Project Name: Project - Personal Assistance for Seniors Who Are Self-reliant

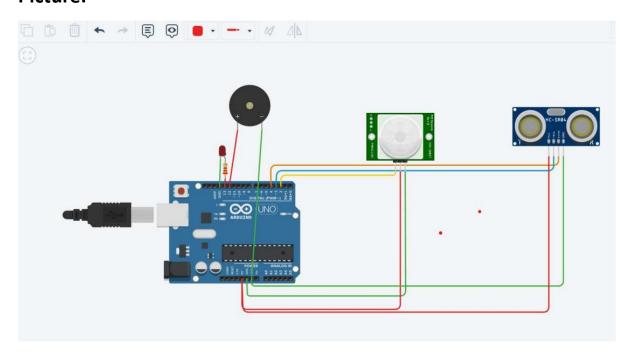
Measuring the value of PIR and Ultrasonic sensor value and turn on the LED.

Code:

```
int led = 13;
int sensor = 2;
int buzzer = 12;
int t = 3;
int e = 4;
void setup() {
pinMode(led, OUTPUT);
 pinMode(sensor, INPUT);
 pinMode(buzzer, OUTPUT);
 pinMode(t, OUTPUT);
 pinMode(e, INPUT);
 Serial.begin(9600);
}
void loop() {
 int sensorval = digitalRead(sensor);
 Serial.println(sensorval);
 if (sensorval == HIGH) {
  digitalWrite(led, HIGH);
  tone(buzzer, 1000, 500);
 }
 else {
  digitalWrite(led, LOW);
 }
 digitalWrite(t, LOW);
 digitalWrite(t, HIGH);
 delayMicroseconds(10);
```

```
digitalWrite(t,LOW);
float dur = pulseIn(e,HIGH);
float dis = (dur*0.0343)/2;
if(dis < 100){
    digitalWrite(led, HIGH);
    tone(buzzer, 1000, 500);
}
else {
    digitalWrite(led, LOW);
}</pre>
```

Picture:



Link:

https://www.tinkercad.com/things/brpPu9nv0Rh-daring-hango-vihelmo?sharecode=-LQQxmpF41kr9d2PXdY_Sm_b7G8X0L6Ulhab9D4M0xs