

**Assignment -4**  
**Python Programming**

Assignment Date	26 October 2022
Student Name	Mr. Hari Vignesh K
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Maximum Marks	2 Marks

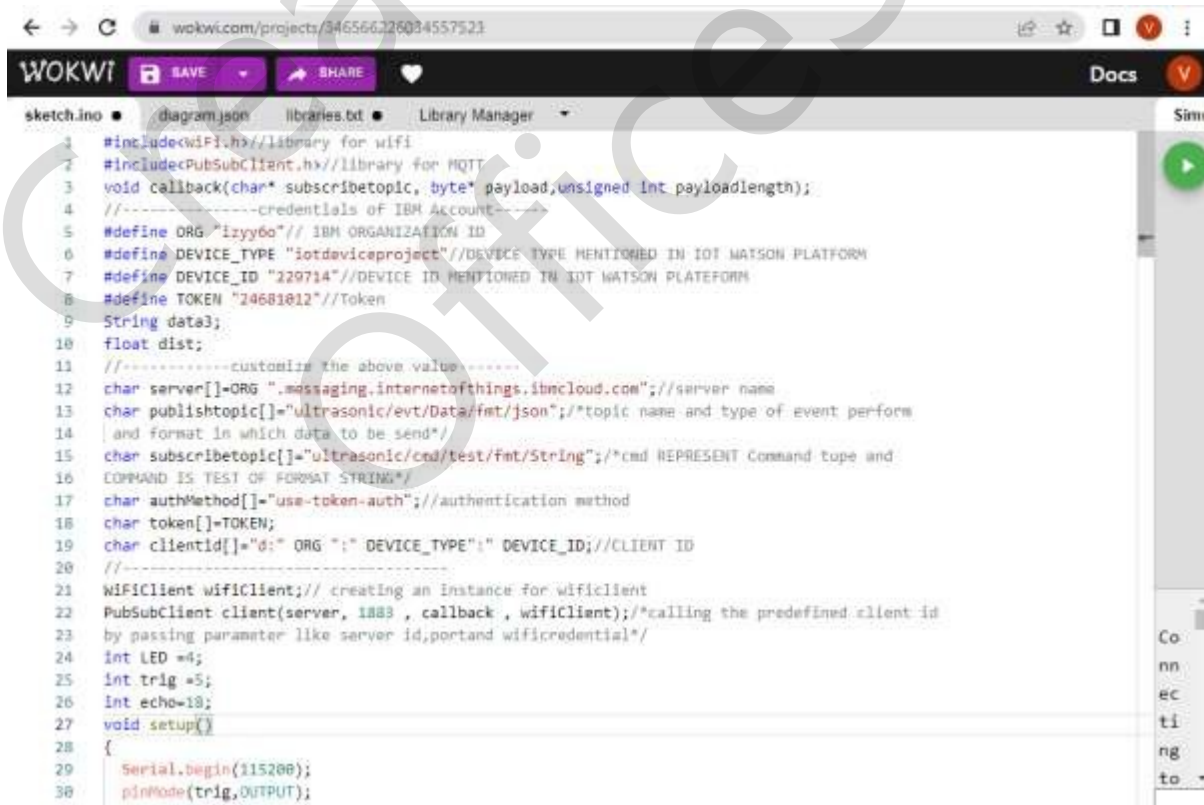
**Question-1:**

Write code and connections in wokwi for ultrasonic sensor.

Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

Upload document with wokwi share link and images of ibm cloud.

**Solution:**



```
1 #include<WiFi.h> //library for wifi
2 #include<PubSubClient.h> //library for MQTT
3 void callback(char* topic, byte* payload, unsigned int payloadlength);
4 //-----credentials of IBM Account-----
5 #define ORG "izyy6o" // IBM ORGANIZATION ID
6 #define DEVICE_TYPE "iotdeviceproject" //DEVICE TYPE MENTIONED IN IOT WATSON PLATFORM
7 #define DEVICE_ID "229714" //DEVICE ID MENTIONED IN IOT WATSON PLATFORM
8 #define TOKEN "24681812" //Token
9 String data;
10 float dist;
11 //-----customize the above value-----
12 char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; //server name
13 char publishTopic[] = "ultrasonic/evt/Data/fmt/json"; //topic name and type of event perform
14 //and format in which data to be send*/
15 char subscribeTopic[] = "ultrasonic/cmd/test/fmt/String"; //cmd REPRESENT Command type and
16 //COMMAND IS TEST OF FORMAT STRING*/
17 char authMethod[] = "use-token-auth"; //authentication method
18 char token[] = TOKEN;
19 char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID; //CLIENT ID
20 //-----
21 WiFiClient wifiClient; // creating an Instance for wifiClient
22 PubSubClient client(server, 1883, callback, wifiClient); //calling the predefined client id
23 //by passing parameter like server id, port and wifi credential*/
24 int LED = 4;
25 int trig = 5;
26 int echo = 18;
27 void setup()
28 {
29   Serial.begin(115200);
30   pinMode(trig, OUTPUT);
```

← → C wokwi.com/projects/346366226034357523

WOKWI SAVE SHARE Docs

sketch.ino diagram.json libraries.txt Library Manager

```
92 }
93 initManagedDevice();
94 Serial.println();
95 }
96 }
97 void wificonnect()//function definition for wificonnect
98 {
99     Serial.println();
100     Serial.print("Connecting to ");
101     WiFi.begin("Wokwi.GUEST", ""); //PASSING THE WIFI CREDENTIALS TO ESTABLISH CONNECTION
102     while (WiFi.status() != WL_CONNECTED){
103         delay(500);
104         Serial.print(".");
105     }
106     Serial.println("");
107     Serial.println("WiFi connected");
108     Serial.println("IP address");
109     Serial.println(WiFi.localIP());
110 }
111 void initManagedDevice(){
112     if(client.subscribe(subscribetopic)){
113         Serial.println(subscribetopic);
114         Serial.println("subscribe to cmd OK");
115     }else{
116         Serial.println("subscribe to cmd failed");
117     }
118 }
119 void callback(char* subscribetopic,byte*payload,unsigned int payloadLength)
120 {
121     Serial.print("callback invoked for topic: ");
122     Serial.println(subscribetopic);
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wokwi.com/projects/346566226034557523
WOKWI SAVE SHARE
sketch.ino diagram.json libraries.txt Library Manager
123 for(int i=0; i< payloadlength; i++){
124   //Serial.print((char)payload[i]);
125   data3 +=(char)payload[i];
126 }
127 //Serial.println("dta: "+ data3);
128 //if(data3=="Near")
129 //{
130 //Serial.println(data3);
131 //digitalwrite(LED,HIGH);
132 //}
133 //else
134 //{
135 //Serial.println(data3);
136 //digitalwrite(LED,LOW);
137 //}
138 data3="";
139 }
```

OUTPUT:

DATA IS SENT TO IBM CLOUD WHEN NO OBJECT IS DETECTED

Browse Action Device Types Interfaces Add Device

DISTANCEDetect		Disconnected	ULTRASON	Device	Oct 20, 2022 9:46 AM	→ ...
Identity	Device Information	Report Events	State	Logs		
This world would not be the same if we didn't have a data stream coming off our Arduino Uno R3.						
Event	Value	Format	Last Received			
Data	["Distance":79.65,"Object": "None"]	json	a few seconds ago			
Data	["Distance":79.65,"Object": "None"]	json	a few seconds ago			
Data	["Distance":79.65,"Object": "None"]	json	a few seconds ago			
Data	["Distance":79.65,"Object": "None"]	json	a few seconds ago			
Data	["Distance":79.65,"Object": "None"]	json	a few seconds ago			

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When no object is detected

