output
```

{'speed': 40, 'doNotHonk': False}